

SAVI Behavior Model Integration Virtual Integration Process

David Redman, AVSI
Texas A&M University

GLOBAL PRODUCT DATA INTEROPERABILITY **SUMMIT** 2015



ELYSIUM

Darker Aerospace

NORTHROP GRUMMAN

BOEING



Outline

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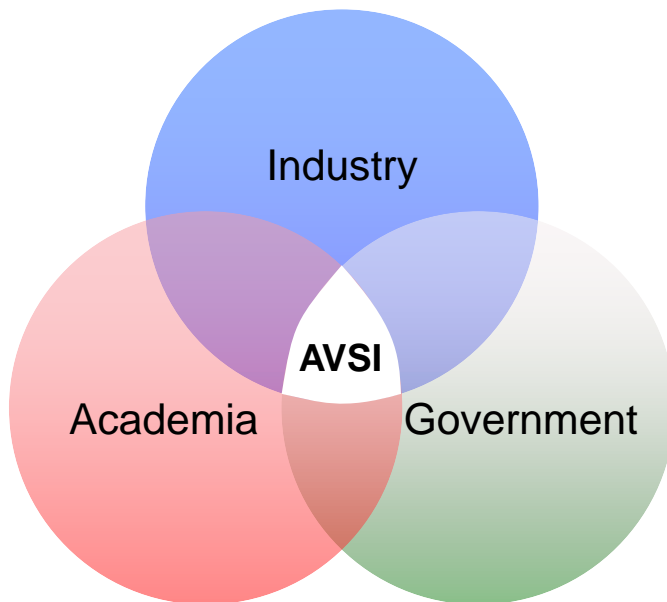
- **AVSI**
- **SAVI Motivation**
- **SAVI Program History**
- **SAVI Behavior Modeling**
- **Summary**

AVSI Facilitates Cooperative Research

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MISSION

AVSI addresses issues that impact the aerospace community through international cooperative research and collaboration conducted by industry, government and academia.



- *Contribute to **standards** and **policies***
- *Establish the **environment** that **enables collaboration** and sharing of costs*
- *Create an **aerospace industry voice***

AVSI Membership Represents the Industry

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Full Members

- Airbus
- Boeing
- DoD
- Airbus Group
- Embraer
- GE Aviation
- Honeywell
- Rockwell Collins
- Rolls Royce
- Saab
- United Technologies

Liaison Members

- FAA
- NASA
- Aerospace Valley
- SEI

Associate Members

- ATI Wah-Chang
- BAE Systems
- Rafael D. S.
- SAES-Getters
- Foresite
- Raytheon
- HARCO Labs



Current membership includes a cross-section of aerospace industry stakeholders, including aircraft producers, system suppliers, regulatory bodies, government and trade organizations, and academia.

Everyone Knows the Problems...

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Increasing System Complexity



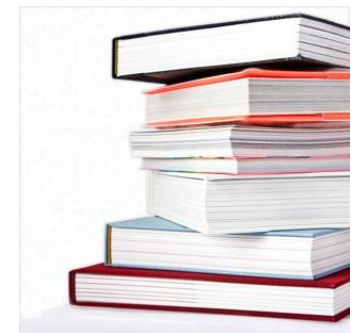
src: http://en.wikipedia.org/wiki/File:Gravis_UltraSound_PNP.jpg

“pi”



Mismatched Assumptions

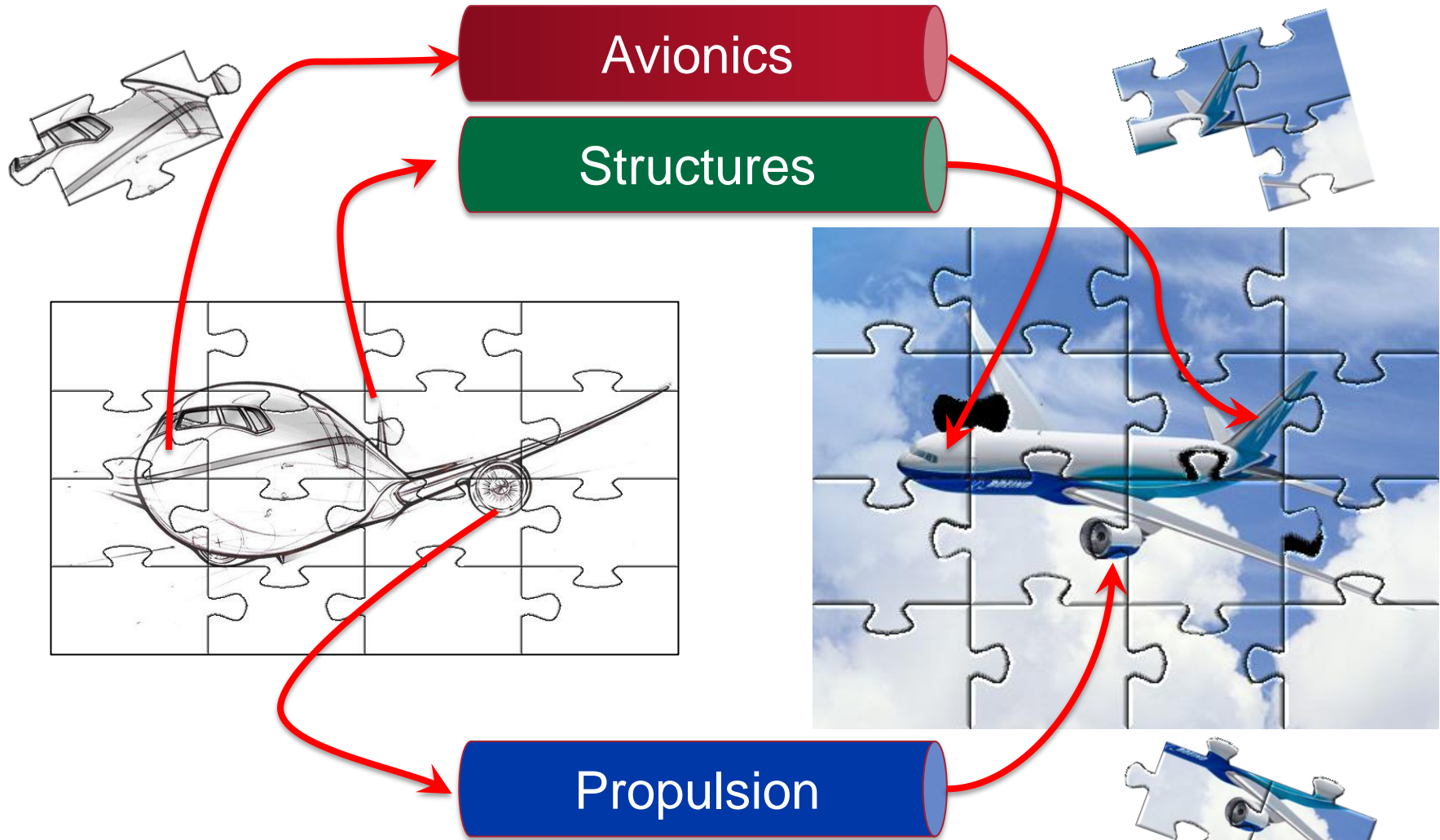
Siloed Organizations



Written Requirements

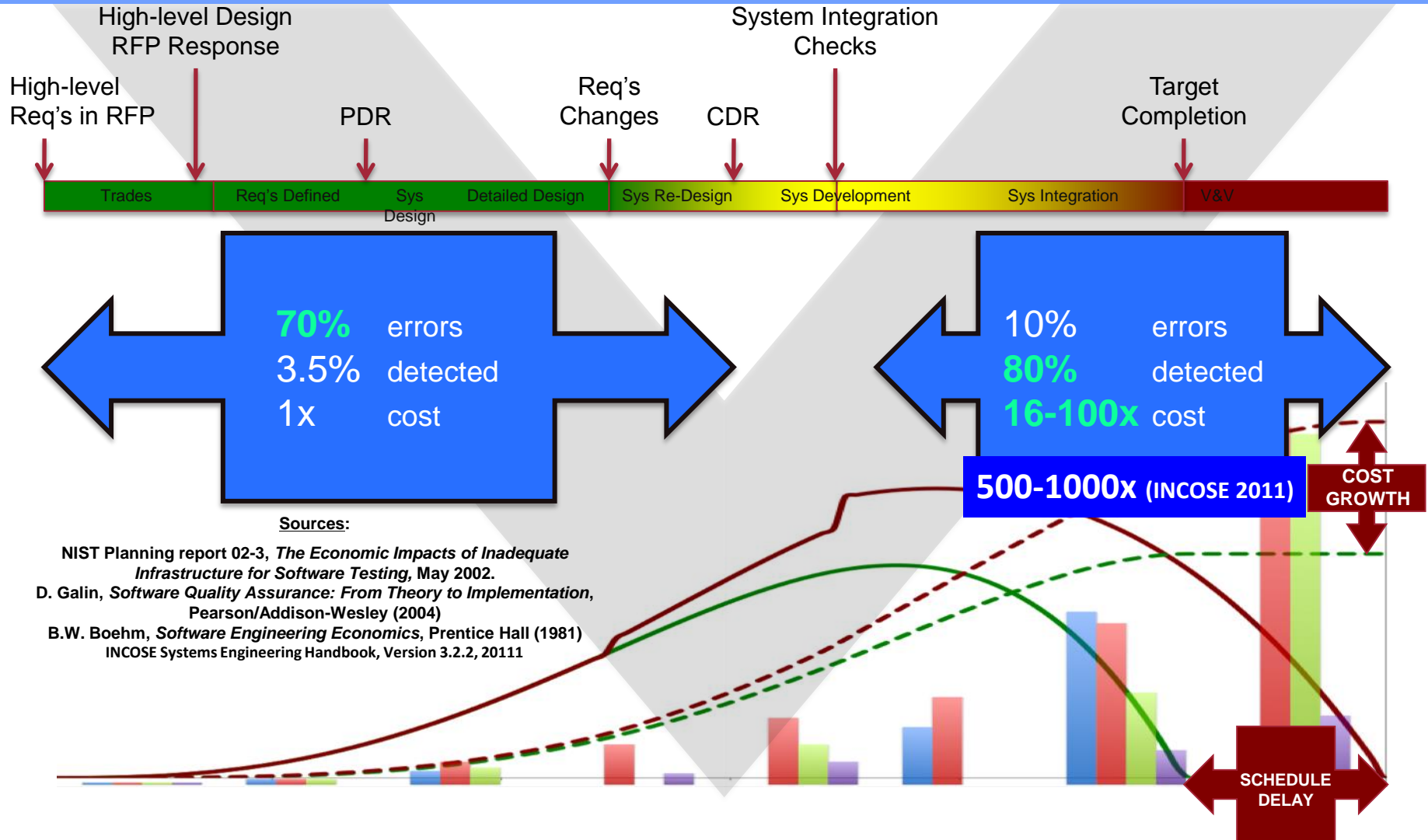
We Start Integrated, But Don't Stay Integrated

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The Impact is Documented

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The Problem Affects Everyone

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- **Integration complexity will continue to increase**
- **Current solutions are insufficient**
- **Individual companies cannot solve it alone**
- **Industry cannot afford to solve it multiple times**
- **We can't afford not to solve it**

A coordinated, industry-wide effort is needed to solve this issue.

The AVSI Systems Architecture Virtual Integration Project

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Full Members

- Airbus
- Boeing
- DoD
- Embraer
- GE Aviation
- Honeywell
- Rockwell Collins
- United Technologies

Tool Vendor Partners

- Adventium Labs
- Esterel Technologies
- Eurostep Limited

Liaison Members

- FAA
- NASA
- SEI



**United
Technologies**

**Rockwell
Collins**



Honeywell



Software Engineering Institute



SAVI
System Architecture Virtual Integration



AIRBUS



BOEING



EMBRAER

SAVI Goals and Approach

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- **Reduce costs/development time through early and continuous model-based virtual integration**
 - Distributed inter-domain/inter-model consistency checks throughout development - (start integrated, stay integrated)
 - Protect intellectual property (IP)
 - Capture incremental evidence for safety analysis and for certification Approach
- **Capture Requirements and Use Cases that define the following:**
 - SAVI Data Exchange Layer
 - SAVI Model Repository
 - SAVI Virtual Integration Process
 - SAVI distributed inter-domain/inter-model dependencies and consistency checks

One Model To Rule Them All



A Fellowship is More Practical

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M/ECAD

Simulink

Modelica

AADL

Excel



Structure

Behavior

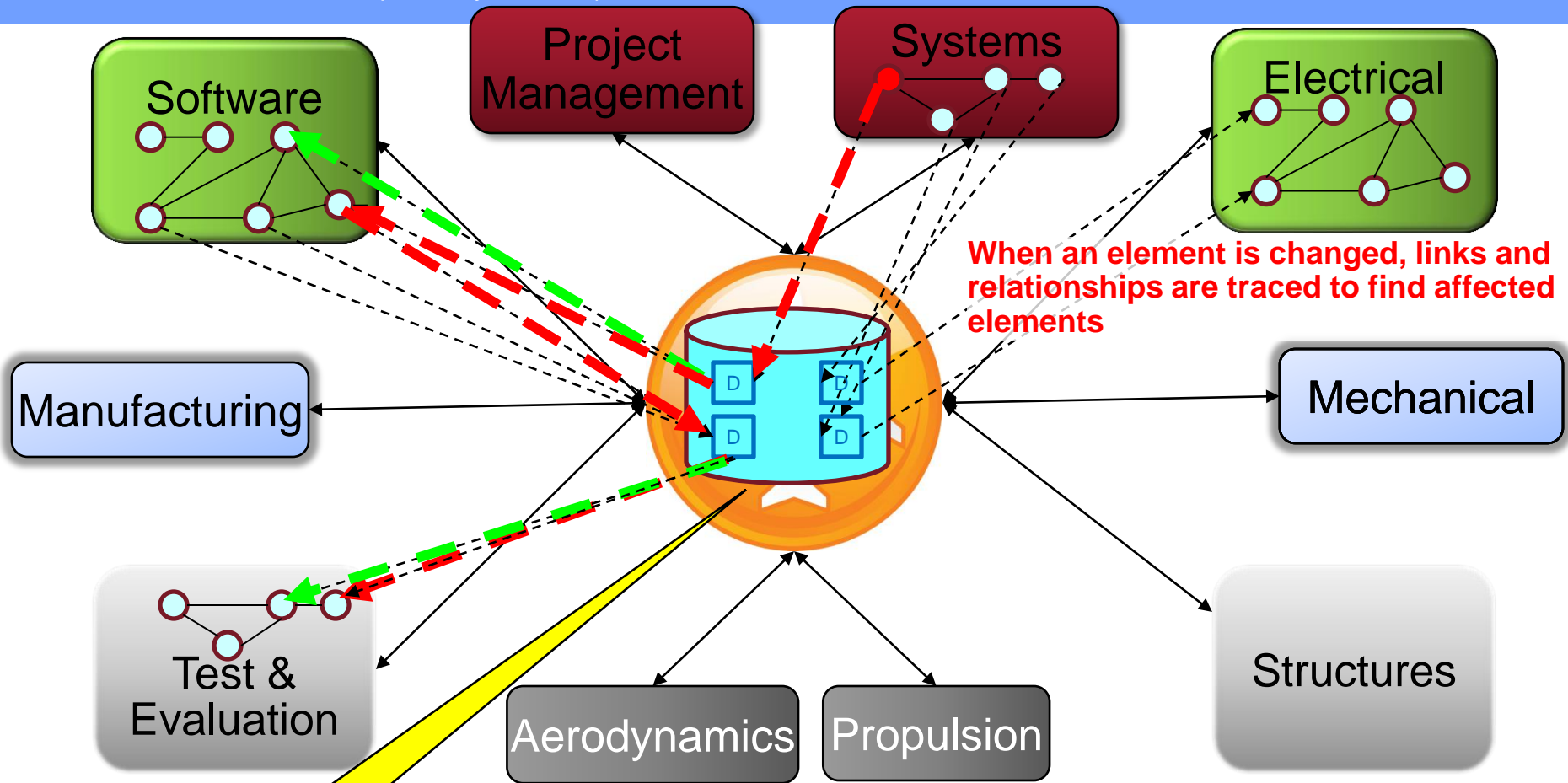
Requirements

Parametrics

SysML

Dependencies Are Key

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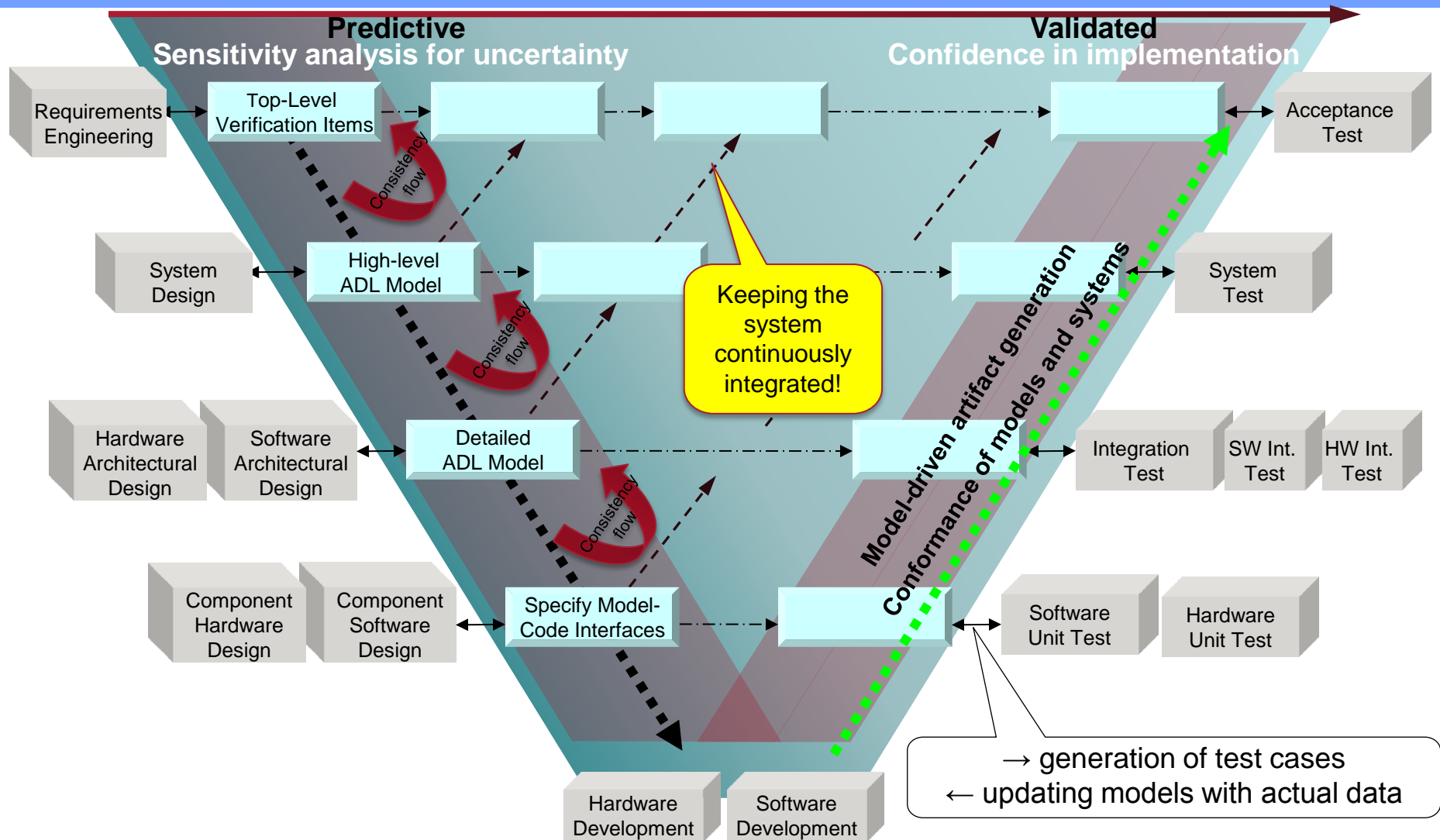


Industry wide, 50% of requirements will change between CDR & delivery into service

■ The SAVI Repository stores the links

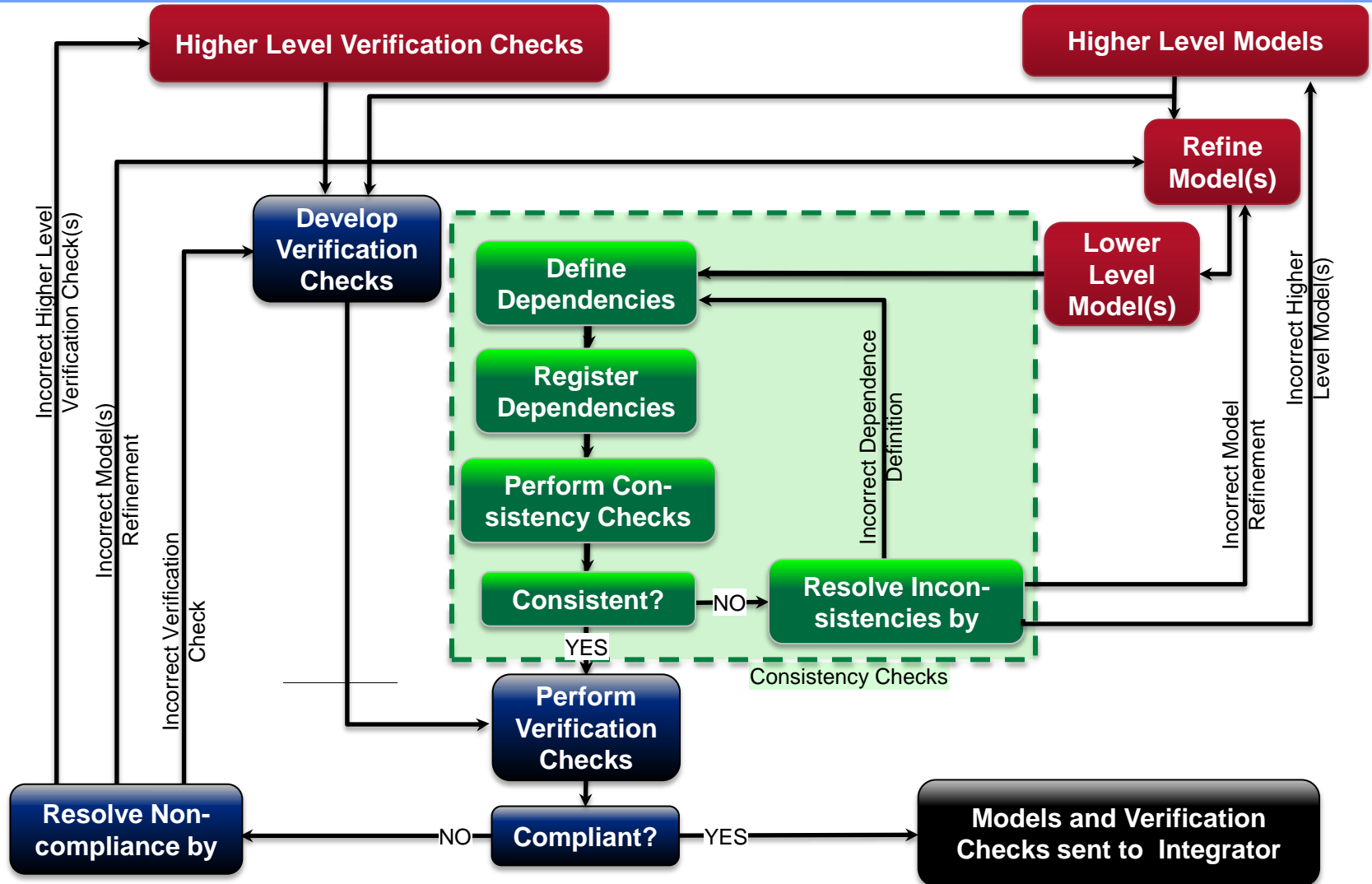
SAVI Virtual Integration “Vee”

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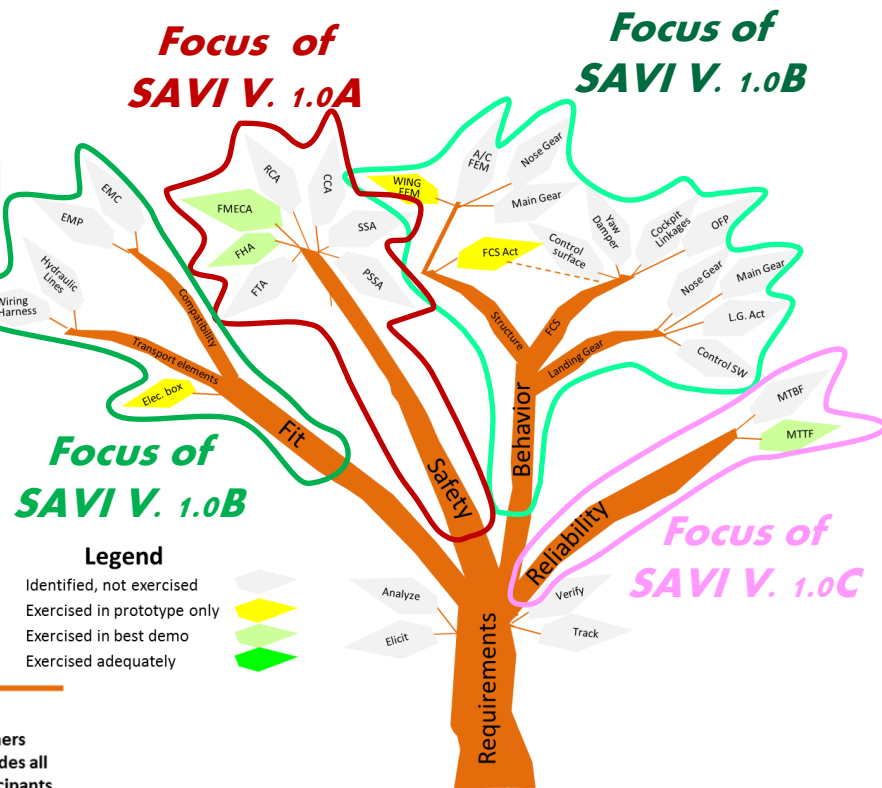


SAVI VIP

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SAVI Behavioral Modeling – Acknowledgements

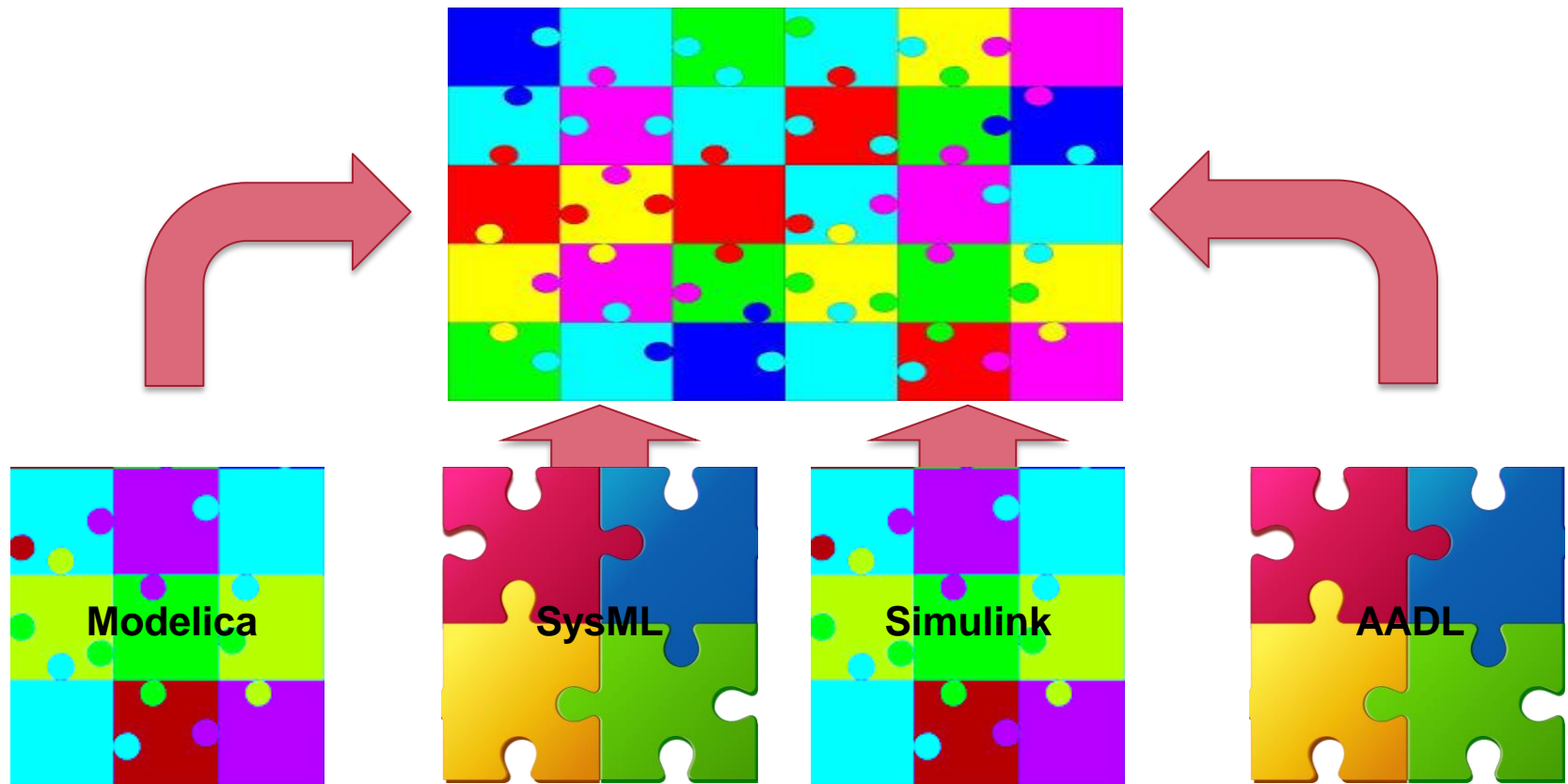
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- **This work is being performed by SAVI members of the Behavior Working Group**
 - K. Woodham – NASA
 - **N. Shaw – Eurostep (SAVI Tool Vendor Partner)**
 - D. Kuehlewind, E. Scholte – Sikorsky/UTAS
 - B. Hall – Honeywell
 - J. Chilenski – Boeing
 - R. Manners, S. Mandalapu – FAA
 - B. Horta, R. Filho – Embraer

Back to the Puzzle Analogy

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- Consider trying to complete a jigsaw puzzle using bits from 4 different puzzles in different formats **taking specifics from each source to make one picture**

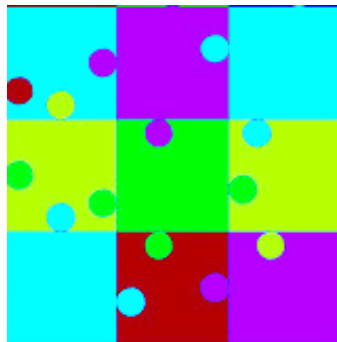
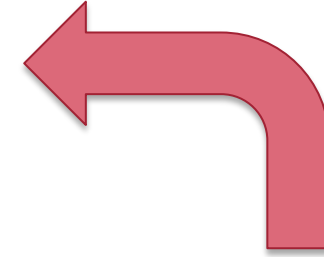
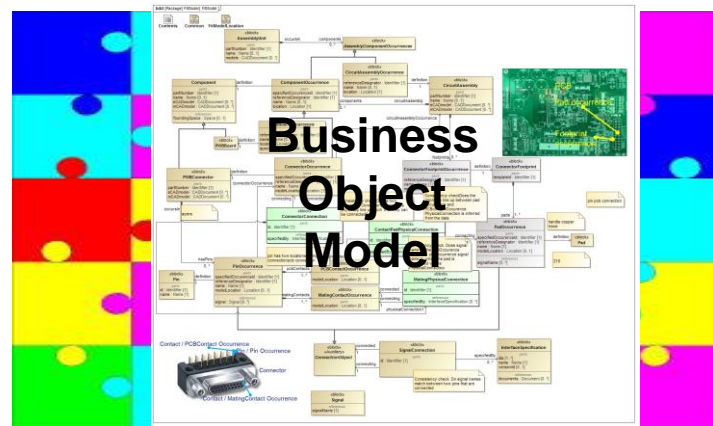
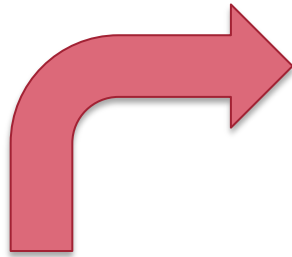


The good news is

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- We can use standards – some commonality
- We can design the target jigsaw to do the job

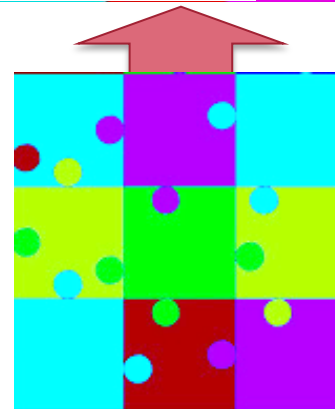
MoSSEC



Modelica



SysML



Simulink



AADL

The Behavioral Model Integration Problem - Background

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- **When an OEM commissions the design of a system which will be part of a new product, there are potentially many companies involved**
 - **The OEM creates a specification for the system**
 - **This is the first model, typically at a high-level**
- **These companies are all expert in their respective areas with established methods and tools**
 - **Increasingly these include the use of model-based approaches**
 - **Now there are many models using different approaches and at different levels of abstraction/detail**
 - **Some (sub-system and component) models will have been created in isolation, independent of the intended use**

The Behavioral Model Integration Problem

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- **Need to determine if a set of models that relate to a system are **consistent**, when:**
 - The models are possibly at different levels of abstraction/detail
 - **Specifications versus simulations**
 - The models are using different languages and paradigms
- **Given a set of models:**
 - How do we know which elements from the models should be consistent?
 - Once we know this we can check the consistency!
- **What do we mean by consistent?**
 - Data value consistency
 - Model property consistency
 - Model behavior consistency (time-history)
 - Model behavior consistency (property assertion)

An example to start with

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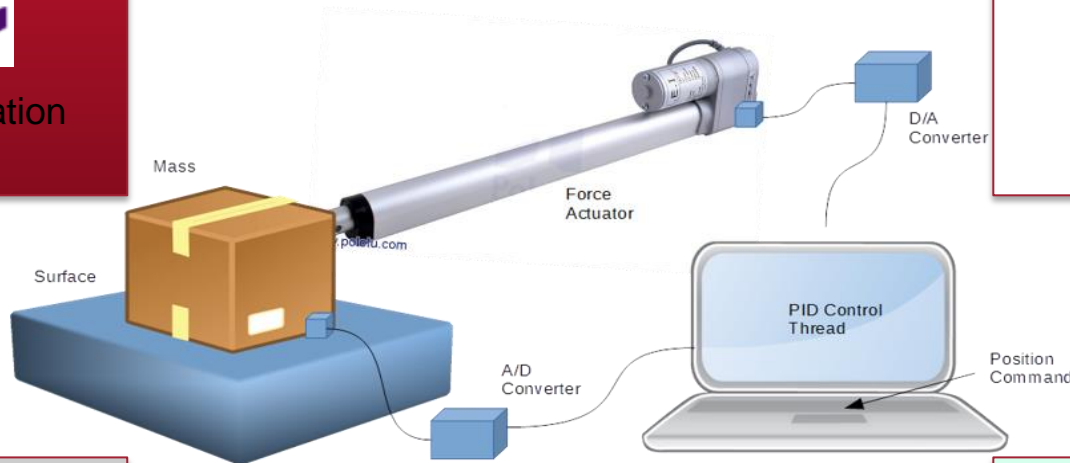
- SAVI have created four models of the same simple system using different languages



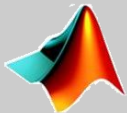
A system specification using SysML



A system model using AADL



The Sliding Mass Example System



SIMULINK

A system model using Simulink®



A system specification using Modelica

The SysML model

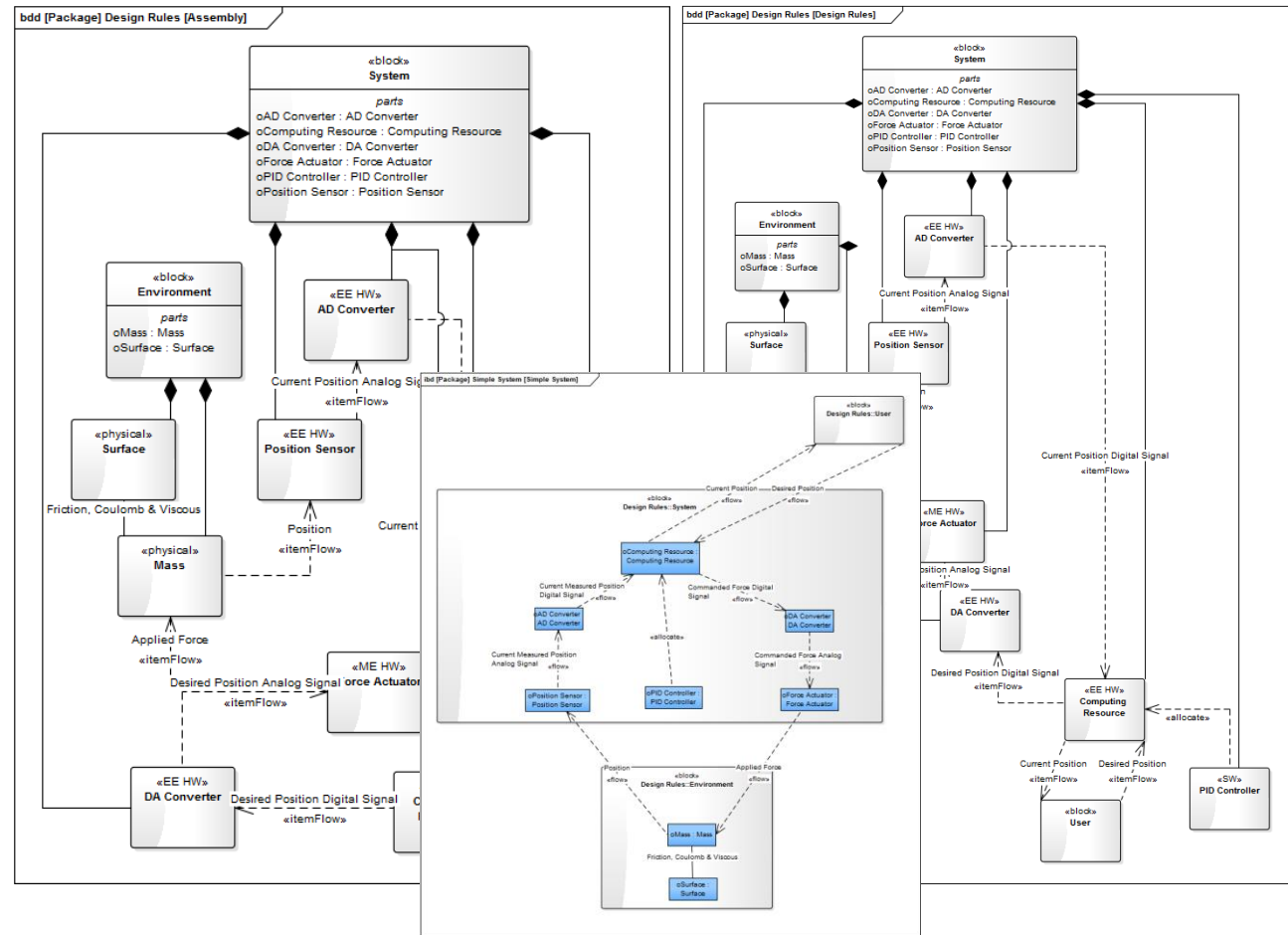
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- The SysML model was created in Enterprise Architect™



A system specification using SysML

SysML is a Graphical Language
Stored as XML using
the OMG's XMI (XML
Metadata Interchange)



The AADL Model

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- **Architecture Analysis & Design Language (AADL) is the SAE Standard AS-5506 for modelling safety critical systems**

```
package SimpleModel
...
system FullSystem
end FullSystem;

system implementation FullSystem.impl
subcomponents
    ControlSys : system Platform.impl;
    PhysicalSys : system Plant.impl;
    UI : device ControllInput;
connections
    c1 :          feature group ControlSys.ActuationIF <->
PhysicalSys.ActuationIF;
    c2 :          feature group ControlSys.SenseIF <-> PhysicalSys.SenseIF;
    c3 :          feature group ControlSys.UserInterface <-> UI.Interface;
end FullSystem.impl;
end SimpleModel;
```



A system model
using AADL

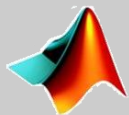
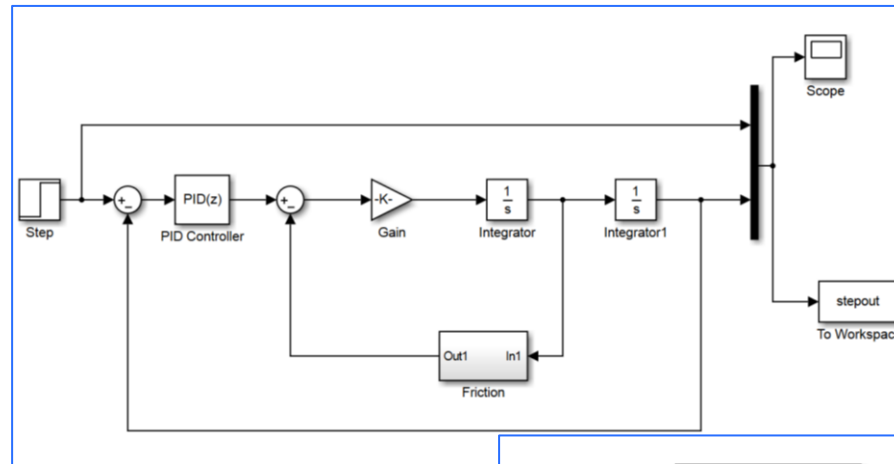
**AADL is stored using
ASCII text
There is also an XML
form**

The Simulink Model

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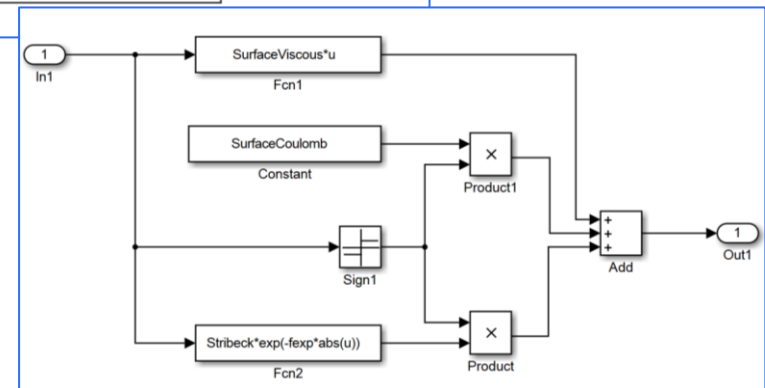
- **Simulink is a graphical programming environment for modeling, simulating and analysing multi-domain dynamic systems.**

Simulink models are stored as Ascii text
There is also an XML form



SIMULINK

A system model
using Simulink®



The Modelica Model

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- **Modelica® is an object-oriented, equation based language to conveniently model complex physical systems**

```
model slidingblockpid1
  Modelica.Blocks.Sources.Step step1(startTime = 1, height = 1.0) ;
  Modelica.Blocks.Math.Add add1(k2 = -1) ;
  Modelica.Mechanics.Translational.Sources.Force force1 ;
  Modelica.Mechanics.Translational.Components.MassWithStopAndFriction boxwithfriction(
    L = 0, s(fixed = true), v(fixed = true), smax = 25, smin = -25, m = 10, F_prop = 0.05,
    F_Coulomb = 0.01, F_Stribeck = 1, fexp = 10) ;
  Modelica.Mechanics.Translational.Sensors.PositionSensor positionsensor1 ;
  Modelica.Blocks.Continuous.PID PID(k = 3.3437, Ti = 64.7929, Td = 6.998, Nd = 20.04, initType =
    Modelica.Blocks.Types.InitPID.DoNotUse_InitialIntegratorState);
equation
  connect(PID.y, force1.f) ;
  connect(add1.y, PID.u) ;
  connect(positionsensor1.s, add1.u2) ;
  connect(step1.y, add1.u1) ;
  connect(force1.flange, boxwithfriction.flange_a);
  connect(boxwithfriction.flange_b, positionsensor1.flange);
  annotation(experiment(StartTime = 0, StopTime = 6, Tolerance = 1e-006, Interval = 0.006));
end slidingblockpid1;
```

**Modelica models are
stored as ASCII text
Depend on libraries of
other Modelica models**



**A system specification
using Modelica**

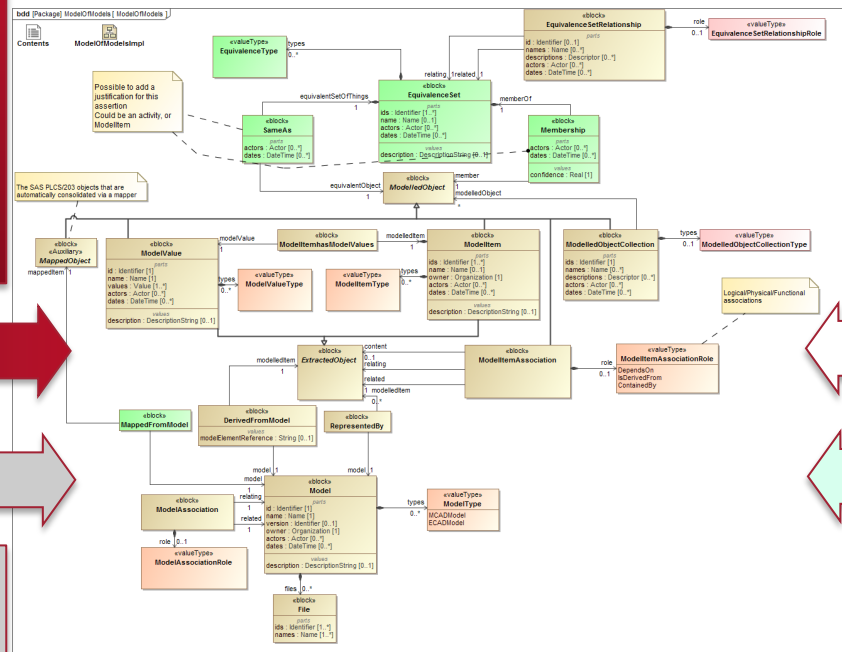
The Approach

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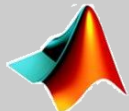
- **In order to compare bring all the models into a common framework - a model of models**



A system specification using SysML



A system model using AADL



SIMULINK

A system model using Simulink®

Model of Models specified in SysML

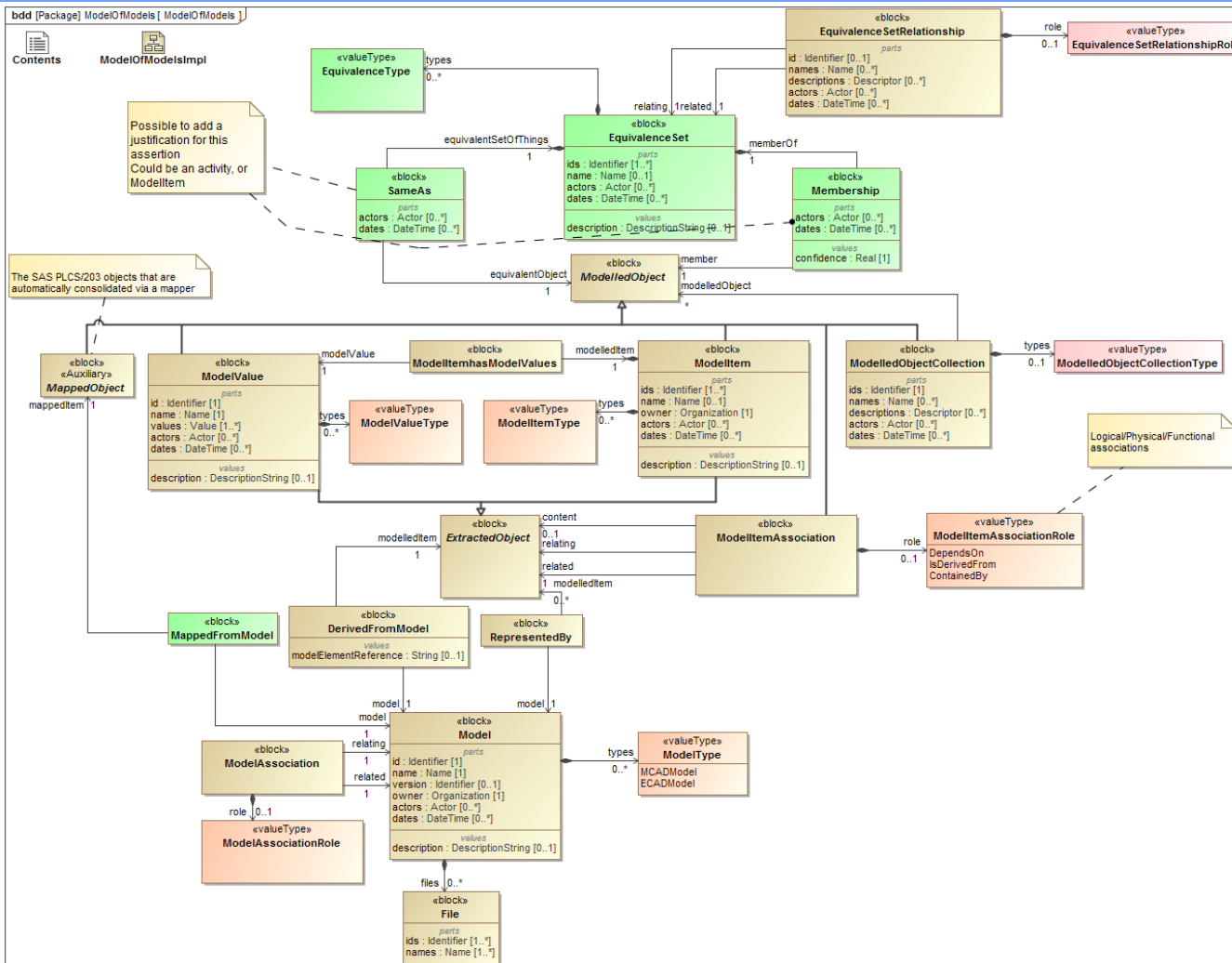
Mappers developed to extract from each into the Model of Models



A system specification using Modelica

The Model of Models

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Information about
equivalence between
things found in the
models

Information about
things found in the
models

Information about
each model

Implementation - Comparison

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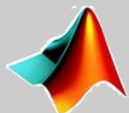
- The potential equivalences are identified and the results added into Share-A-space



A system specification using SysML



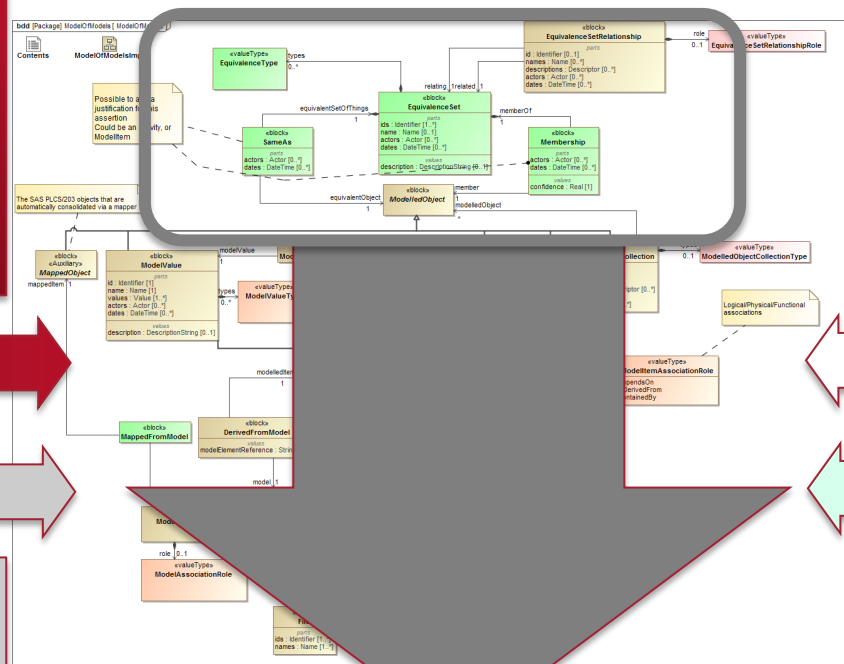
A system model using AADL



SIMULINK
A system model using Simulink®



A system specification using Modelica



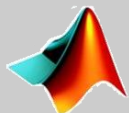
Implementation - Visualisation

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- The resulting data set (models, model content and equivalences) is then visualised

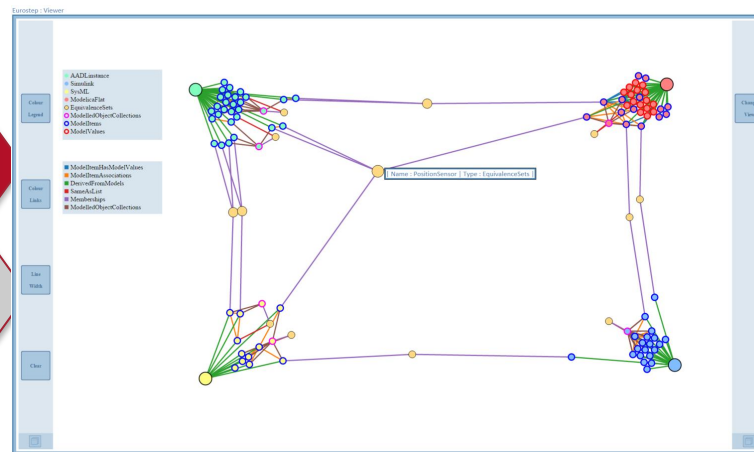


A system specification using SysML



SIMULINK

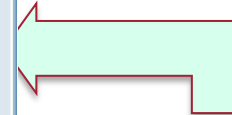
A system model using Simulink®



share A space



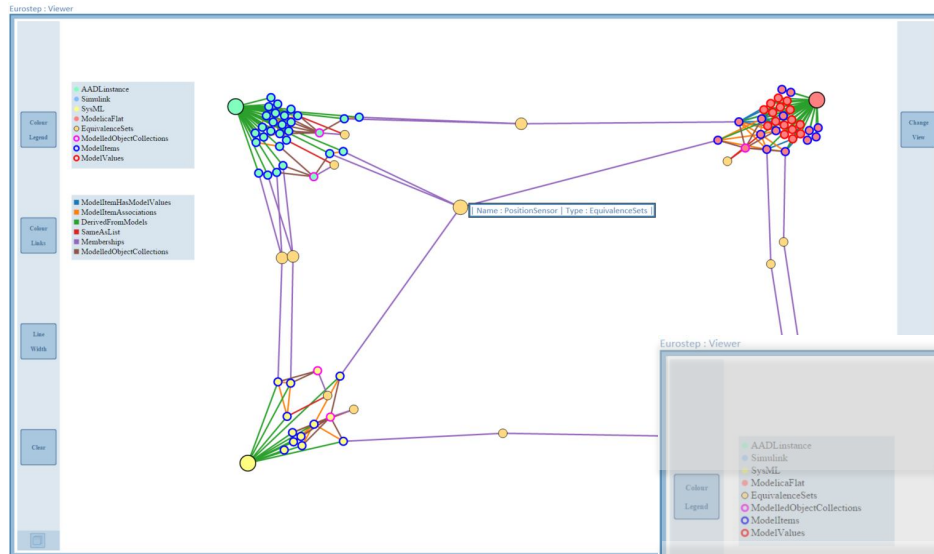
A system model using AADL



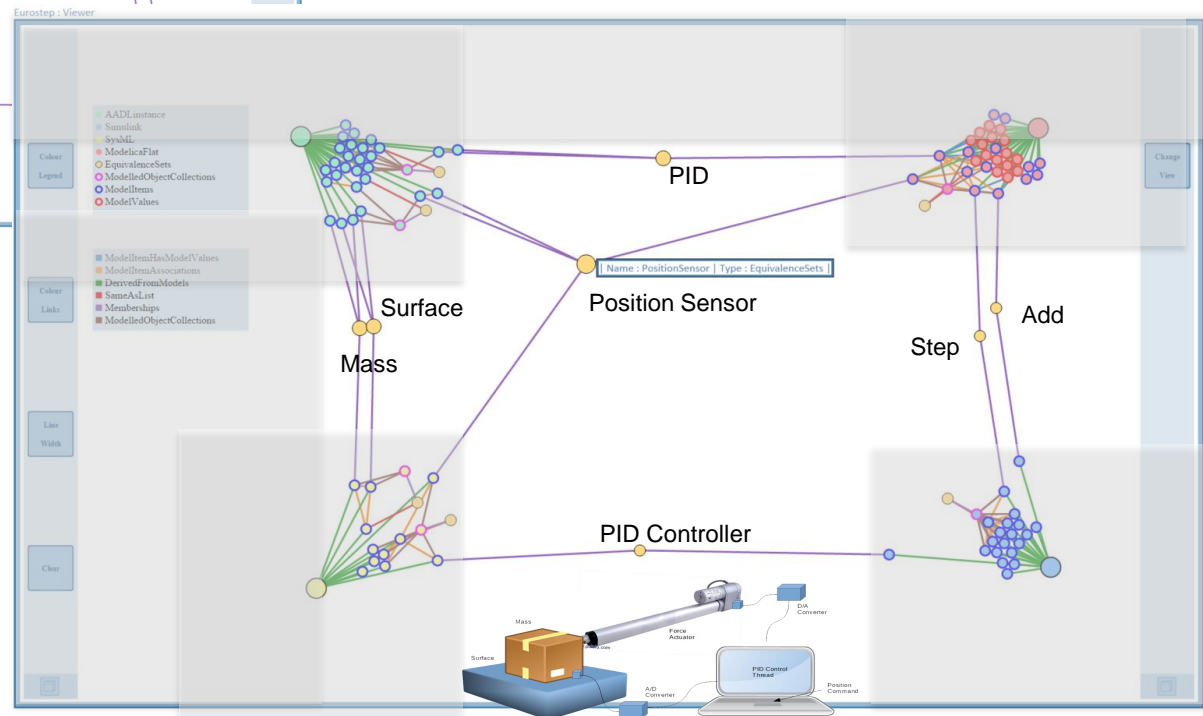
A system specification using Modelica

Visualization aid Identifying Equivalences

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Equivalence sets were created on the basis of fuzzy name comparison



Conclusions

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- **Using a common model-of-models approach is feasible**
 - The different syntaxes of the four model types are not a barrier
 - Although some are harder than others to process
 - The approach did not need the tools that edit/execute the respective models
- **A graphical approach is appropriate to present the results**
- **Initial approach to equivalence has identified equivalences across all four models**
 - But nothing common to all four

Summary

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- **The AVSI SAVI project is demonstrating the use of the Virtual Integration Process, Model Repository, and Data Exchange Layer to analyze intermodel consistency**
- **The standards-based methodologies show promise based on proof of concept and simple system representations**
- **Additional work is being pursued to extend these concepts and add to the SAVI capability.**