Applying Process Models in a Model-based Safety Analysis Interoperability Platform

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September 30, 2015

Grant Blythe Bio

Grant Blythe is a member of the Systems Level Engineering team at Mentor Graphics where he specializes in solutions for military and aerospace applications. Prior to joining Mentor Graphics, Grant spent 10 years in systems engineering roles developing both commercial and military avionics. In addition to his role at Mentor Graphics, Grant is a member of the SAE S-18 Airplane System Development Committee which publishes the ARP4754A and ARP4761 standards. Grant holds a B.S. in electrical engineering from Iowa State University and an M.B.A. from the University of Oregon.

Agenda

- **The challenge: “leaning” the safety analysis process**
- **The approach: OSLC, SDM, and Process Models**
- **Developing an ARP4754A based Process Model**
- **Project Results & Continuous Improvement**

Wheel Brake System Safety Process

as presented in ARP4754A/ARP4761/AIR6110

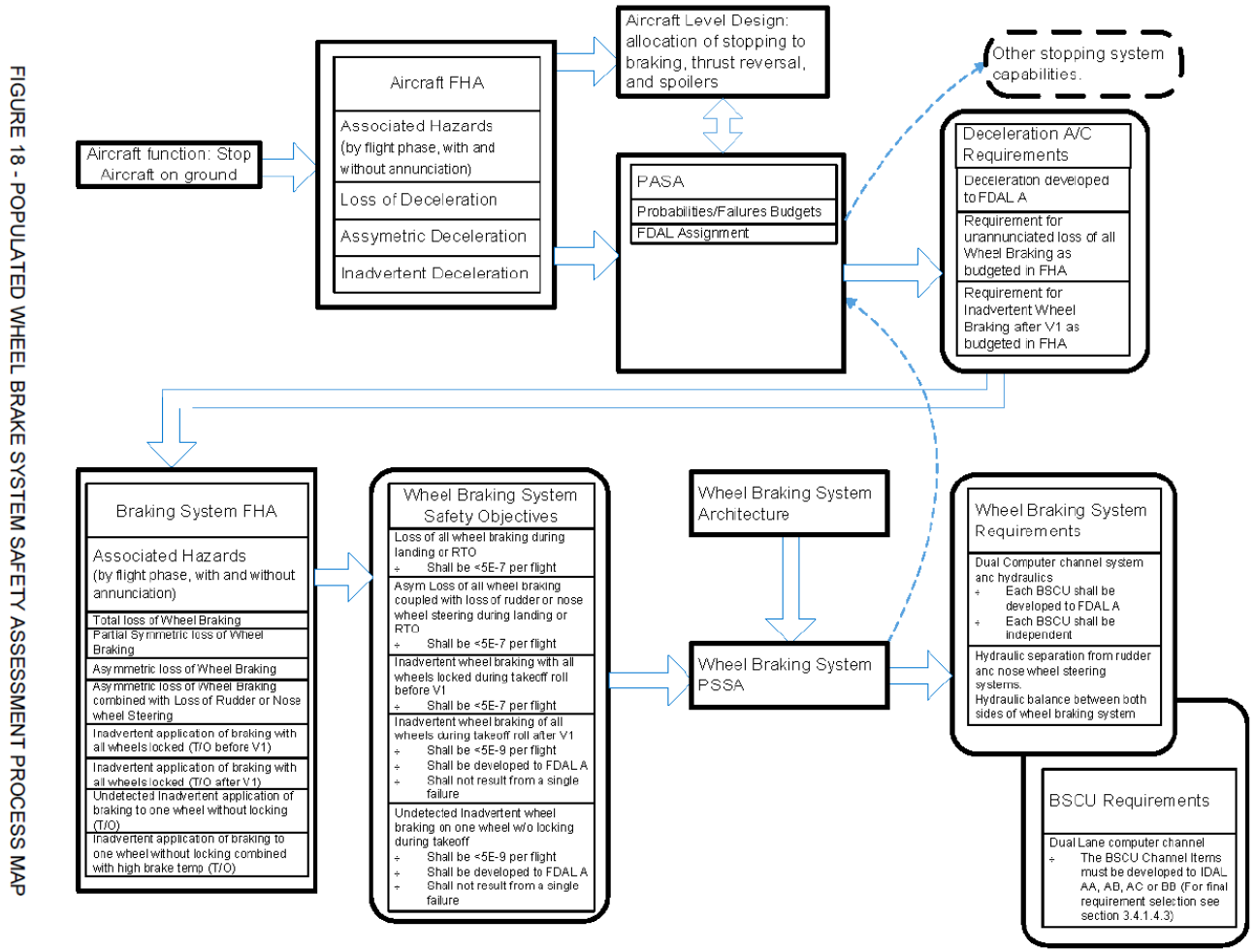


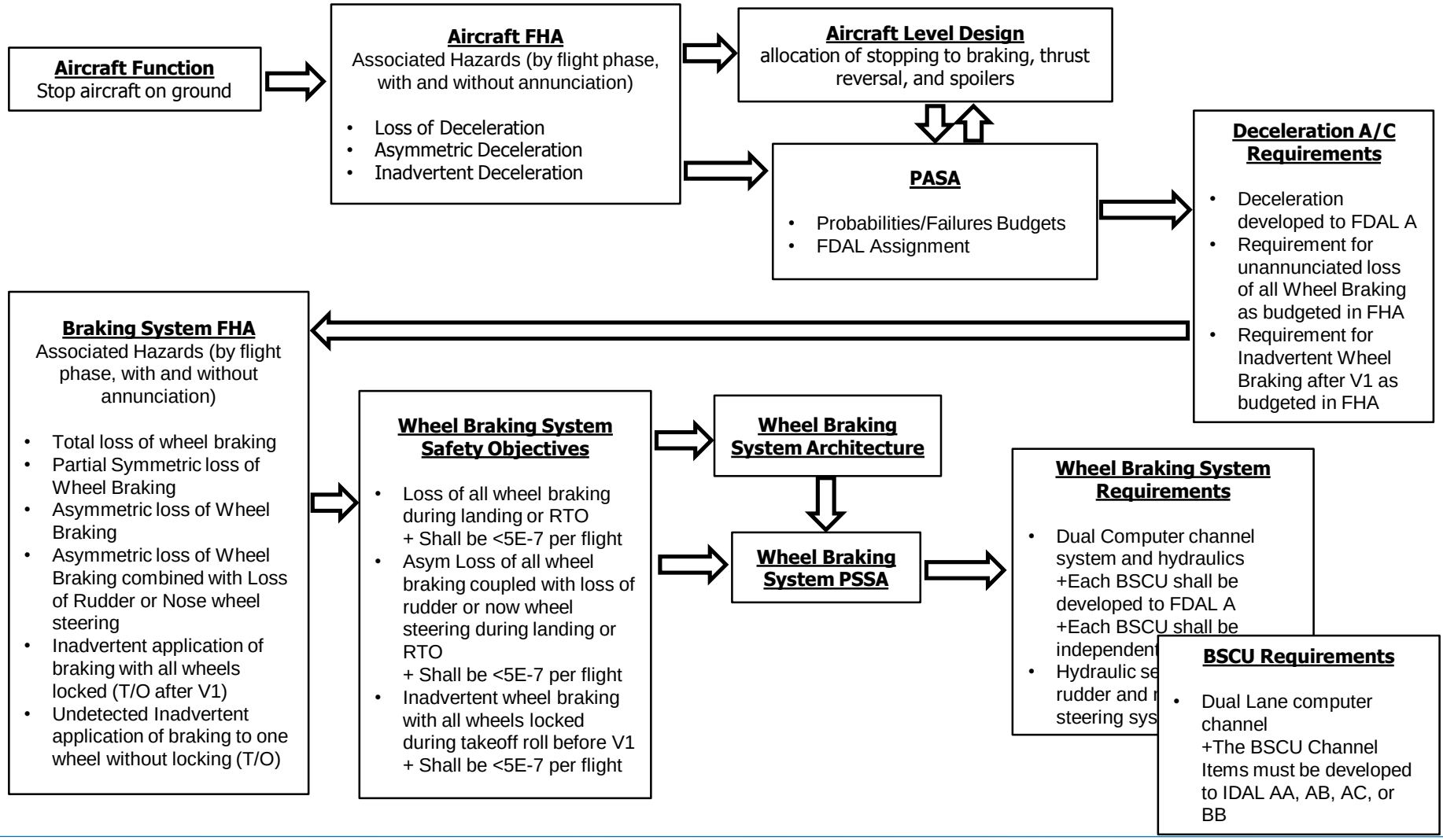
FIGURE 18 - POPULATED WHEEL BRAKE SYSTEM SAFETY ASSESSMENT PROCESS MAP

SAE AIR6110 Page 38 of 107

Source: Extracted from SAE AIR6110, Contiguous Aircraft/System Development Process Example.

ARP4754A Process with tool layer

Rhapsody
DOORS
Excel/Tbl
PDFs
CAFTA
Matlab/Simulink



Waste in System Development Process

Typical characterizations of some of the wastes in production, and in design

- ***Transportation***
  - **Manually moving/importing/exporting data between multiple design tools**
  - **Manually reformatting/translating data for use in multiple tools**
- ***Motion***
  - **Staff switching & multi-tasking across several unintegrated tools**
  - **Searching for data in multiple locations**
- ***Waiting***
  - **Attempting to start tasks before inputs are ready**
  - **Tasks not performed according to priority (off critical path)**
- ***Over-production***
  - **Creating & maintaining multiple copies of the same data**
- ***Defects***
  - **Defects introduced during non-value add activities such as moving, copying, translating data**





With attention to these – and other sources of waste, a model driven systems engineering approach can yield improvements in productivity, schedule and repeatability that yield higher quality results and enable continuing improvement of the process over iterations and time

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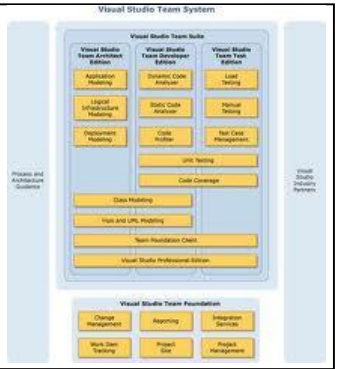
Need for better integration approaches

Past integration approaches provided limited choice and coverage

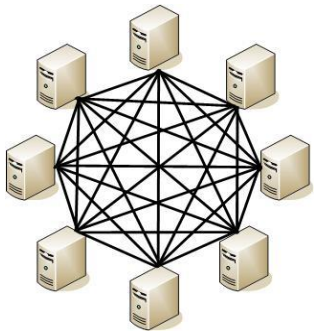
Single repository

"Can I really expect one vendor to provide all the functionality I need? And what about my existing tools?"



Point-to-point integrations

"How can I ever upgrade one tool without breaking everything else?"



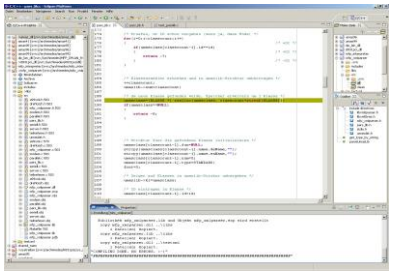
Past integration approaches were disruptive and slow to emerge

Universal metadata standard

"How did I ever think all those vendors would be able to agree?"

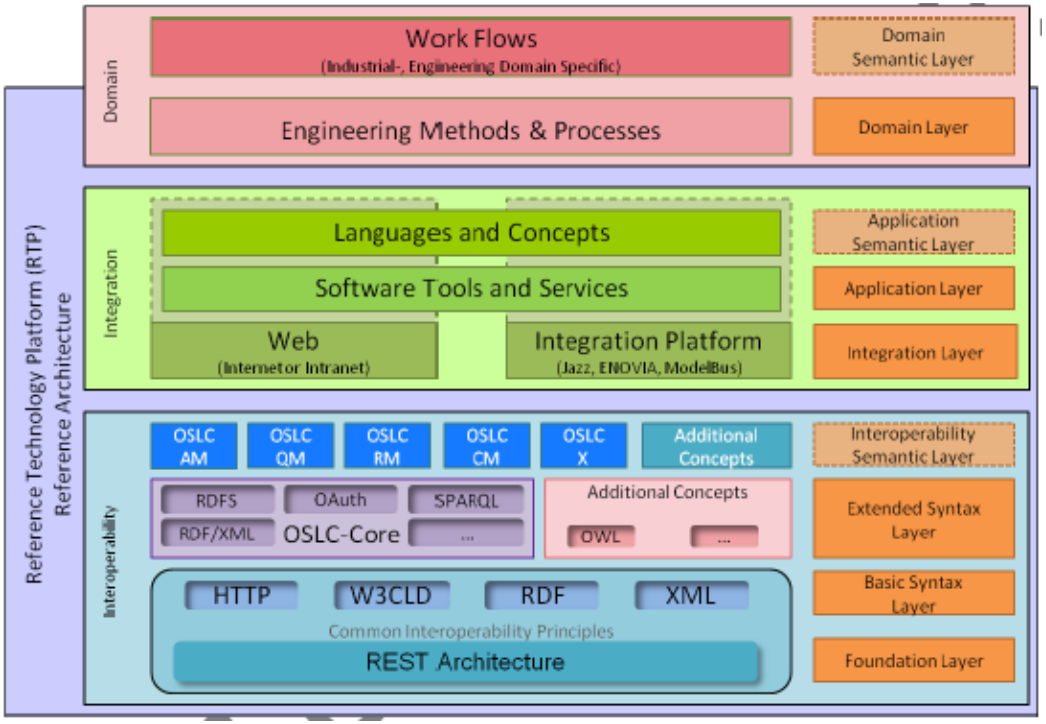
Standard implementations

"Did I really believe that every vendor would rewrite their tools on a single framework?"



Pilot Project Technology Platform

CESAR Technology Platform (D_SP1_R1.6_M4)



Chosen Platform

Tailored MetaModels (User Processes)

Generic MetaModels (ARP4754A, ARP4761, etc.)

Design Tool Integrations & Plugins

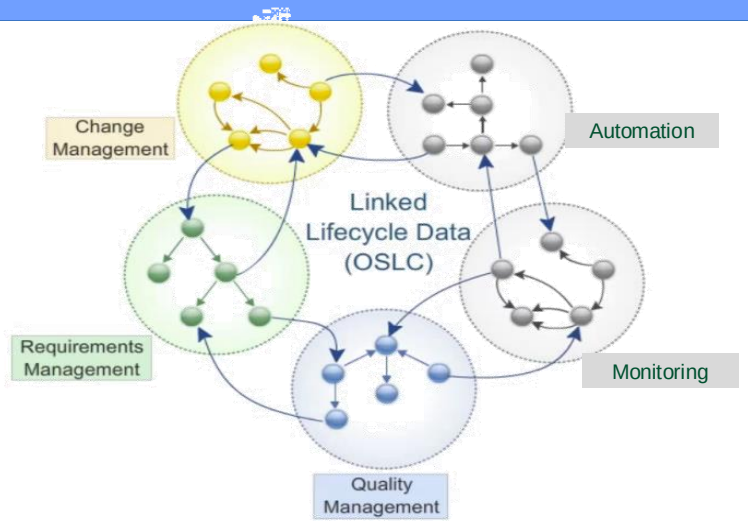
Context SDM Platform

Enabling Technologies

REST, OSLC, etc.

Layer 1: Interoperability
Open Services for Lifecycle Collaboration

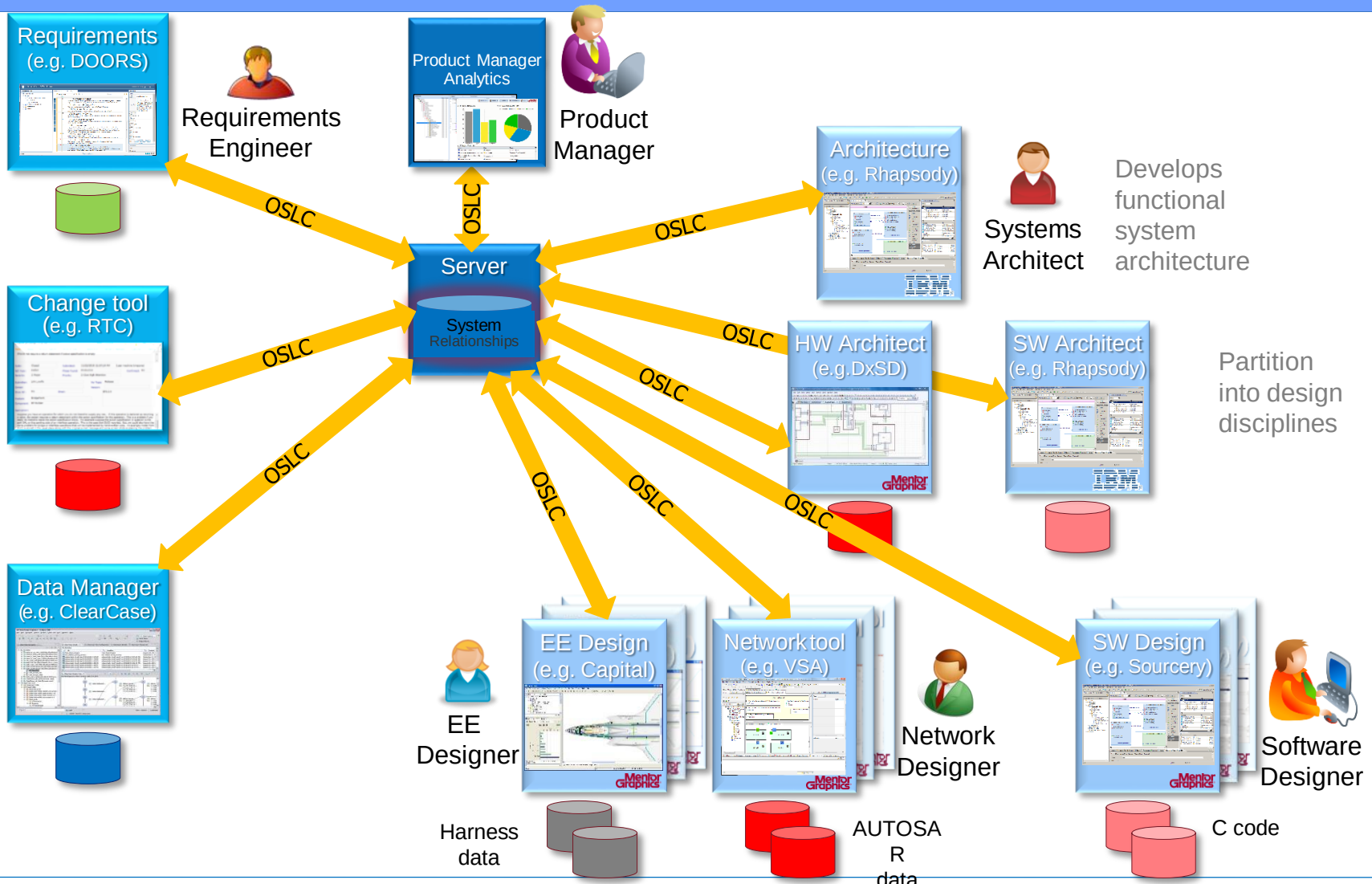
- **Management of linked data**
- **Tool to tool integration**
- **Standards-based communication**



OSLC
Inspired by the web

- **Open Services For Lifecycle Collaboration(OSLC) solves traditional tool integration challenges**
  - **Resilient, standards based approach minimizes IT maintenance**
  - **Seamless experience maximizes user productivity**
  - **Tool vendor IP protection maximizes commercial appeal**

Layer 2: Integration



Layer 3: Domain Models

Aerospace

ARP4754A/ARP4761
DO-178b/c
DO-254

Automotive

ISO26262

Medical

IEC 60601

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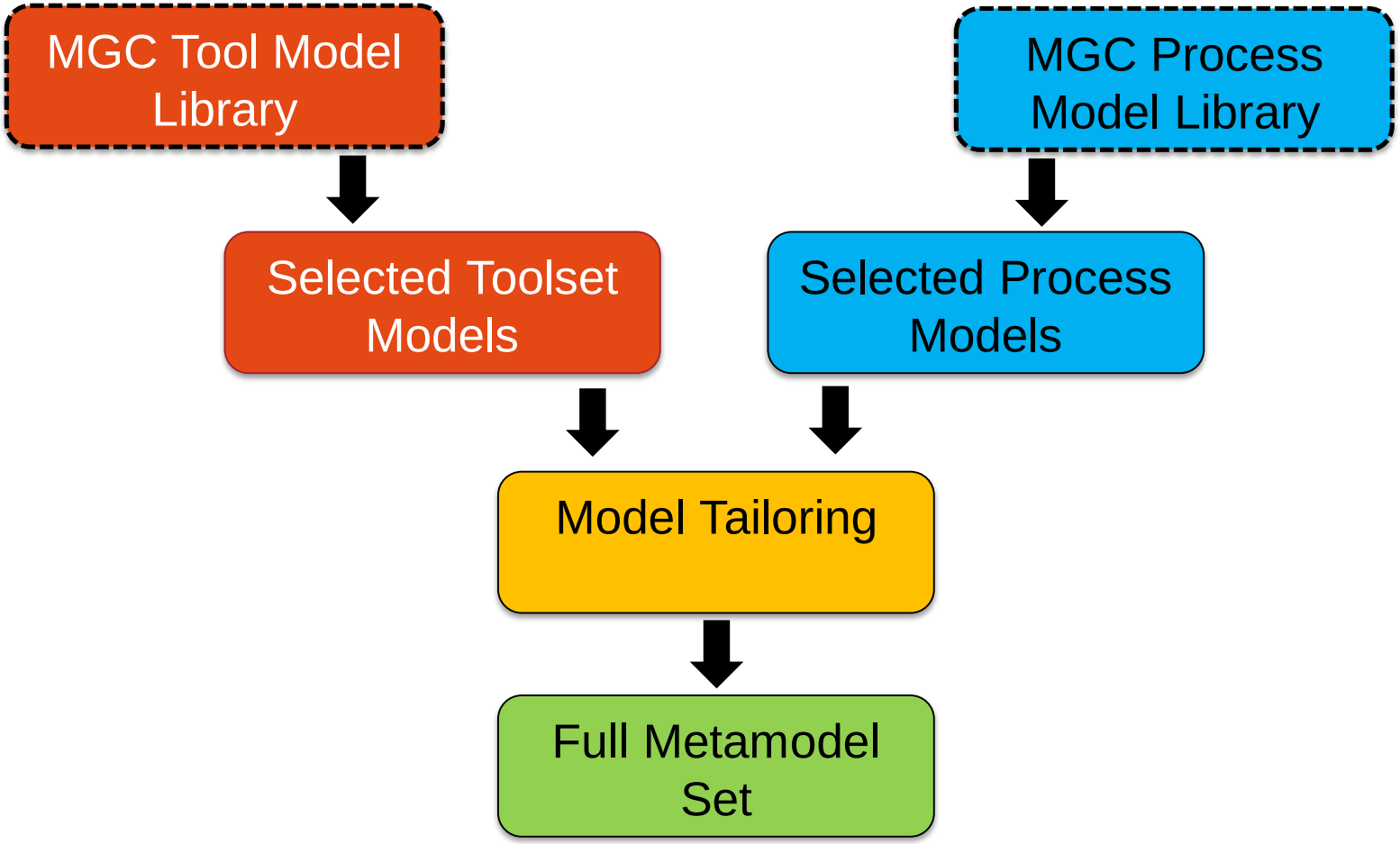
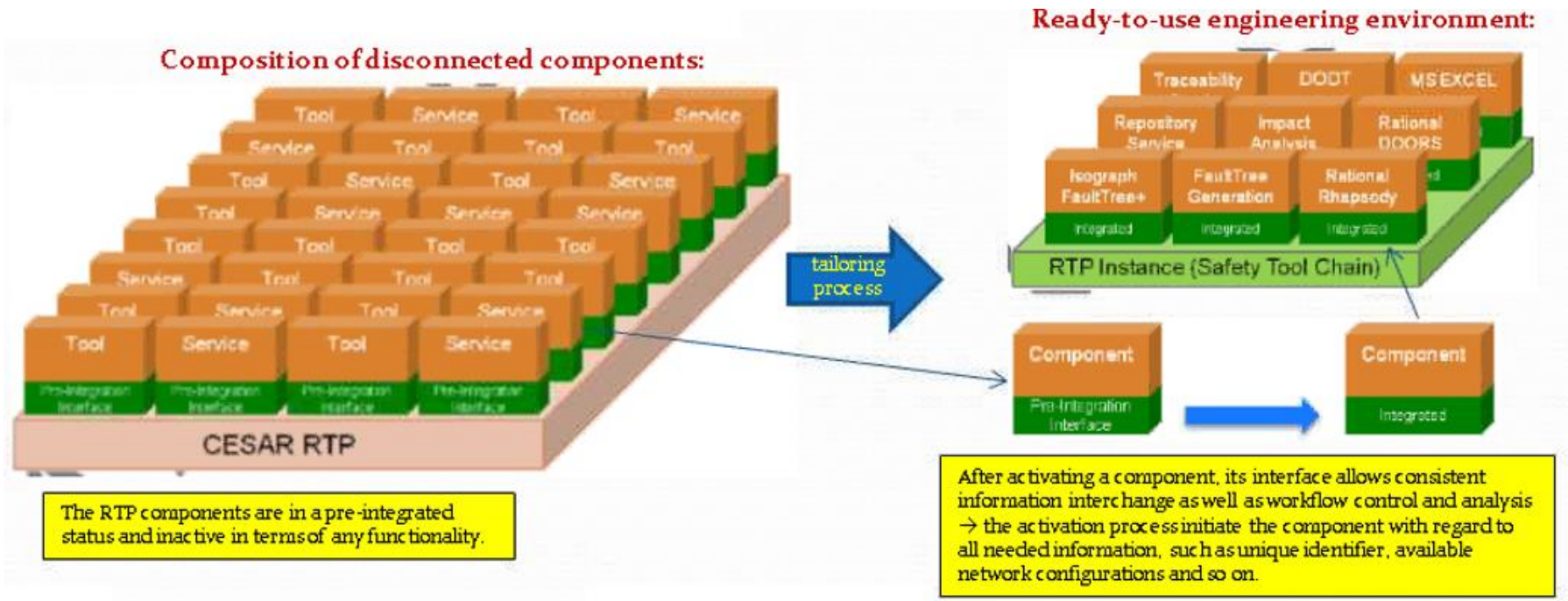
Metamodel Development and Architecture

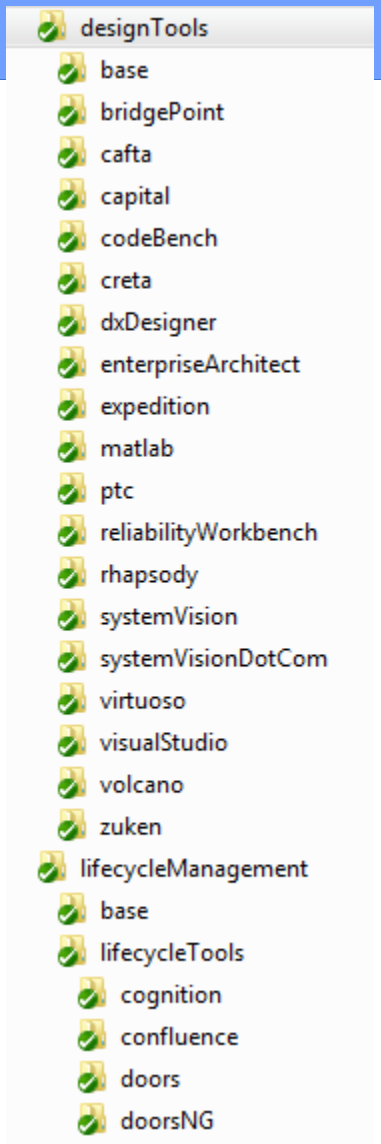


Platform Tailoring - CESAR



Tool Metamodels

- **Platform Library of Supported Tools**
- **Both a metamodel and a plugin/interface**
- **Developed by Mentor Graphics**
  - **Opportunity for user development of new tools integrations in next phase**



Process Model Development

- MGC developed metamodel to generically follow applicable standard
- User organizations can further tailor model to match enterprise processes
- Full process model includes models, views, queries, action listeners, reports, etc.

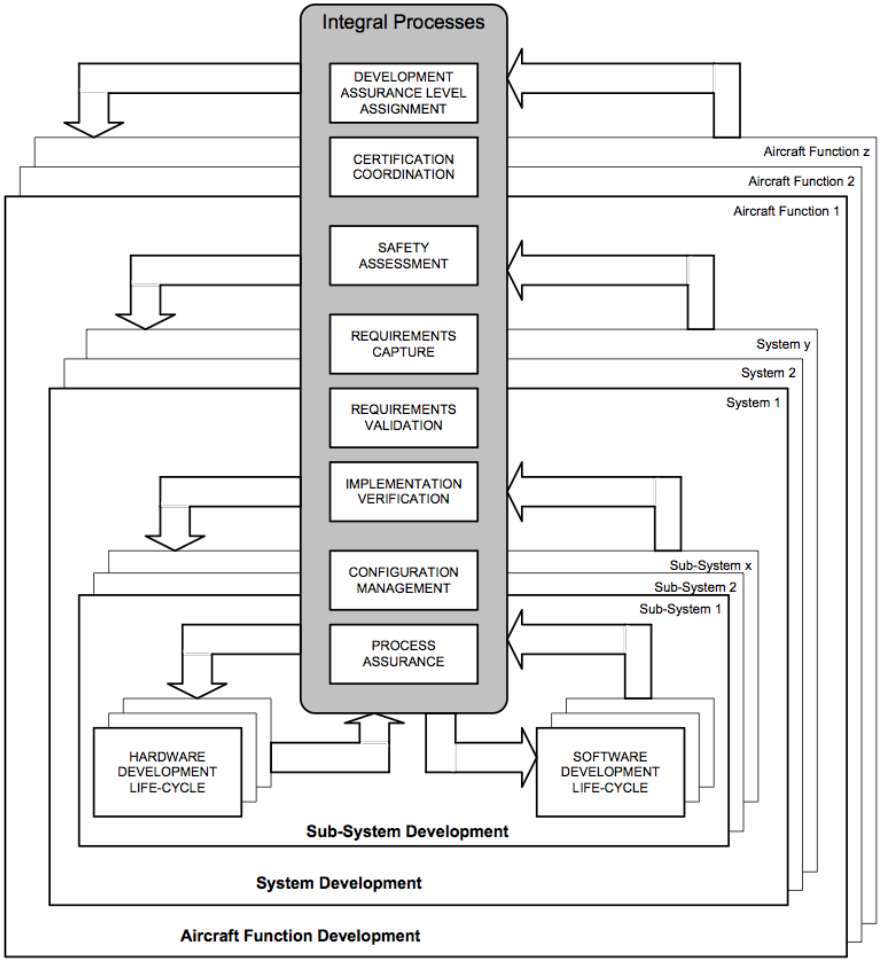


FIGURE 6 - AIRCRAFT FUNCTION IMPLEMENTATION PROCESS

Metamodels – Technical Overview

- **XML Based**
- **Main building block is a “Class”**
  - **Classes have attributes of any type (int, Boolean, enums, etc.)**
  - **References are links to other classes**

```
<!-- Classes -->
<classes>
   <class Name="Requirement Set" NamespaceName="arp4754aReqSdm:RequirementSet" Image="icons/fatcow/farm_fresh/16x16/todo_list.png" Abstract="1"
   ParentClassNamespaceName="sdm:Root">
   </class>
   <class Name="DOORS Requirement Set" NamespaceName="arp4754aReqSdm:RequirementSetDoors" Image="icons/mgc/doors/16x16/doorsModule.png" Abstract="0"
   ParentClassNamespaceName="arp4754aReqSdm:RequirementSet">
      <attribute NamespaceName="arp4754aReqSdm:requirementDoors" Range="0..*"/>
   </class>


   <class Name="Requirement" NamespaceName="arp4754aReqSdm:Requirement" Image="icons/fatcow/farm_fresh/16x16/todo_list.png" Abstract="1"
   ParentClassNamespaceName="sdm:Root" DefaultView="this.attribute('sdm:tabbedView')">
      <!-- Views -->
      <!--
      <attribute NamespaceName="sdm:tabbedView" Range="0">
         <sdmObjectView NamespaceName="sdm:tabbedView" Width="1000px" Height="740px">
            {
               "htmlFile": "aerospaceRequirementWithFDAL.html",
               "cssFiles":
```

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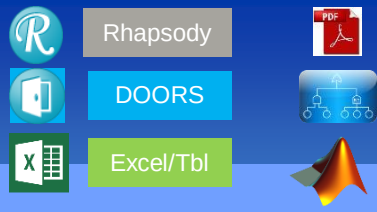
ARP4754A Process with tool layer



Aircraft Function
Stop aircraft on ground

Aircraft FHA
Associated Hazards (by flight phase, with and without annunciation)

- Loss of Deceleration
- Asymmetric Deceleration
- Inadvertent Deceleration

Aircraft Level Design
allocation of stopping to braking, thrust reversal, and spoilers

PASA

- Probabilities/Failures Budgets
- FDAL Assignment

Deceleration A/C Requirements

- Deceleration developed to FDAL A
- Requirement for unannunciated loss of all Wheel Braking as budgeted in FHA
- Requirement for Inadvertent Wheel Braking after V1 as budgeted in FHA

Braking System FHA
Associated Hazards (by flight phase, with and without annunciation)

- Total loss of wheel braking
- Partial Symmetric loss of Wheel Braking
- Asymmetric loss of Wheel Braking
- Asymmetric loss of Wheel Braking combined with Loss of Rudder or Nose wheel steering
- Inadvertent application of braking with all wheels locked (T/O after V1)
- Undetected Inadvertent application of braking to one wheel without locking (T/O)

Wheel Braking System Safety Objectives

- Loss of all wheel braking during landing or RTO
  + Shall be <5E-7 per flight
- Asym Loss of all wheel braking coupled with loss of rudder or now wheel steering during landing or RTO
  + Shall be <5E-7 per flight
- Inadvertent wheel braking with all wheels locked during takeoff roll before V1
  + Shall be <5E-7 per flight

Wheel Braking System Architecture

Wheel Braking System PSSA

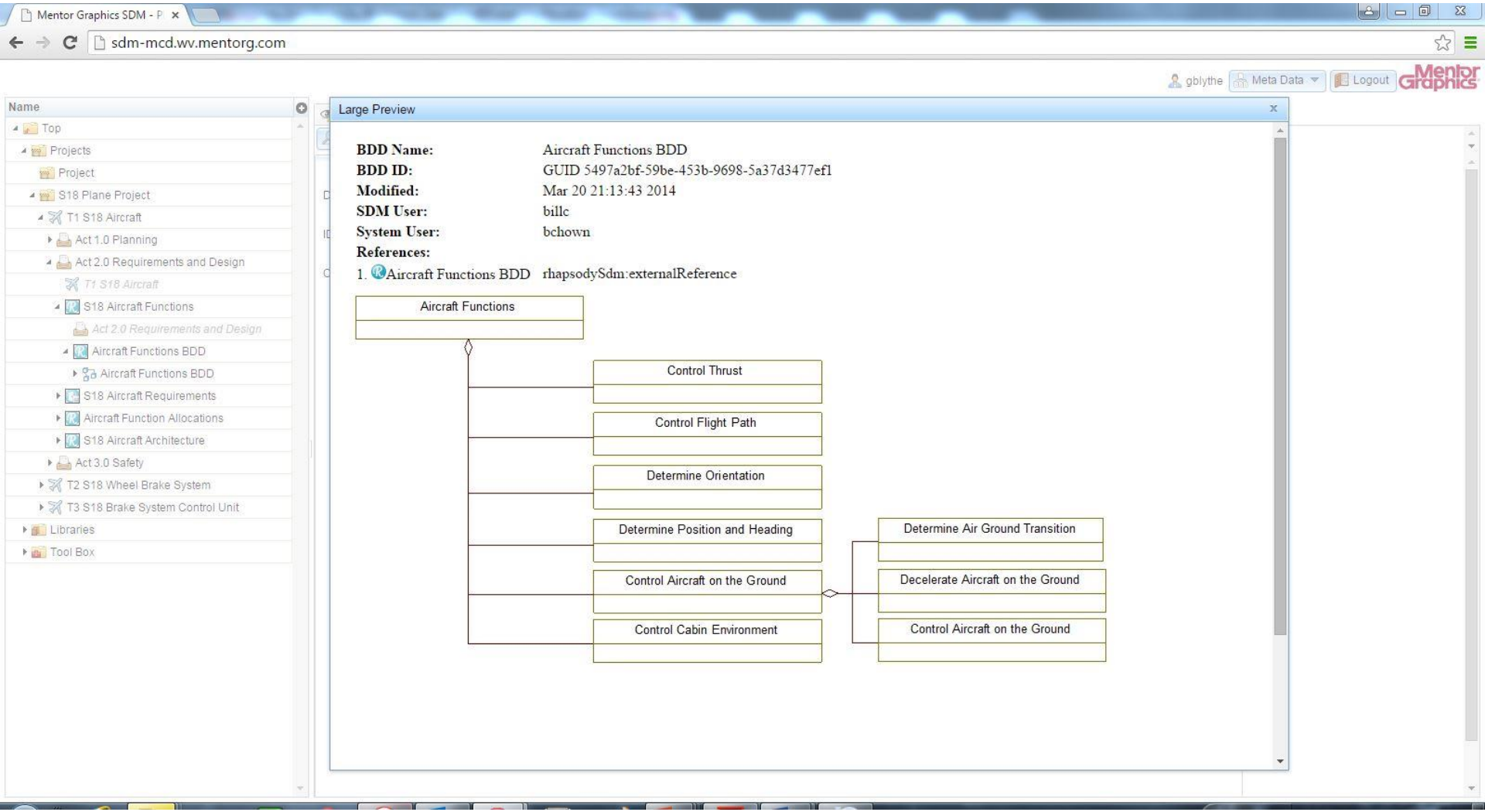
Wheel Braking System Requirements

- Dual Computer channel system and hydraulics
  +Each BSCU shall be developed to FDAL A
  +Each BSCU shall be independent
- Hydraulic se
  rudder and
  steering sys

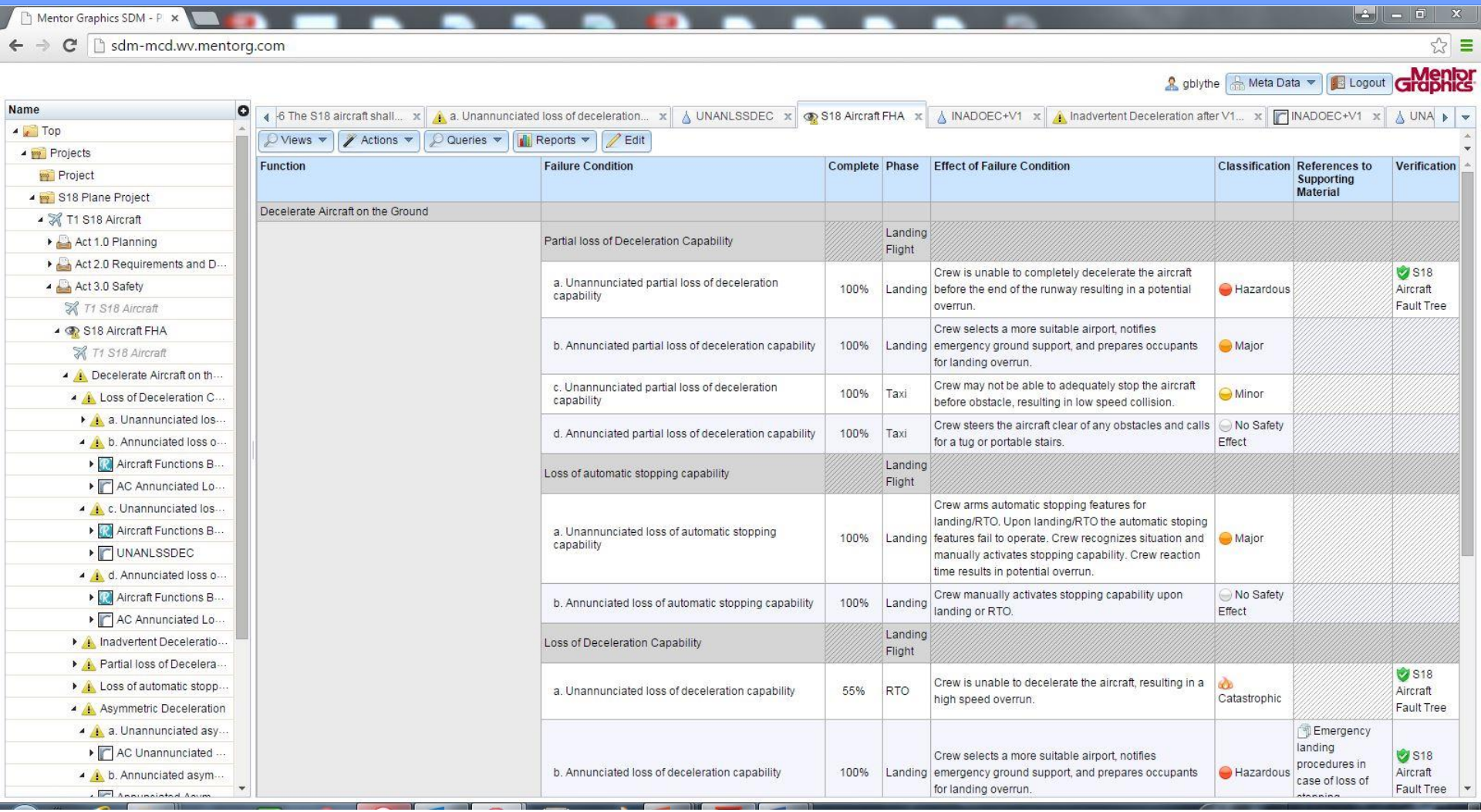
BSCU Requirements

- Dual Lane computer channel
  +The BSCU Channel Items must be developed to IDAL AA, AB, AC, or BB

Results - Aircraft Functions

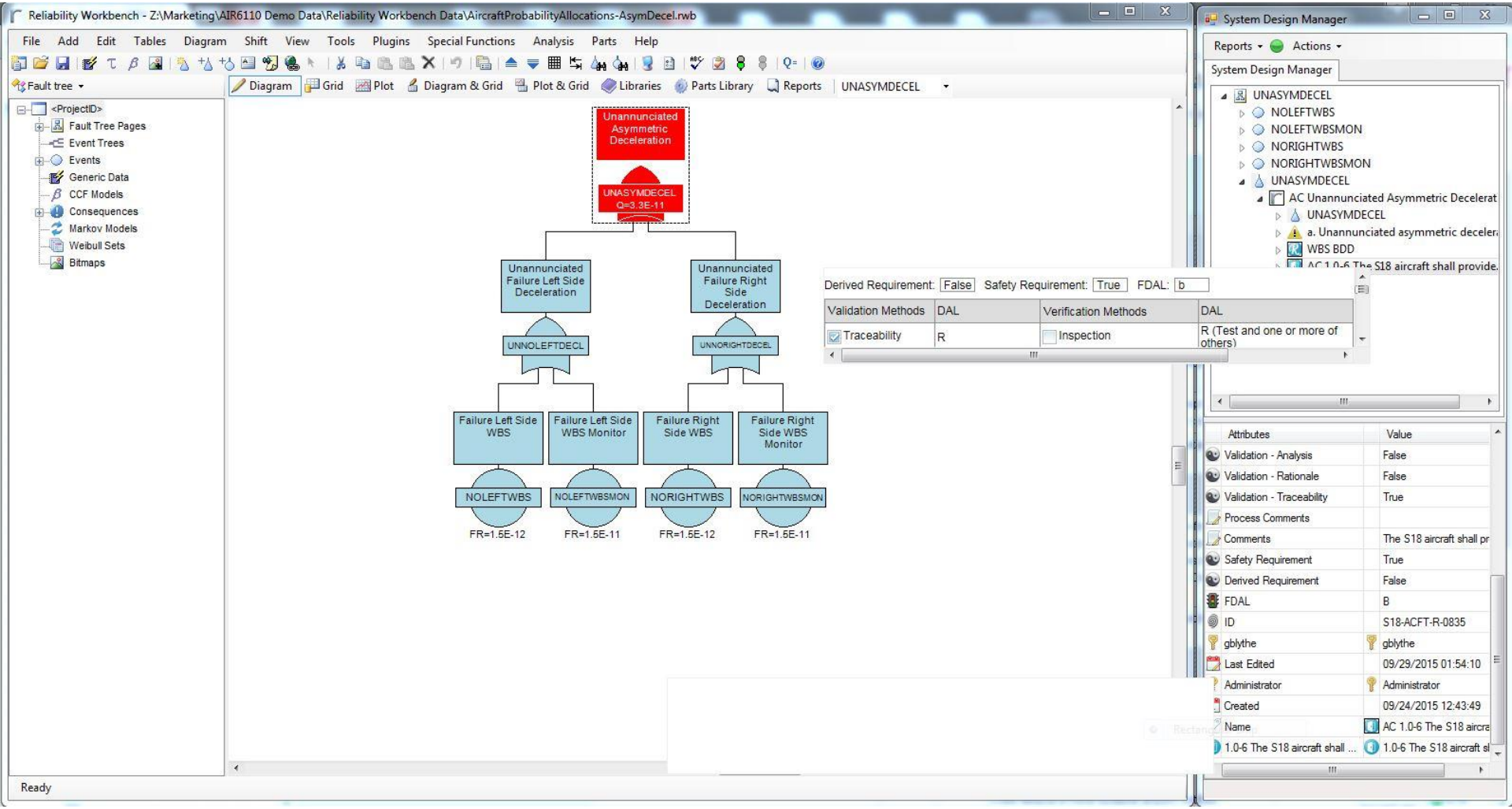


Results - Functional Hazard Assessment

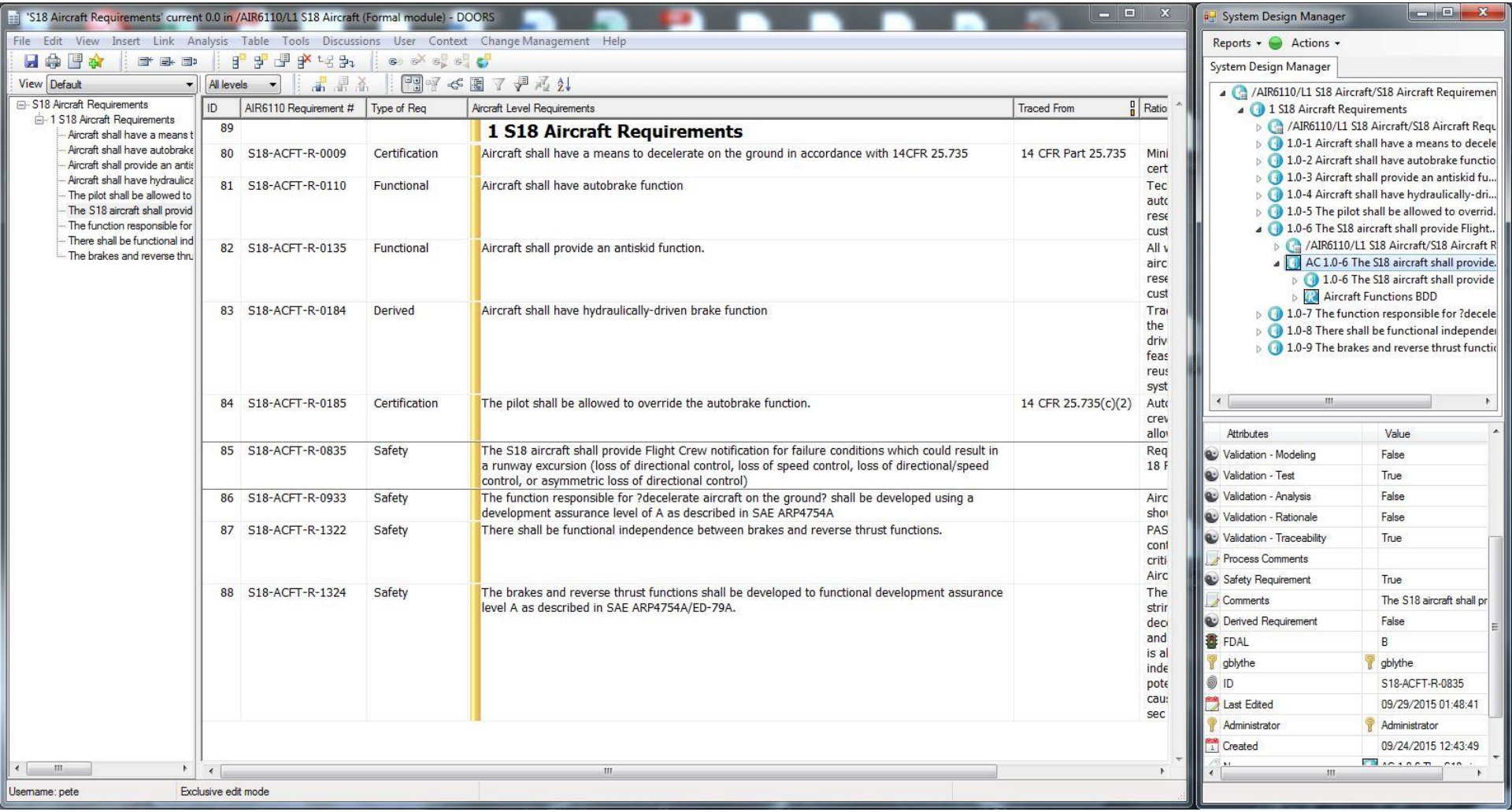


Function	Failure Condition	Complete	Phase	Effect of Failure Condition	Classification	References to Supporting Material	Verification
Decelerate Aircraft on the Ground							
	Partial loss of Deceleration Capability		Landing Flight				
	a. Unannunciated partial loss of deceleration capability	100%	Landing	Crew is unable to completely decelerate the aircraft before the end of the runway resulting in a potential overrun.	Hazardous		S18 Aircraft Fault Tree
	b. Annunciated partial loss of deceleration capability	100%	Landing	Crew selects a more suitable airport, notifies emergency ground support, and prepares occupants for landing overrun.	Major		
	c. Unannunciated partial loss of deceleration capability	100%	Taxi	Crew may not be able to adequately stop the aircraft before obstacle, resulting in low speed collision.	Minor		
	d. Annunciated partial loss of deceleration capability	100%	Taxi	Crew steers the aircraft clear of any obstacles and calls for a tug or portable stairs.	No Safety Effect		
	Loss of automatic stopping capability		Landing Flight				
	a. Unannunciated loss of automatic stopping capability	100%	Landing	Crew arms automatic stopping features for landing/RTO. Upon landing/RTO the automatic stoping features fail to operate. Crew recognizes situation and manually activates stopping capability. Crew reaction time results in potential overrun.	Major		
	b. Annunciated loss of automatic stopping capability	100%	Landing	Crew manually activates stopping capability upon landing or RTO.	No Safety Effect		
	Loss of Deceleration Capability		Landing Flight				
	a. Unannunciated loss of deceleration capability	55%	RTO	Crew is unable to decelerate the aircraft, resulting in a high speed overrun.	Catastrophic		S18 Aircraft Fault Tree
	b. Annunciated loss of deceleration capability	100%	Landing	Crew selects a more suitable airport, notifies emergency ground support, and prepares occupants for landing overrun.	Hazardous	Emergency landing procedures in case of loss of	S18 Aircraft Fault Tree

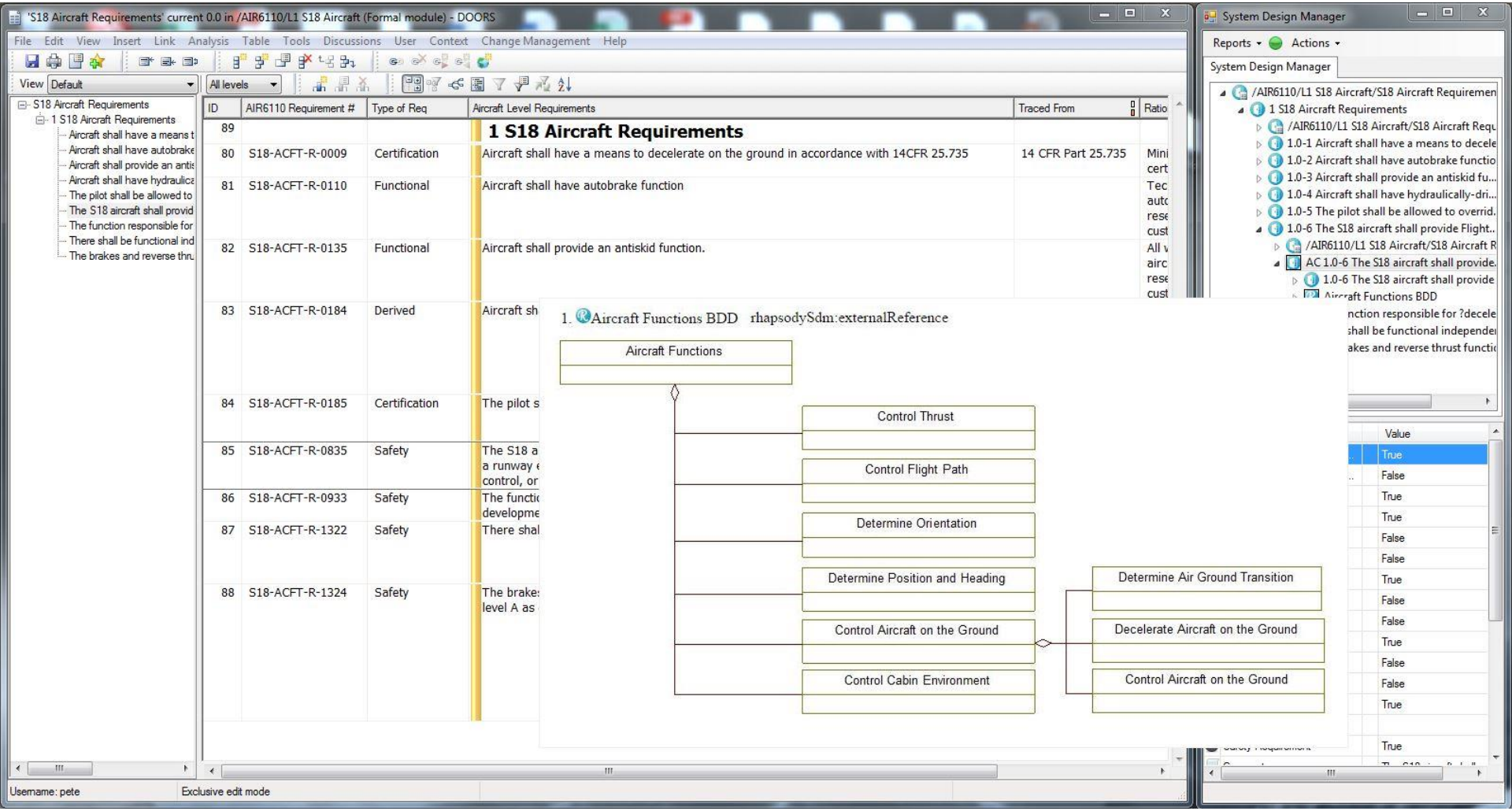
Results – Fault Tree Analysis



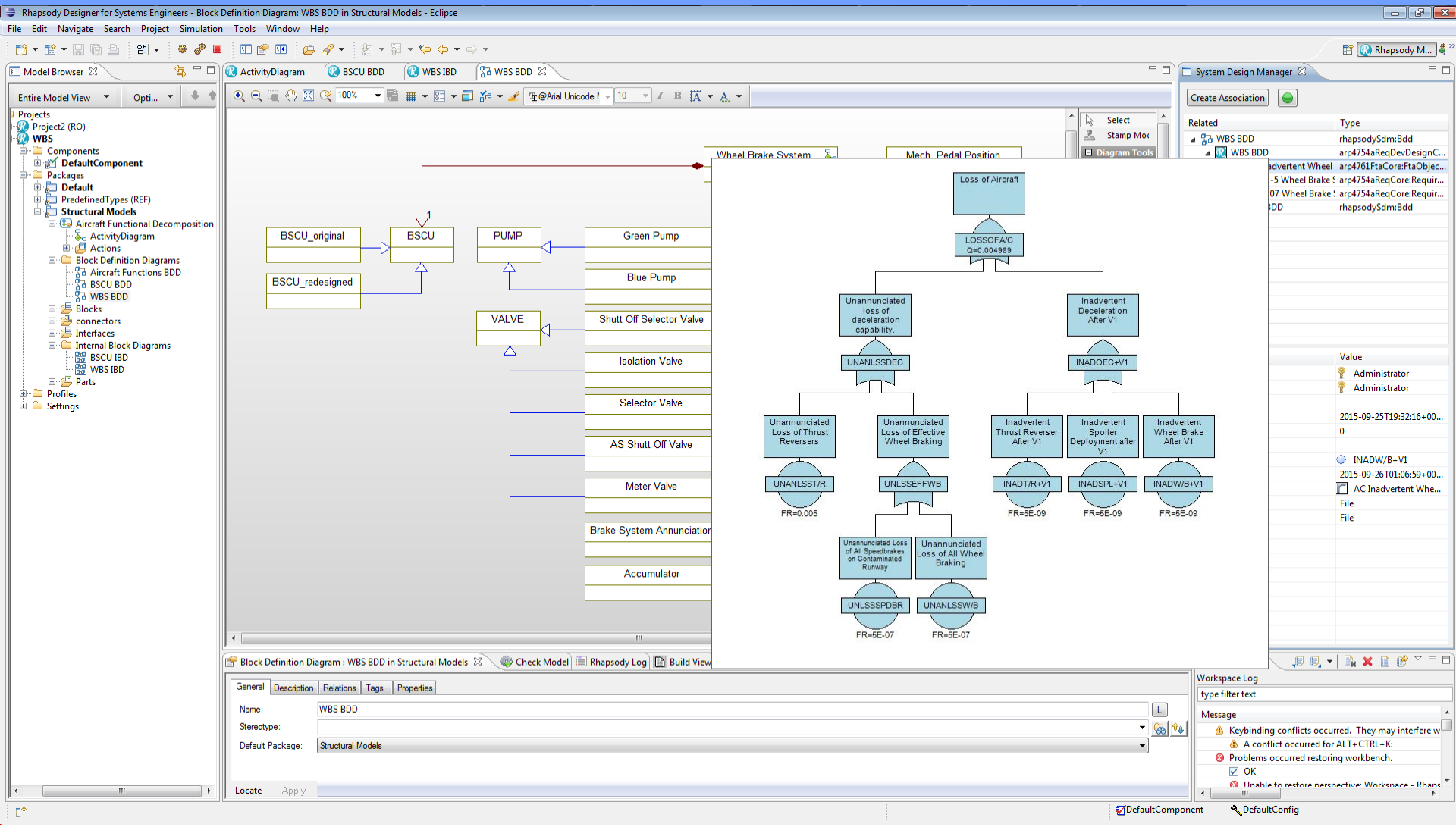
Results – Requirements



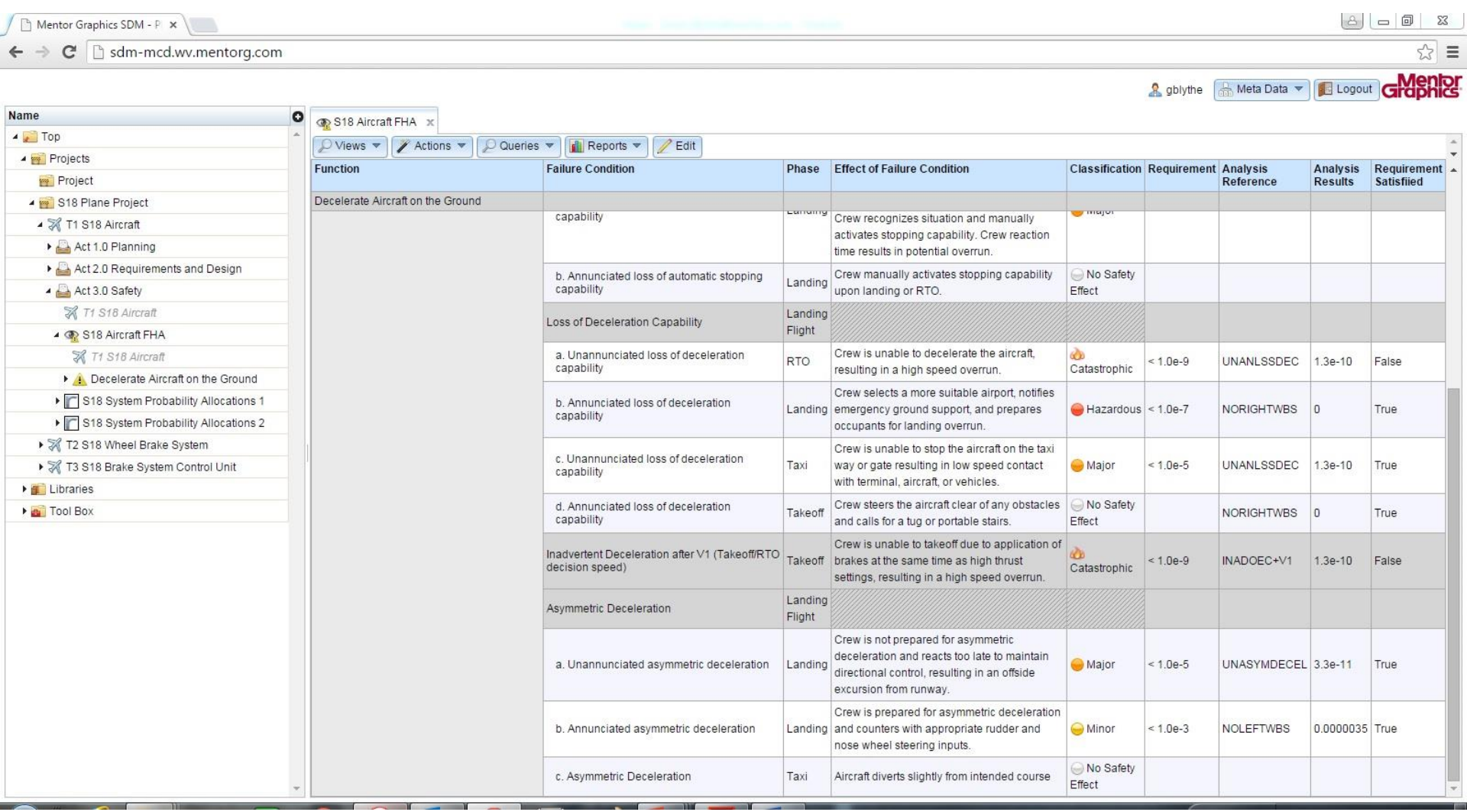
Results – Requirements traced to Design



Results – System Design



Results – Safety Analysis



Function	Failure Condition	Phase	Effect of Failure Condition	Classification	Requirement	Analysis Reference	Analysis Results	Requirement Satisfiied
Decelerate Aircraft on the Ground								
	capability	Landing	Crew recognizes situation and manually activates stopping capability. Crew reaction time results in potential overrun.	Major				
	b. Annunciated loss of automatic stopping capability	Landing	Crew manually activates stopping capability upon landing or RTO.	No Safety Effect				
	Loss of Deceleration Capability	Landing Flight						
	a. Unannunciated loss of deceleration capability	RTO	Crew is unable to decelerate the aircraft, resulting in a high speed overrun.	Catastrophic	< 1.0e-9	UNANLSSDEC	1.3e-10	False
	b. Annunciated loss of deceleration capability	Landing	Crew selects a more suitable airport, notifies emergency ground support, and prepares occupants for landing overrun.	Hazardous	< 1.0e-7	NORIGHTWBS	0	True
	c. Unannunciated loss of deceleration capability	Taxi	Crew is unable to stop the aircraft on the taxi way or gate resulting in low speed contact with terminal, aircraft, or vehicles.	Major	< 1.0e-5	UNANLSSDEC	1.3e-10	True
	d. Annunciated loss of deceleration capability	Takeoff	Crew steers the aircraft clear of any obstacles and calls for a tug or portable stairs.	No Safety Effect		NORIGHTWBS	0	True
	Inadvertent Deceleration after V1 (Takeoff/RTO decision speed)	Takeoff	Crew is unable to takeoff due to application of brakes at the same time as high thrust settings, resulting in a high speed overrun.	Catastrophic	< 1.0e-9	INADOEC+V1	1.3e-10	False
	Asymmetric Deceleration	Landing Flight						
	a. Unannunciated asymmetric deceleration	Landing	Crew is not prepared for asymmetric deceleration and reacts too late to maintain directional control, resulting in an offside excursion from runway.	Major	< 1.0e-5	UNASYMDECEL	3.3e-11	True
	b. Annunciated asymmetric deceleration	Landing	Crew is prepared for asymmetric deceleration and counters with appropriate rudder and nose wheel steering inputs.	Minor	< 1.0e-3	NOLEFTWBS	0.0000035	True
	c. Asymmetric Deceleration	Taxi	Aircraft diverts slightly from intended course	No Safety Effect				

Next Steps: Pursuing Continuous Improvement

Where is non-value added work still existing in the value-stream?

Transportation

- Manually moving/importing/exporting data between multiple design tools
- Manually reformatting/translating data for use in multiple tools

Motion

- Staff switching & multi-tasking across several unintegrated tools
- Searching for data in multiple locations

Waiting

- Attempting to start tasks before inputs are ready
- Tasks not performed according to priority (off critical path)

Over-production

- Creating & maintaining multiple copies of the same data

Defects

- Defects introduced during non-value add activities such as moving, copying, translating data

Improved Usability	Configuration Management	Reporting/Analysis
More robust integrations with toolsets	Better Integrating CM between the selected toolset	Deeper analysis of data. Improved automation of reports

Thank you!

For Questions…

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