

Applying Process Models in a Model-based Safety Analysis Interoperability Platform

Grant Blythe
Mentor Graphics
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GLOBAL PRODUCT DATA INTEROPERABILITY **SUMMIT** 2015



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Grant Blythe Bio

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Grant Blythe is a member of the Systems Level Engineering team at Mentor Graphics where he specializes in solutions for military and aerospace applications. Prior to joining Mentor Graphics, Grant spent 10 years in systems engineering roles developing both commercial and military avionics. In addition to his role at Mentor Graphics, Grant is a member of the SAE S-18 Airplane System Development Committee which publishes the ARP4754A and ARP4761 standards. Grant holds a B.S. in electrical engineering from Iowa State University and an M.B.A. from the University of Oregon.

Agenda

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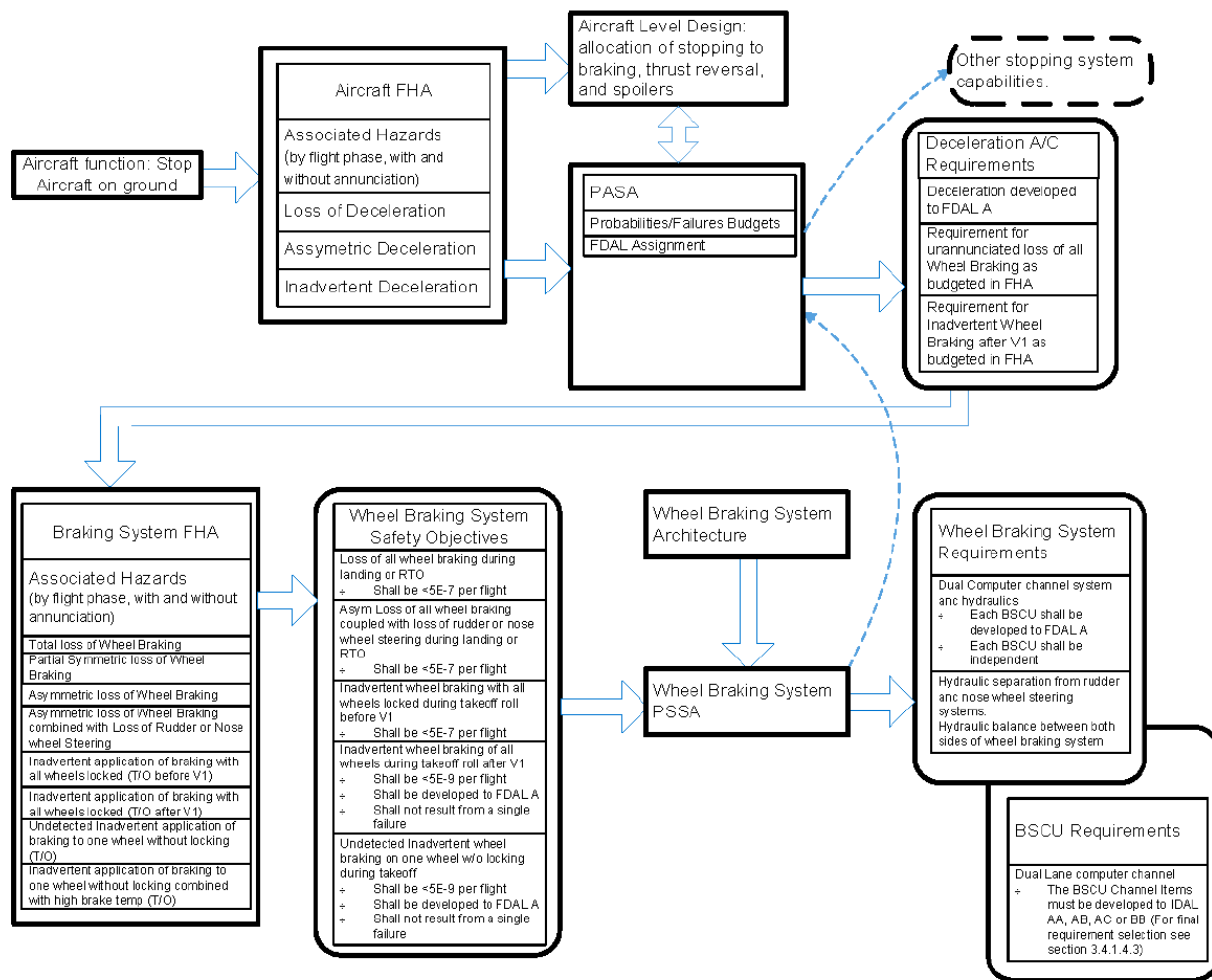
- **The challenge: “leaning” the safety analysis process**
- **The approach: OSLC, SDM, and Process Models**
- **Developing an ARP4754A based Process Model**
- **Project Results & Continuous Improvement**

Wheel Brake System Safety Process

as presented in ARP4754A/ARP4761/AIR6110

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FIGURE 18 - POPULATED WHEEL BRAKE SYSTEM SAFETY ASSESSMENT PROCESS MAP



SAE

AIR6110

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Source: Extracted from SAE AIR6110, Contiguous Aircraft/System Development Process Example.

ARP4754A Process with tool layer

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Rhapsody



DOORS



Excel/Tbl



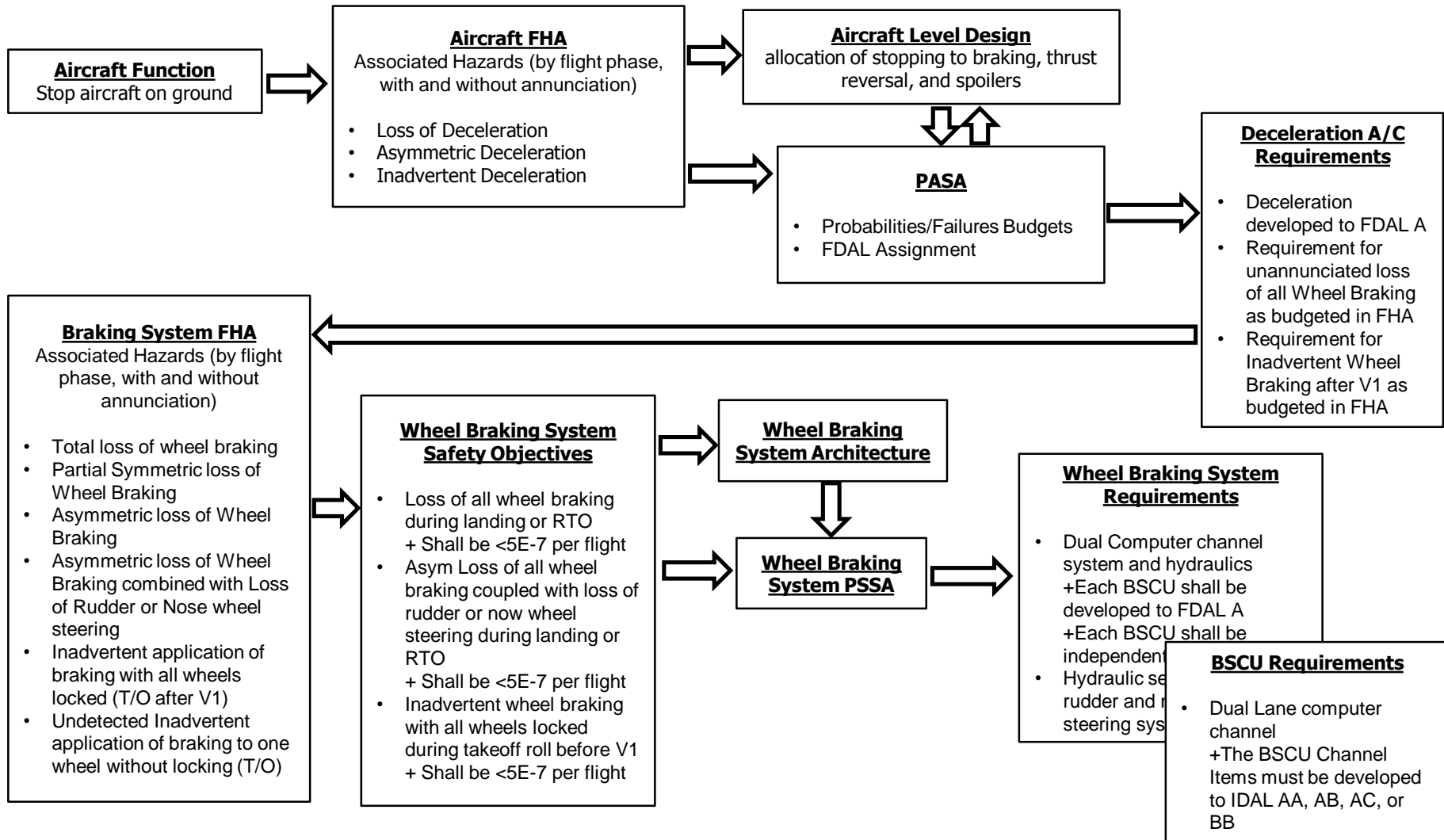
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Waste in System Development Process

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Typical characterizations of some of the wastes in production, and in design

- **Transportation**
 - Manually moving/importing/exporting data between multiple design tools
 - Manually reformatting/translating data for use in multiple tools
- **Motion**
 - Staff switching & multi-tasking across several unintegrated tools
 - Searching for data in multiple locations
- **Waiting**
 - Attempting to start tasks before inputs are ready
 - Tasks not performed according to priority (off critical path)
- **Over-production**
 - Creating & maintaining multiple copies of the same data
- **Defects**
 - Defects introduced during non-value add activities such as moving, copying, translating data



With attention to these – and other sources of waste, a model driven systems engineering approach can yield improvements in productivity, schedule and repeatability that yield higher quality results and enable continuing improvement of the process over iterations and time

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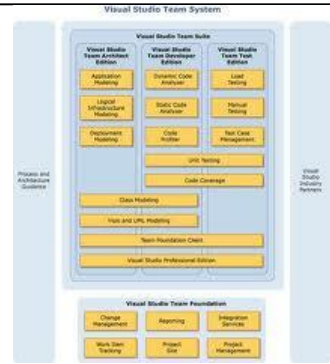
Need for better integration approaches

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Past integration approaches provided limited choice and coverage

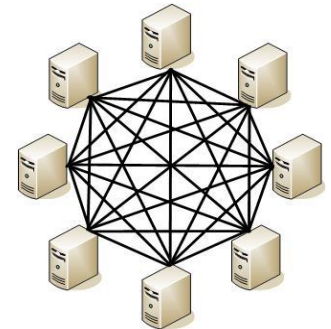
Single repository

“Can I really expect one vendor to provide all the functionality I need? And what about my existing tools?”



Point-to-point integrations

“How can I ever upgrade one tool without breaking everything else?”



Past integration approaches were disruptive and slow to emerge

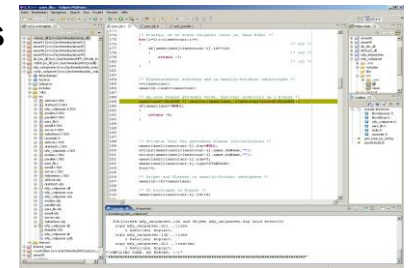
Universal metadata standard

“How did I ever think all those vendors would be able to agree?”



Standard implementations

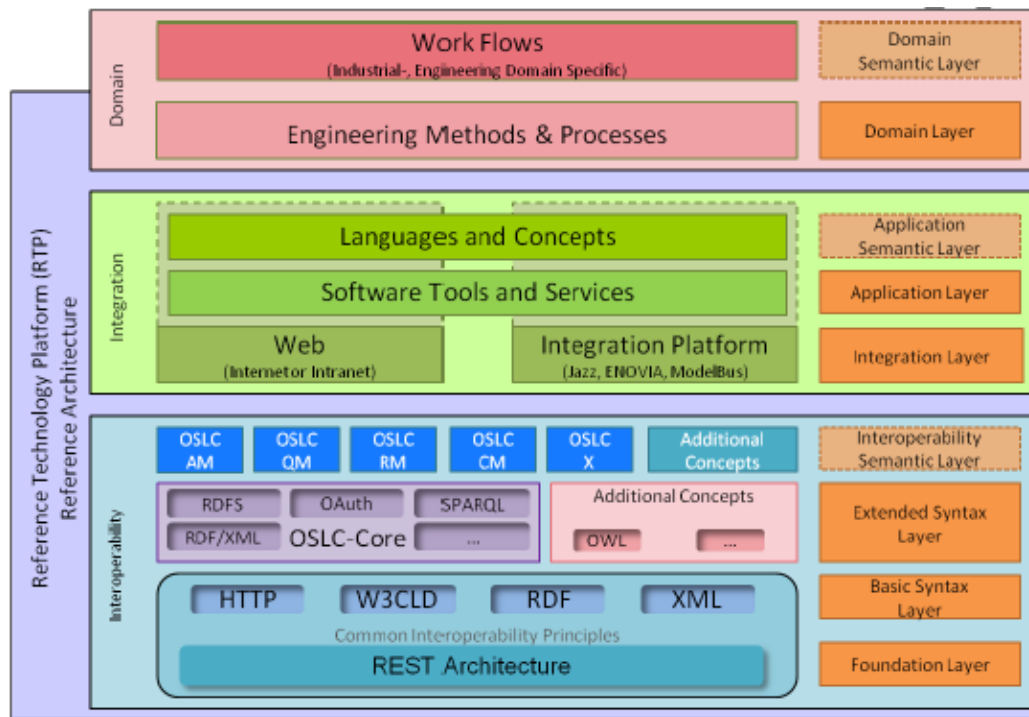
“Did I really believe that every vendor would rewrite their tools on a single framework?”



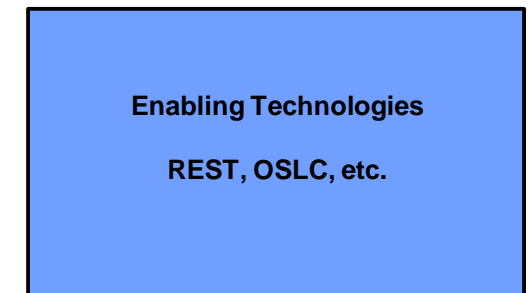
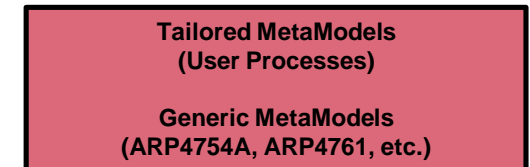
Pilot Project Technology Platform

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CESAR Technology Platform (D_SP1_R1.6_M4)



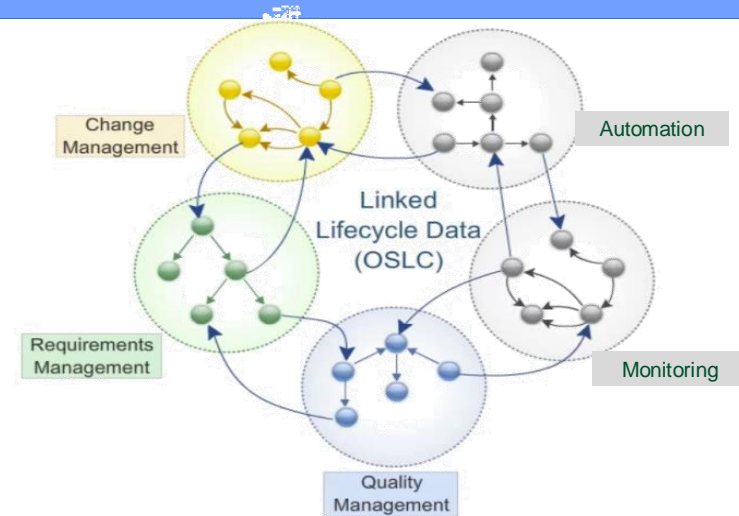
Chosen Platform



Layer 1: Interoperability Open Services for Lifecycle Collaboration

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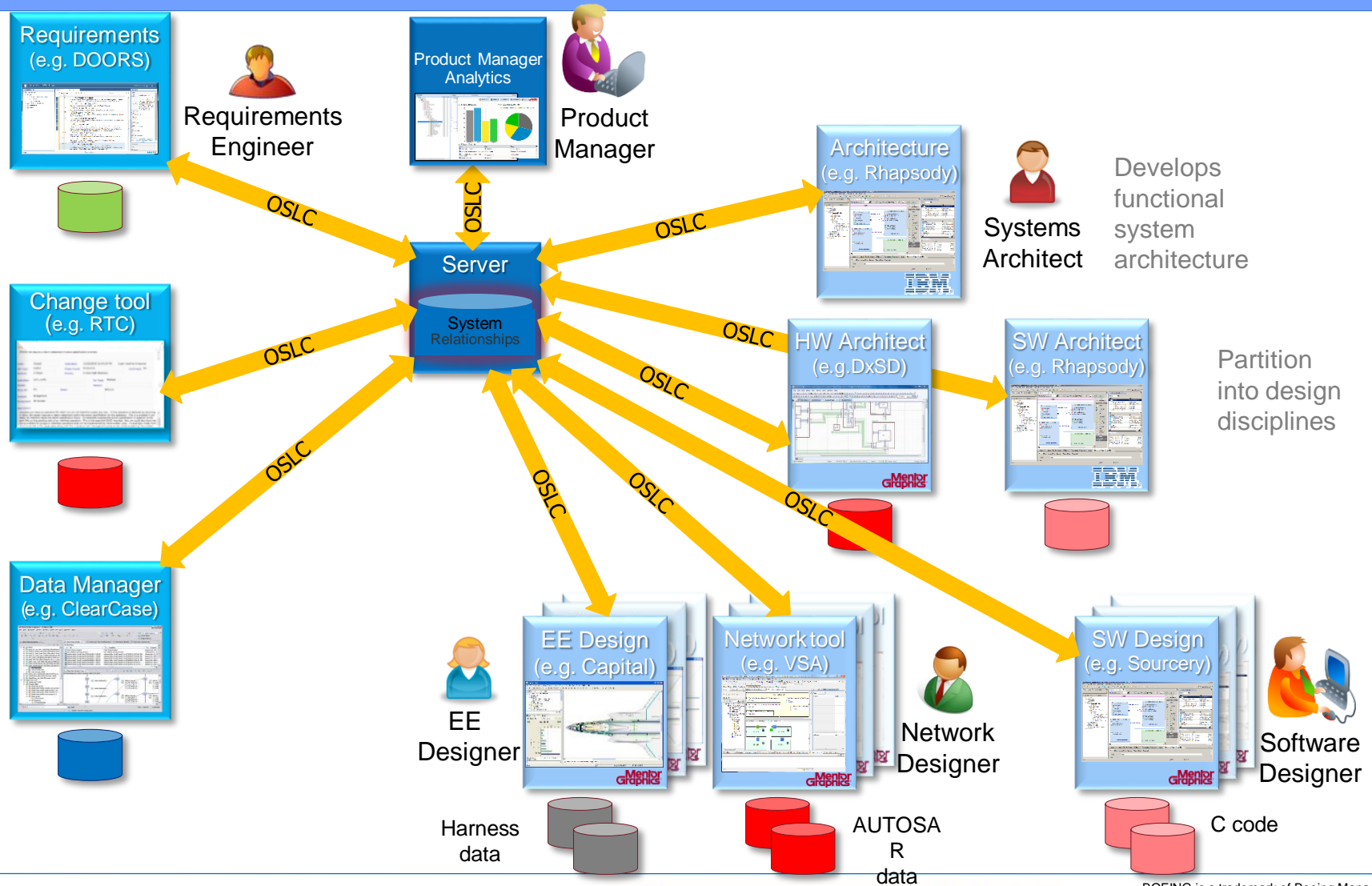
- **Management of linked data**
- **Tool to tool integration**
- **Standards-based communication**



- **Open Services For Lifecycle Collaboration(OSLC)
solves traditional tool integration challenges**
 - Resilient, standards based approach minimizes IT maintenance
 - Seamless experience maximizes user productivity
 - Tool vendor IP protection maximizes commercial appeal

Layer 2: Integration

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Layer 3: Domain Models

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Aerospace ARP4754A/ARP4761 DO-178b/c DO-254



Automotive ISO26262



Medical IEC 60601



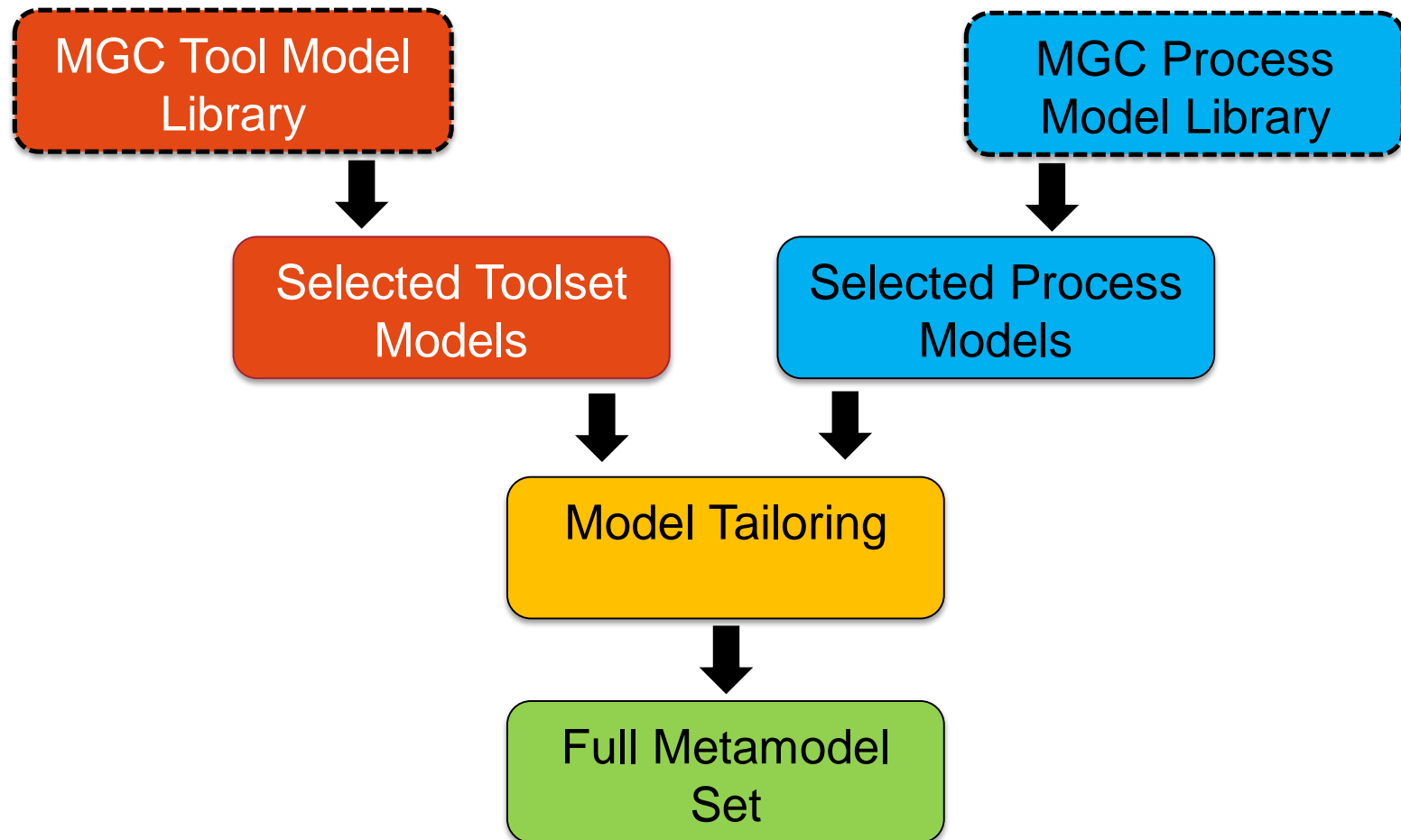
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Metamodel Development and Architecture

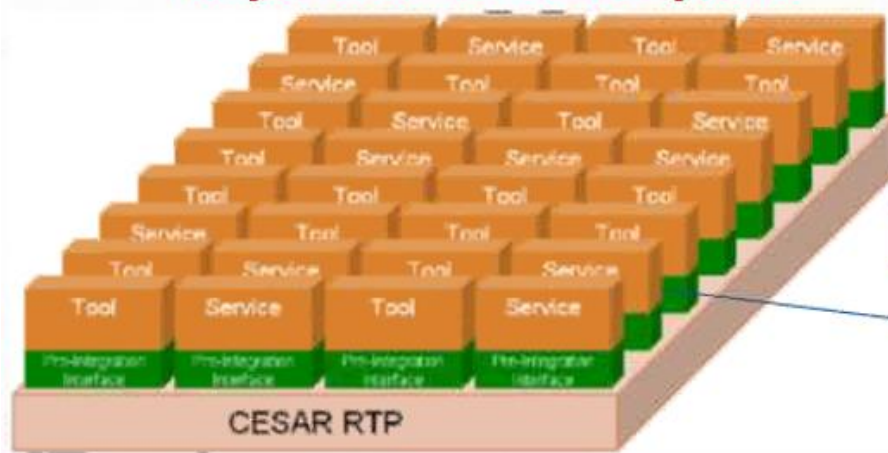
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Platform Tailoring - CESAR

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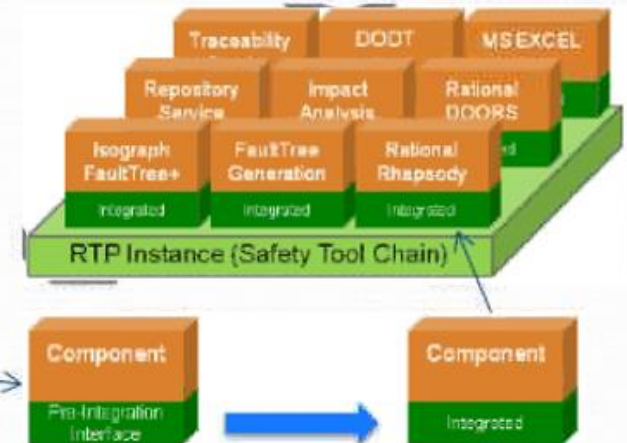
Composition of disconnected components:



The RTP components are in a pre-integrated status and inactive in terms of any functionality.

tailoring process

Ready-to-use engineering environment:

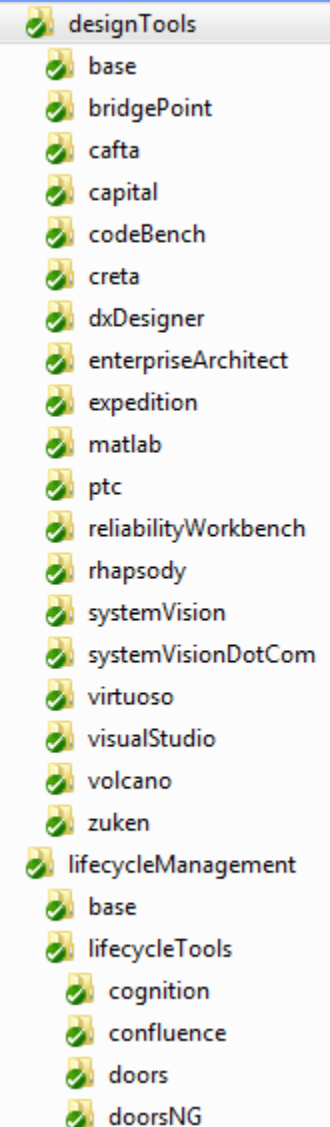


After activating a component, its interface allows consistent information interchange as well as workflow control and analysis
→ the activation process initiates the component with regard to all needed information, such as unique identifier, available network configurations and so on.

Tool Metamodels

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- **Platform Library of Supported Tools**
- **Both a metamodel and a plugin/interface**
- **Developed by Mentor Graphics**
 - Opportunity for user development of new tools integrations in next phase



Process Model Development

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- MGC developed metamodel to generically follow applicable standard
- User organizations can further tailor model to match enterprise processes
- Full process model includes models, views, queries, action listeners, reports, etc.

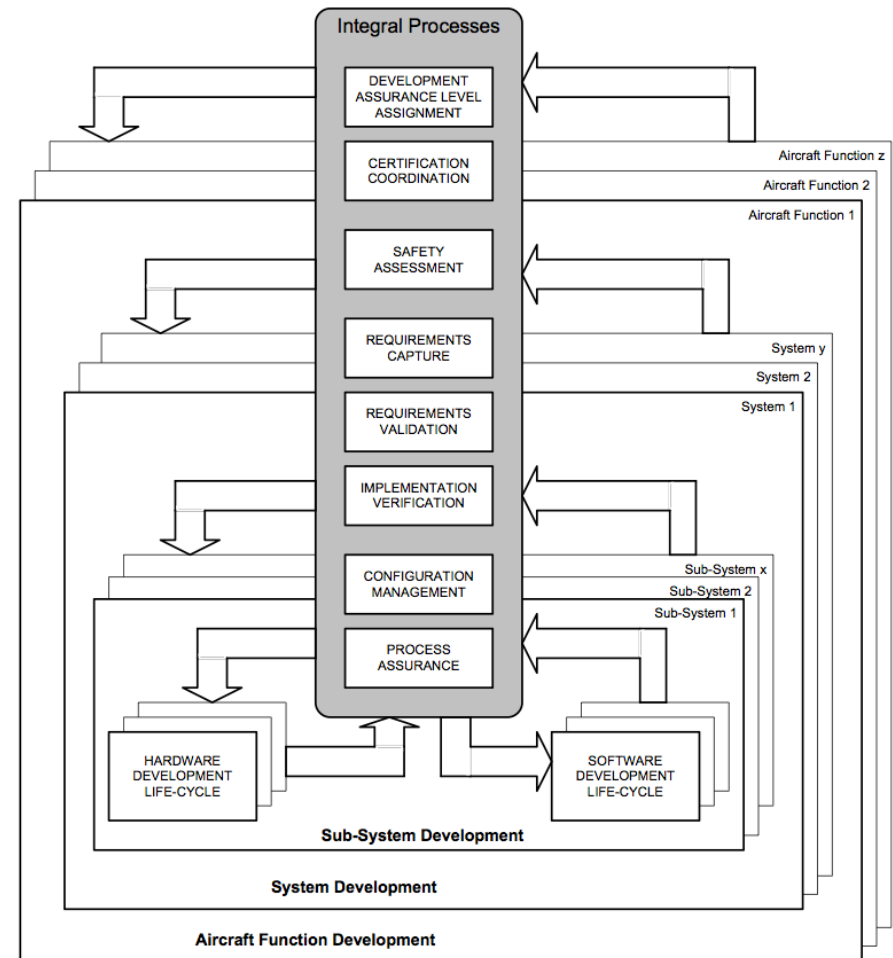


FIGURE 6 - AIRCRAFT FUNCTION IMPLEMENTATION PROCESS

Metamodels – Technical Overview

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- XML Based
- Main building block is a “Class”
 - Classes have attributes of any type (int, Boolean, enums, etc.)
 - References are links to other classes

```
<!-- Classes -->
<classes>
  <class Name="Requirement Set" NamespaceName="arp4754aReqSdm:RequirementSet" Image="icons/fatcow/farm_fresh/16x16/todo_list.png" Abstract="1"
  ParentClassNamespaceName="sdm:Root">
  </class>
  <class Name="DOORS Requirement Set" NamespaceName="arp4754aReqSdm:RequirementSetDoors" Image="icons/mgc/doors/16x16/doorsModule.png" Abstract="0"
  ParentClassNamespaceName="arp4754aReqSdm:RequirementSet">
    <attribute NamespaceName="arp4754aReqSdm:requirementDoors" Range="0..*" />
  </class>

  <class Name="Requirement" NamespaceName="arp4754aReqSdm:Requirement" Image="icons/fatcow/farm_fresh/16x16/todo_list.png" Abstract="1"
  ParentClassNamespaceName="sdm:Root" DefaultView="this.attribute('sdm:tabbedView')">
    <!-- Views -->
    <!--
    <attribute NamespaceName="sdm:tabbedView" Range="0">
      <sdmObjectView NamespaceName="sdm:tabbedView" Width="1000px" Height="740px">
        {
          "htmlFile": "aerospaceRequirementWithFDAL.html",
          "cssFiles":
```

Agenda

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ARP4754A Process with tool layer

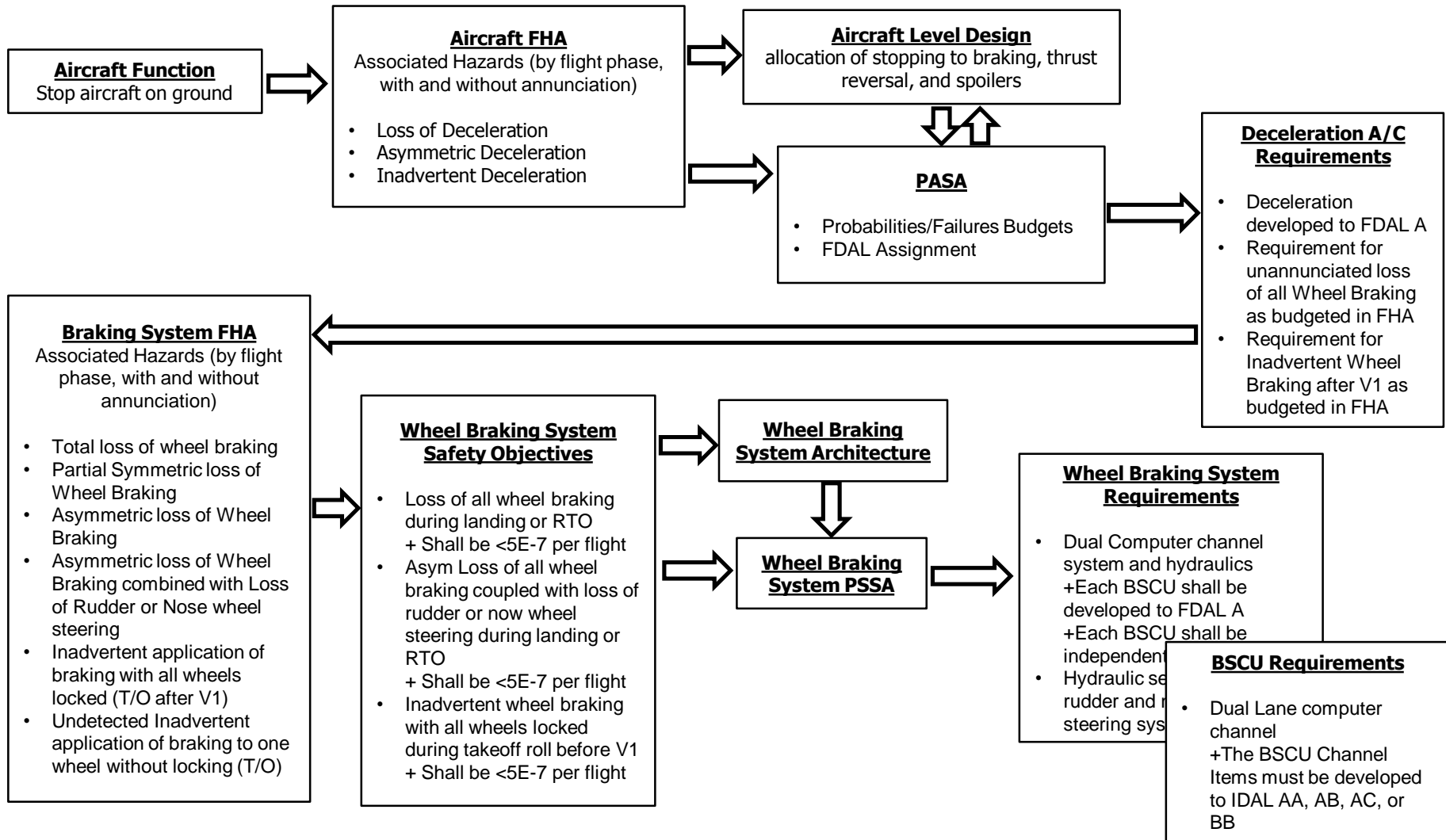
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Rhapsody
DOORS
Excel/Tbl

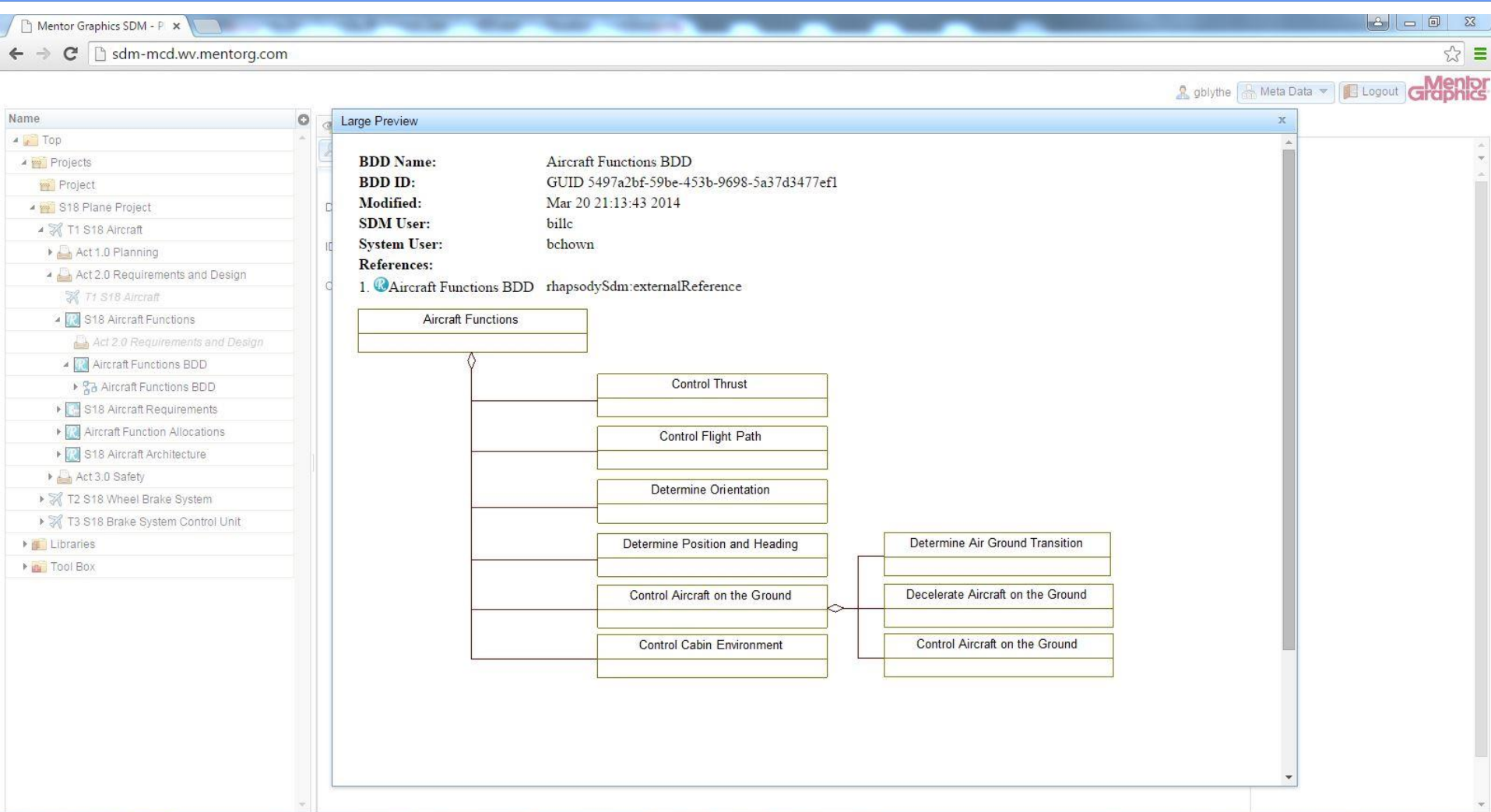


PDFs
CAFTA
Matlab/Simulink



Results - Aircraft Functions

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Results - Functional Hazard Assessment

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Views Actions Queries Reports Edit

Name	Function	Failure Condition	Complete	Phase	Effect of Failure Condition	Classification	References to Supporting Material	Verification
Top	Decelerate Aircraft on the Ground							
Projects		Partial loss of Deceleration Capability		Landing Flight				
Project		a. Unannounced partial loss of deceleration capability	100%	Landing	Crew is unable to completely decelerate the aircraft before the end of the runway resulting in a potential overrun.	Hazardous		✓ S18 Aircraft Fault Tree
S18 Plane Project		b. Announced partial loss of deceleration capability	100%	Landing	Crew selects a more suitable airport, notifies emergency ground support, and prepares occupants for landing overrun.	Major		
T1 S18 Aircraft		c. Unannounced partial loss of deceleration capability	100%	Taxi	Crew may not be able to adequately stop the aircraft before obstacle, resulting in low speed collision.	Minor		
Act 1.0 Planning		d. Announced partial loss of deceleration capability	100%	Taxi	Crew steers the aircraft clear of any obstacles and calls for a tug or portable stairs.	No Safety Effect		
Act 2.0 Requirements and D...		Loss of automatic stopping capability		Landing Flight				
Act 3.0 Safety		a. Unannounced loss of automatic stopping capability	100%	Landing	Crew arms automatic stopping features for landing/RTO. Upon landing/RTO the automatic stopping features fail to operate. Crew recognizes situation and manually activates stopping capability. Crew reaction time results in potential overrun.	Major		
T1 S18 Aircraft		b. Announced loss of automatic stopping capability	100%	Landing	Crew manually activates stopping capability upon landing or RTO.	No Safety Effect		
S18 Aircraft FHA		Loss of Deceleration Capability		Landing Flight				
T1 S18 Aircraft		a. Unannounced loss of deceleration capability	55%	RTO	Crew is unable to decelerate the aircraft, resulting in a high speed overrun.	Catastrophic		✓ S18 Aircraft Fault Tree
Decelerate Aircraft on th...		b. Announced loss of deceleration capability	100%	Landing	Crew selects a more suitable airport, notifies emergency ground support, and prepares occupants for landing overrun.	Hazardous	Emergency landing procedures in case of loss of stopping	✓ S18 Aircraft Fault Tree
Loss of Deceleration C...								
a. Unannounced los...								
b. Announced loss o...								
Aircraft Functions B...								
AC Announced Lo...								
c. Unannounced los...								
Aircraft Functions B...								
AC Announced Lo...								
d. Announced loss o...								
Aircraft Functions B...								
AC Announced Lo...								
Inadvertent Deceleratio...								
Partial loss of Decelera...								
Loss of automatic stopp...								
Asymmetric Deceleration								
a. Unannounced asy...								
AC Unannounced ...								
b. Announced asym...								
Announced asym...								

Results – Fault Tree Analysis

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Reliability Workbench - Z:\Marketing\AIR6110 Demo Data\Reliability Workbench Data\AircraftProbabilityAllocations-AsymDecel.rwb

File Add Edit Tables Diagram Shift View Tools Plugins Special Functions Analysis Parts Help

Diagram Grid Plot Diagram & Grid Plot & Grid Libraries Parts Library Reports UNASYMDECEL

ProjectID>
Fault Tree Pages
Event Trees
Events
Generic Data
CCF Models
Consequences
Markov Models
Weibull Sets
Bitmaps

Unannounced Asymmetric Deceleration
UNASYMDECEL
Q=3.3E-11

Unannounced Failure Left Side Deceleration
UNNOLEFTDECL

Unannounced Failure Right Side Deceleration
UNNORIGHTDECL

Failure Left Side WBS
NOLEFTWBS
FR=1.5E-12

Failure Left Side WBS Monitor
NOLEFTWBSMON
FR=1.5E-11

Failure Right Side WBS
NORIGHTWBS
FR=1.5E-12

Failure Right Side WBS Monitor
NORIGHTWBSMON
FR=1.5E-11

Derived Requirement: ☐ False Safety Requirement: ☒ True FDAL:

Validation Methods	DAL	Verification Methods	DAL
<input checked="" type="checkbox"/> Traceability	R	<input type="checkbox"/> Inspection	R (Test and one or more of others)

Attributes Value

Attributes	Value
Validation - Analysis	False
Validation - Rationale	False
Validation - Traceability	True
Process Comments	
Comments	The S18 aircraft shall pr
Safety Requirement	True
Derived Requirement	False
FDAL	B
ID	S18-ACFT-R-0835
gbltye	gbltye
Last Edited	09/29/2015 01:54:10
Administrator	Administrator
Created	09/24/2015 12:43:49
Name	AC 1.0-6 The S18 airca
1.0-6 The S18 aircraft shall ...	1.0-6 The S18 aircraft s

Ready

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 INTEROPERABILITY
SUMMIT **2015**

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 GPDIS_2015.ppt | 24

Results – Requirements traced to Design

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The screenshot displays two software windows. The main window is 'S18 Aircraft Requirements' in DOORS, showing a table of requirements and a linked functional block diagram. The table lists requirements with IDs, AIR6110 numbers, types, descriptions, and tracing information. The diagram shows a hierarchy starting with 'Aircraft Functions' and branching into various control and determination functions.

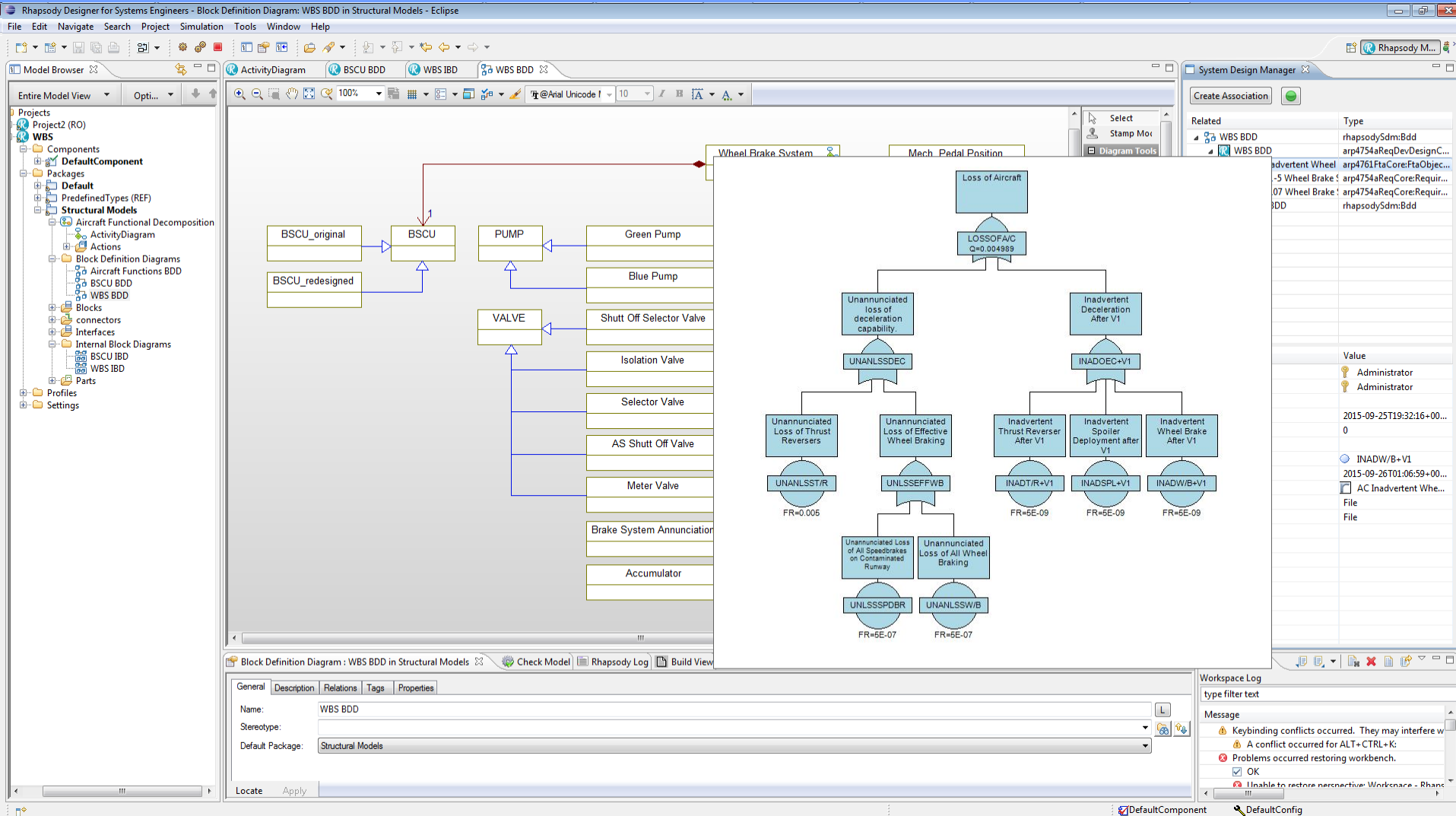
ID	AIR6110 Requirement #	Type of Req	Aircraft Level Requirements	Traced From	Ratio
89			1 S18 Aircraft Requirements		
80	S18-ACFT-R-0009	Certification	Aircraft shall have a means to decelerate on the ground in accordance with 14CFR 25.735	14 CFR Part 25.735	Mini cert
81	S18-ACFT-R-0110	Functional	Aircraft shall have autobrake function		Tec autt rese cust
82	S18-ACFT-R-0135	Functional	Aircraft shall provide an antiskid function.		All v airc rese cust
83	S18-ACFT-R-0184	Derived	Aircraft sh		
84	S18-ACFT-R-0185	Certification	The pilot s		
85	S18-ACFT-R-0835	Safety	The S18 a a runway c control, or		
86	S18-ACFT-R-0933	Safety	The functi developme		
87	S18-ACFT-R-1322	Safety	There shal		
88	S18-ACFT-R-1324	Safety	The brake: level A as		

Functional Block Diagram:

- 1. Aircraft Functions BDD rhapsodySdm:externalReference
 - Aircraft Functions
 - Control Thrust
 - Control Flight Path
 - Determine Orientation
 - Determine Position and Heading
 - Determine Air Ground Transition
 - Decelerate Aircraft on the Ground
 - Control Aircraft on the Ground
 - Control Cabin Environment

Results – System Design

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Results – Safety Analysis

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Name

- Top
- Projects
 - Project
 - S18 Plane Project
 - T1 S18 Aircraft
 - Act 1.0 Planning
 - Act 2.0 Requirements and Design
 - Act 3.0 Safety
 - T1 S18 Aircraft
 - S18 Aircraft FHA
 - T1 S18 Aircraft
 - Decelerate Aircraft on the Ground
 - S18 System Probability Allocations 1
 - S18 System Probability Allocations 2
 - T2 S18 Wheel Brake System
 - T3 S18 Brake System Control Unit
 - Libraries
 - Tool Box

S18 Aircraft FHA

Views Actions Queries Reports Edit

| Function | Failure Condition | Phase | Effect of Failure Condition | Classification | Requirement | Analysis Reference | Analysis Results | Requirement Satisfied |
|-----------------------------------|--|----------------|--|------------------|-------------|--------------------|------------------|-----------------------|
| Decelerate Aircraft on the Ground | capability | Landing | Crew recognizes situation and manually activates stopping capability. Crew reaction time results in potential overrun. | Major | | | | |
| | b. Annunciated loss of automatic stopping capability | Landing | Crew manually activates stopping capability upon landing or RTO. | No Safety Effect | | | | |
| | Loss of Deceleration Capability | Landing Flight | | | | | | |
| | a. Unannunciated loss of deceleration capability | RTO | Crew is unable to decelerate the aircraft, resulting in a high speed overrun. | Catastrophic | < 1.0e-9 | UNANLSSDEC | 1.3e-10 | False |
| | b. Annunciated loss of deceleration capability | Landing | Crew selects a more suitable airport, notifies emergency ground support, and prepares occupants for landing overrun. | Hazardous | < 1.0e-7 | NORIGHTWBS | 0 | True |
| | c. Unannunciated loss of deceleration capability | Taxi | Crew is unable to stop the aircraft on the taxi way or gate resulting in low speed contact with terminal, aircraft, or vehicles. | Major | < 1.0e-5 | UNANLSSDEC | 1.3e-10 | True |
| | d. Annunciated loss of deceleration capability | Takeoff | Crew steers the aircraft clear of any obstacles and calls for a tug or portable stairs. | No Safety Effect | | NORIGHTWBS | 0 | True |
| | Inadvertent Deceleration after V1 (Takeoff/RTO decision speed) | Takeoff | Crew is unable to takeoff due to application of brakes at the same time as high thrust settings, resulting in a high speed overrun. | Catastrophic | < 1.0e-9 | INADOEC+V1 | 1.3e-10 | False |
| | Asymmetric Deceleration | Landing Flight | | | | | | |
| | a. Unannunciated asymmetric deceleration | Landing | Crew is not prepared for asymmetric deceleration and reacts too late to maintain directional control, resulting in an offside excursion from runway. | Major | < 1.0e-5 | UNASYMDECEL | 3.3e-11 | True |
| | b. Annunciated asymmetric deceleration | Landing | Crew is prepared for asymmetric deceleration and counters with appropriate rudder and nose wheel steering inputs. | Minor | < 1.0e-3 | NOLEFTWBS | 0.0000035 | True |
| | c. Asymmetric Deceleration | Taxi | Aircraft diverts slightly from intended course | No Safety Effect | | | | |

Next Steps: Pursuing Continuous Improvement

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Where is non-value added work still existing in the value-stream?

Transportation

- Manually moving/importing/exporting data between multiple design tools
- Manually reformatting/translating data for use in multiple tools

Motion

- Staff switching & multi-tasking across several unintegrated tools
- Searching for data in multiple locations

Waiting

- Attempting to start tasks before inputs are ready
- Tasks not performed according to priority (off critical path)

Over-production

- Creating & maintaining multiple copies of the same data

Defects

- Defects introduced during non-value add activities such as moving, copying, translating data

Improved
Usability

More robust
integrations with
toolsets

Configuration
Management

Better Integrating
CM between the
selected toolset

Reporting/Analysis

Deeper analysis of
data. Improved
automation of
reports

Thank you!

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For Questions...

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