Augmenting Current Tools and Processes to increase the productivity of an engineering team

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Bill Chown

- Product Manager for the System-Level Engineering division at Mentor Graphics, responsible for OSLC-based integrated tool solutions for system design management.
- Bill has worked as an electronic designer, systems engineer and group leader in both systems and semiconductor companies before joining the EDA vendor community at its inception thirty years ago.
- He is active in several standards bodies, a board member for the Object Management Group, member of the OASIS OSLC steering committee, a Senior Member of the IEEE, and Secretary of the Cascade Chapter of INCOSE.









System Design Challenges

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Dealing with Complexity and Change

- Ever increasing and evolving design requirements
- Convergence of multiple disciplines in a single system from requirements through implementation
- Complicated communication due to domain-specific tools, file formats, databases, and protocols
- Inter-divisional or even multi-company supply chains
- Literally millions of design artifacts for even a moderately sized project















A Flow-based Use Case Example for Safety Analysis

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Requirements

Typically in "Systems Engineering"

System Architecture

Often not the same person[s] in "Systems"

Fault Injection Modeling

Representative architecture and hazard simulation

Fault Tree Analysis

Traditional logical deductive failure analysis

Changes that Permeate Throughout

Demands comprehension of variants across domains









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Captures system requirements



Rev x



New/changed requirement

Traditional communication approaches (e.g., hallway discussions, email, staff meetings, etc.)





Develops functional system architecture



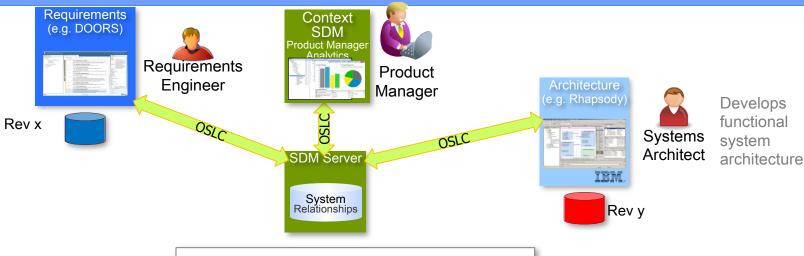








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Tool-to-tool communication can automate and integrate

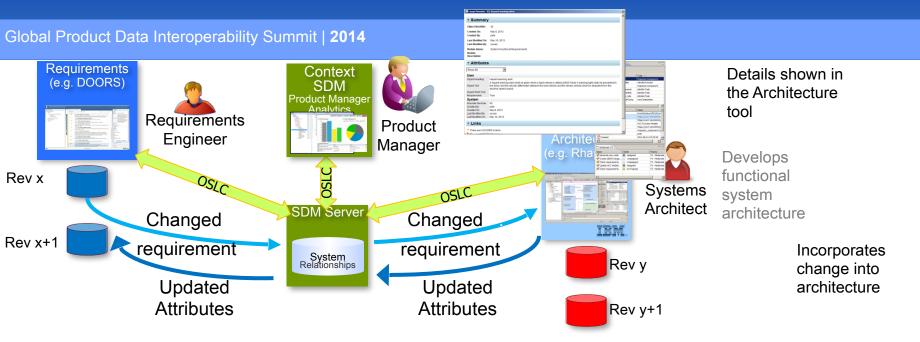
The Context SDM Server acts as a focal point, shares relevant changes, and builds history











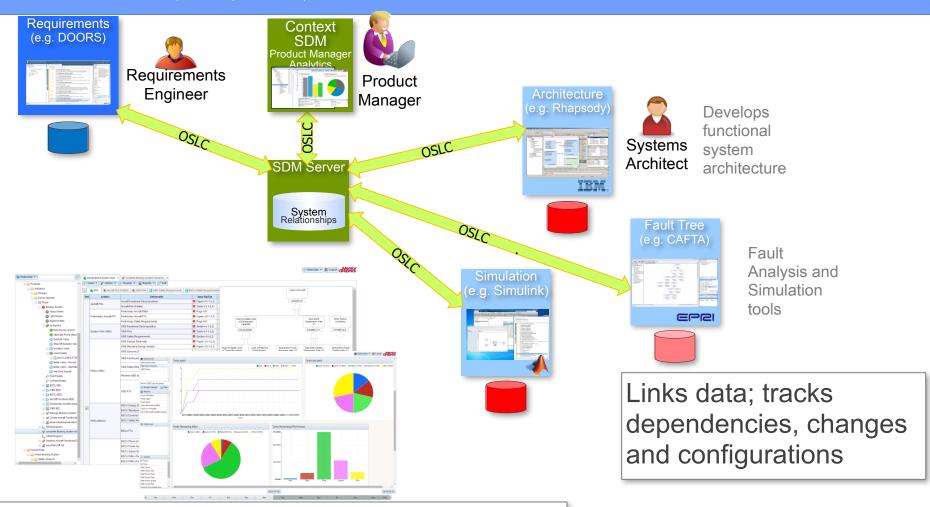








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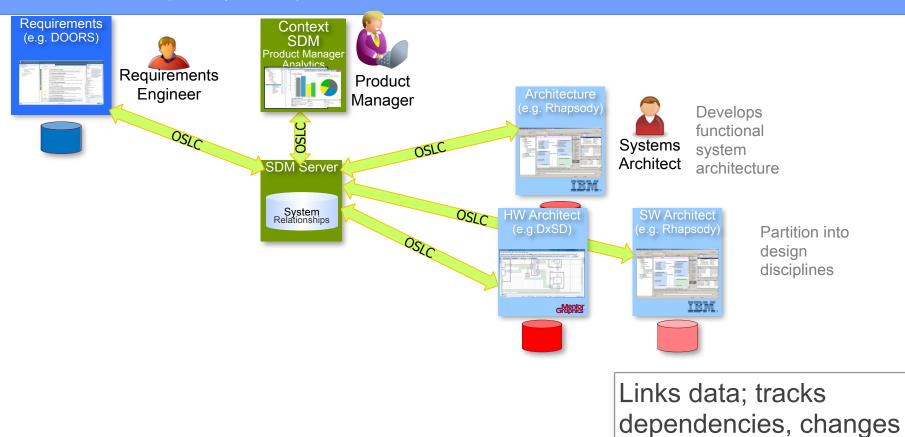
Cross-reference information, extract analyses





Logical and Physical Architectures

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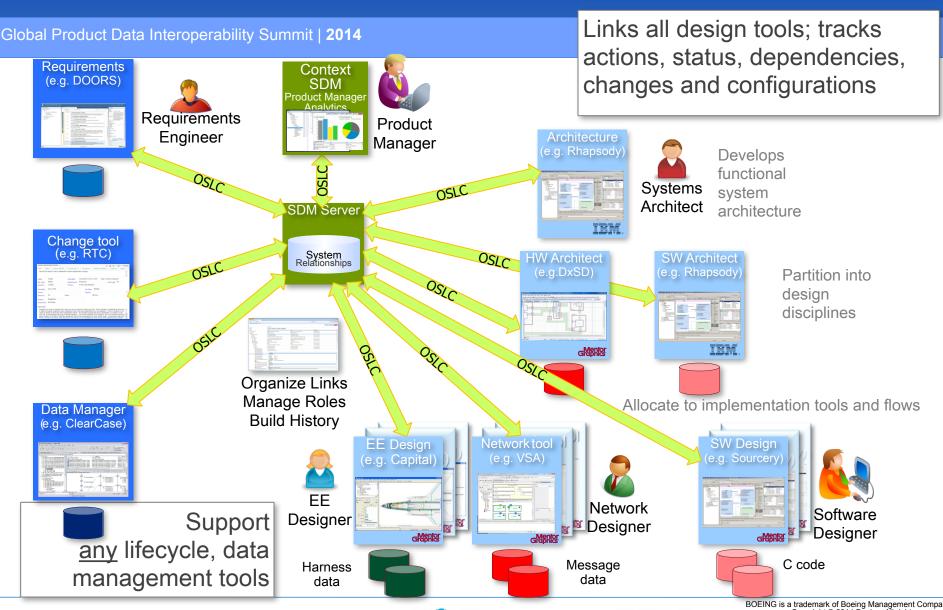






and configurations

Logical and Physical Architectures













Lifecycle Management for 'Work in Progress'

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Managing Change

Changing requirements, dependencies, configurations

Coordinating Disciplines

Differing schedules, steps, terminology, progress

Finding Information

Standards, processes, requirements, dependencies

Meeting Standards

Regulatory, process, and corporate needs

Proving Process and Traceability

Required by most standards and regulatory bodies

Report Status, Standards, Results...

Extracting, abstracting, and organizing information

Hand Off to Production

Version & configuration management and tracking







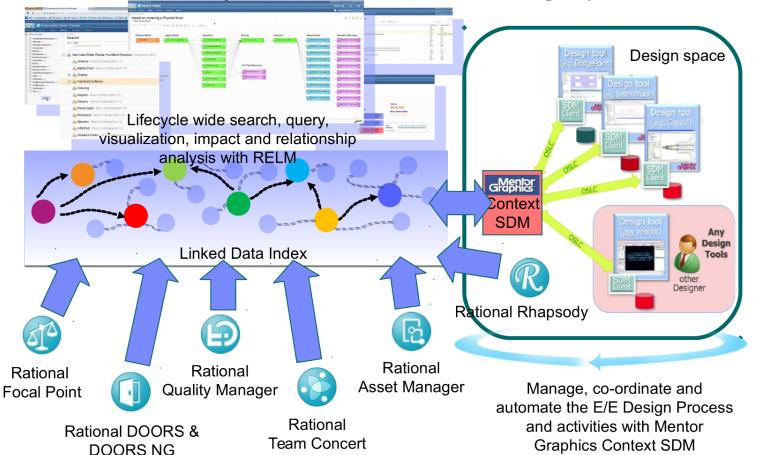




RELM with Mentor Graphics Context SDM



Extend RELM visibility to include the entire E/E design space



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ELYSIUM









Introducing Context™ SDM

- Management of linked data
- Tool-to tool-integration
- Standards-based communication



- Context Server stores and manages the links
 - Builds history; enables traceability and reporting
 - Original data remains with original tools and repositories
- Context SDM plugins augment design tools
 - Integration available for any Mentor tool
 - Can also support other vendors' or internal design tools
- Web-based Product Manager accesses data and analytics
- OSLC standard connects to other tools









Scenarios and Use Cases

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- The Project Manager needs ...
 - Visibility and status



Access to relevant information



Traceability and auditability



- Complete and current data
- The System Designer needs ...
 - The right product, at the right time

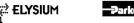












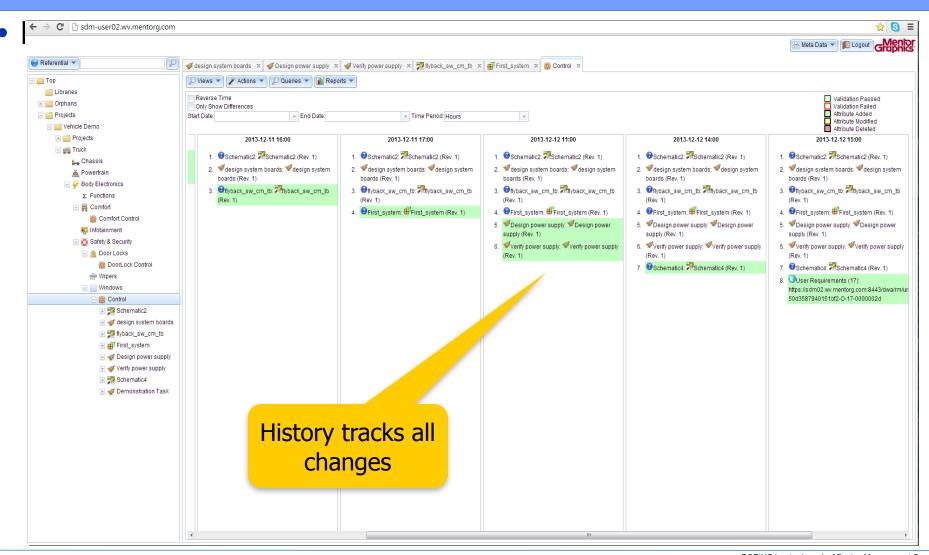








Building Relationships around the Product





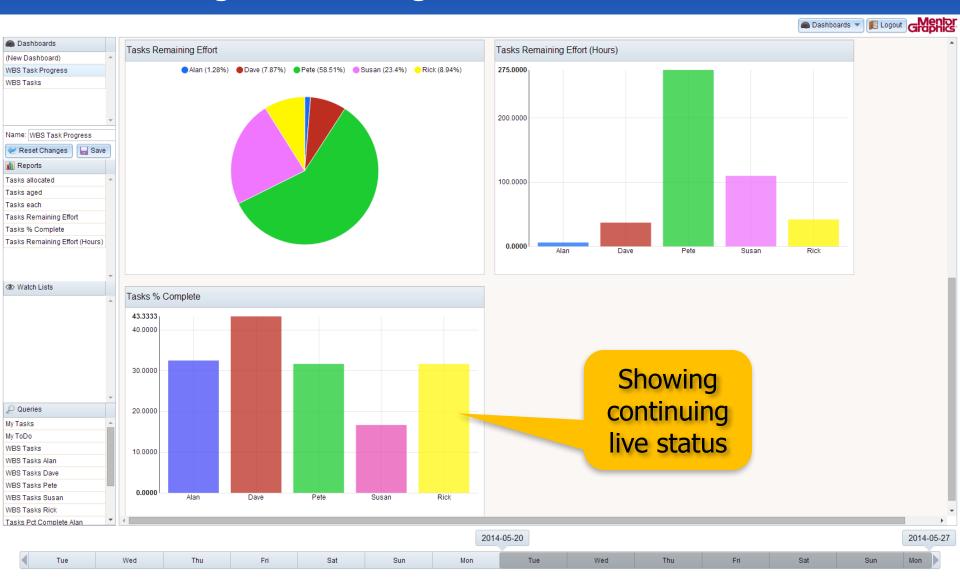








Product Manager – Tracking Resources













Design Tool Use Cases

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Remain in the familiar cockpit

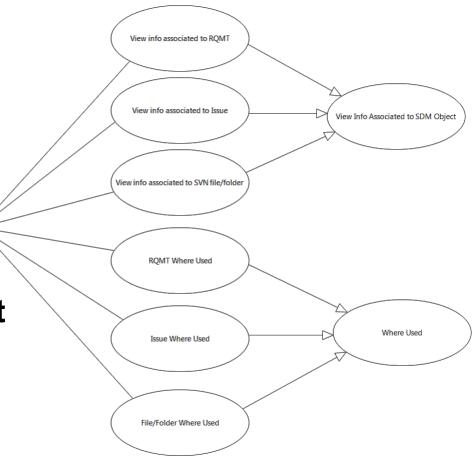
Perform usual activities

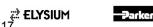
"Link as you think"

Access to all design dependencies

• Interactivity with System Engineer System En

Immediate status and issue visibility



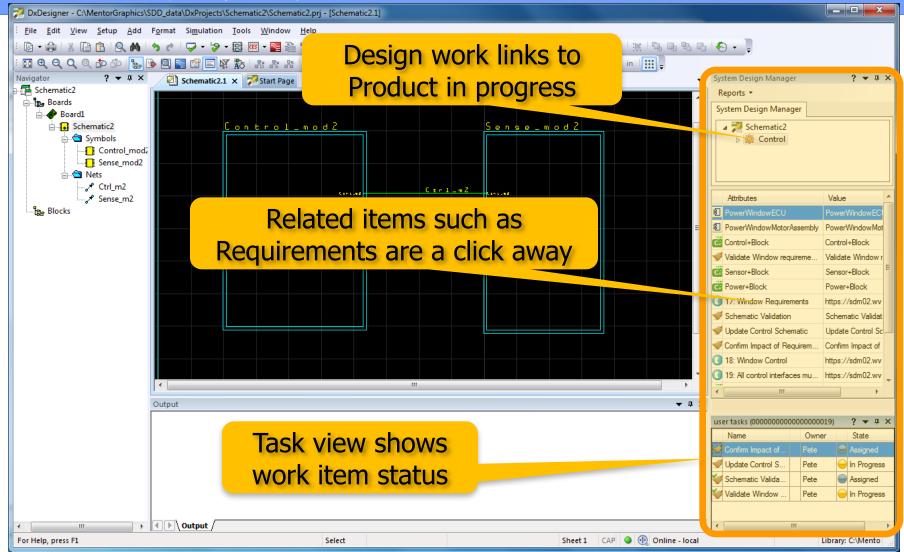








How Does It Look? - Operation inside the Design Tools





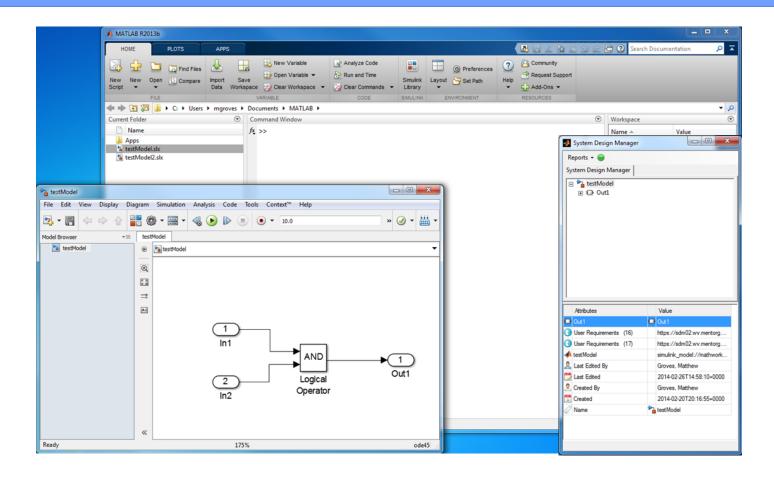


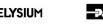






Linking in Simulink





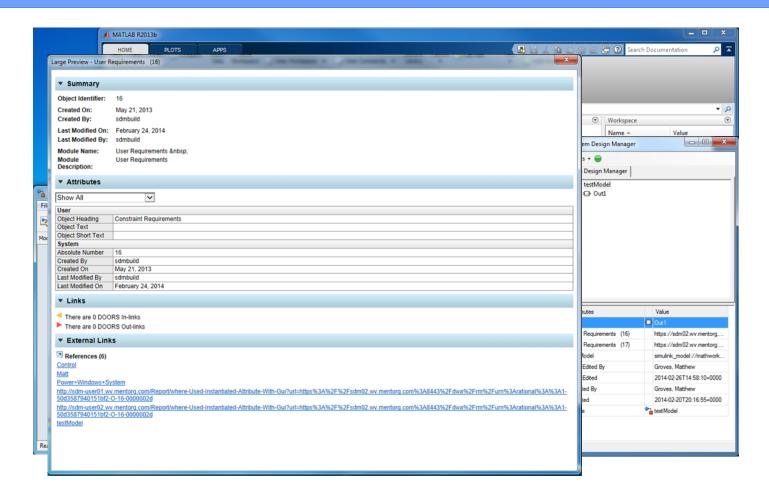








DOORS Access (illustrated in Simulink)











Functional Models in Rhapsody, with Context SDM

Global Product Data Interoperability Summit | 2014 Rhapsody Modeling - Object Model Diagram: AdaptiveCruiseOverview in AdaptiveCCM Pkg - Eclipse _ | D | X File Edit Navigate Search Project Run Code Generator Tools Window Help Rhapsody De... (» AdaptiveCruiseOverview 🗍 System Design Manager 🕱 ● ● □ ♥ 🖸 💘 100% 🔻 🖺 # + 🖾 + 🗐 🕍 + 🖊 👍 @Batang ▼ 10 ▼ I H A - A -Entire Model View Type ▼ Builder Select □ 割 Target rhapsody:Component ☐ MentorACC Stamp Mode \Box fx ACC Function Models vehicle:Function — Components ■ Diagram Tools 王 包 Target rhapsody:Component itsEngineControl:EngineControl sdmAlm:Task Object itsCruise AdaptiveCCM_Pkg Update ACC Models sdmAlm:Task Class sensedVehSpd:double=0.0 desiredSpeed:double + Classes desiredSpeed ★ ● Generate new code sdmAlm:Task desiredSpeed:double=0.0 Composite Cla memorySpeed vsa:Composition thrust:double=0.0 Package 🛨 🔑 Files speedOffset difference:double=0.0 + Object Model Diagrams -0 Port evCruiseEnable integrate:long double=0.0 Objects Generalization Attributes evCruiseDisable Ė ... < Types FrontWindowLiftCtrlComp FrontWindowLiftCtrlCom Association evSetCoastRelease MIN_DIST_THRESHOLD_ALE 🕕 42: Hazard warning alert https://win7-x64:8443/c Directed Associ MAX_THRESHOLD_COUNTS ➡ chSensedVehSpd() 1 44: Initial warning alert https://win7-x64:8443/c MIN DIST THRESHOLD SAF evCruiseEnabled() Aggregation ACC Function Models ACC Function Models MIN VEH SPD itsSpeedFilter:SpeedFilter evCruiseDisabled() Composition 45: Distance Gap Control https://win7-x64:8443/c sensedVehSpd:double Link Target rhapsody_component://. sensedVehSpd:double measuredSpeed:double Dependency Created By ArchitecturePkg sensedVehSpd:double vehicleSpeed:double 31 Created 2013-06-01 07:25:29 Flow Realization Interface To Do List 💢 itsEnvironment:FrictionModel Actor ➡ chMeasuredSpeed() State Priority **⊞** Common Generate new code Assianed P3 - Moderate updateSpeed():void ■ Free Shapes 🍑 Create GENIVI targe... 🥽 Unassigned P3 - Moderate **■** Layout Check requirements P3 - Moderate Unassigned Update ACC Models Assigned P3 - Moderate measuredSpeed:double actualSpeed:double Check requirements In Progress P3 - Moderate - P P 🗜 Problems 🚰 Component : Target in MentorACC 📮 Console 🔚 Rhapsody Log 🖟 Animation 🗖 Browser 😭 Component : Target in MentorACC 🕱 General Scope Variation Points Description Relations Tags Properties Name: Target Debug









ALM Operation inside the Design Tools

Global Product Data Interoperability Summit | 2014 ■ Rhapsody Modeling - Object Model Diagram: AdaptiveCruiseOverview in AdaptiveCCM Pkg - Eclipse _ U X File Edit Navigate Search Project Run Code Generator Tools Window Help 🖺 ち Rhapsody De... 🅡 » AdaptiveCruiseOverview ■ Model Browser 🖾 Navigator ▼ 10 ▼ Z B A · A · Entire Model View Related Type ▼ Select Builder □ 包 Target rhapsody:Component Stamp Mode \Box fx ACC Function Models vehicle:Function — Components ■ Diagram Tools rhapsody:Component itsEngineControl:EngineControl - Packages sdmAlm:Task Object itsCruise sdmAlm:Task Class desiredSpeed:double sensedVehSpd:double=0.0 ± 4 Classes desiredSpeed sdmAlm:Task desiredSpeed:double=0.0 Composite Cla <u>+</u> ∴ è Dependencies memorySpeed vsa:Composition thrust:double=0.0 Package speedOffset desiredSpeed:double difference:double=0.0 ± ... a Object Model Diagrams -0 Port evCruiseEnable integrate:long double=0.0 🗓 🔑 Objects Generalization Attributes Value evCruiseDisable Generate new code Generate new code Association MIN DIST THRESHOLD ALE Update ACC Models Update ACC Models MAX_THRESHOLD_COUNTS Directed Asso chSensedVehSpd
 ∩ Check requirements Check requirements MIN DIST THRESHOLD SAF evCruiseEnabled() Aggregation Target Target MIN_VEH_SPD itsSpeedFilter:SpeedFilter evCruiseDisabled() Composition 🤽 Created Bv ...

LEAD_VEH_SPEED_OFFSET sensedVehSpd:double Link 31 Created 2013-05-31 08:13:24 AnalysisPkg sensedVehSpd:double measuredSpeed:double & Last Edited Bv ArchitecturePkg Dependency sensedVehSpd:double vehicleSpeed:double 🛅 InterfacesPkg 31 Last Edited 2013-05-31 08:13:24 Realization Interface To Do List 💥 itsEnvironment:FrictionModel Actor Name State Priority chMeasuredSpeed() Generate new code P3 - Moderate updateSpeed():void ■ Free Shapes Moderate Check requir Moderate Generate new code Attributes Update ACC Moderate Rename Generate new code measuredSpeed:double actualSpeed:double 🍑 Check requir Moderate Copy URI Preview This designer commences - -Problems Problems a new task General | Scope | Variation



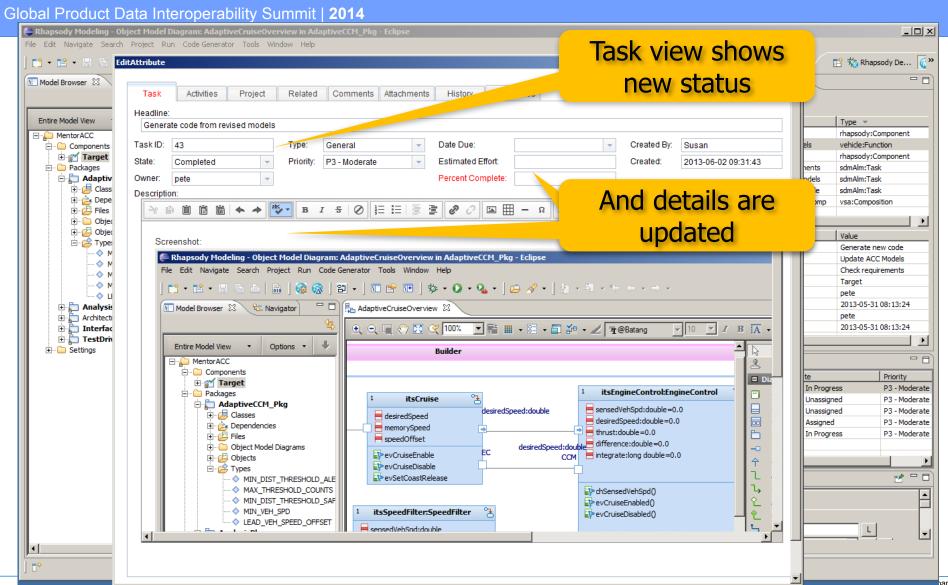


Locate



Debug

ALM Operation inside the Design Tools

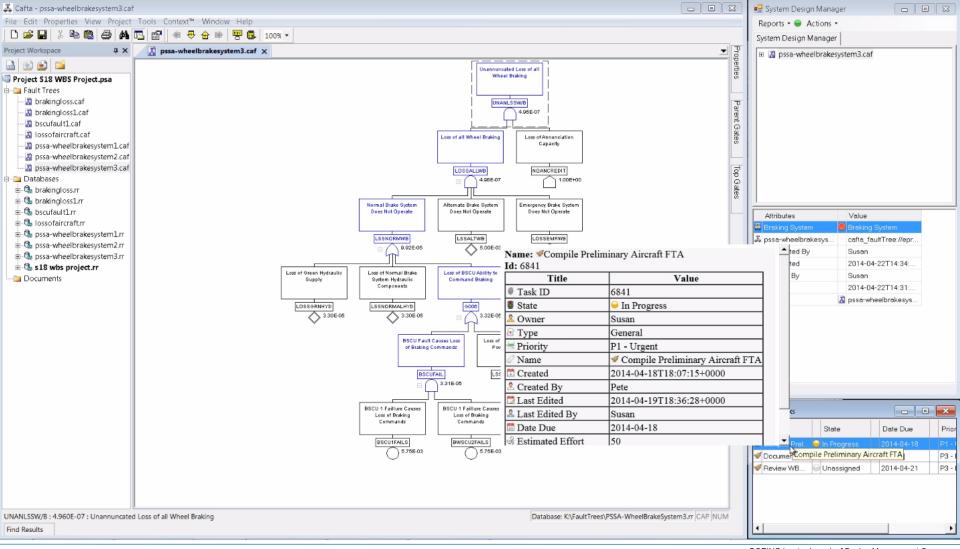








CAFTA Fault Tree Integration



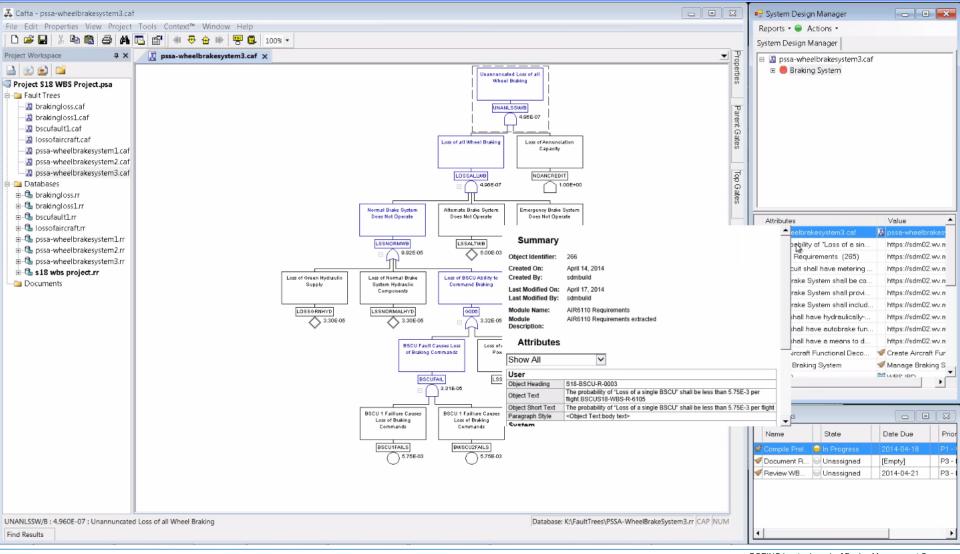








CAFTA Fault Tree Integration



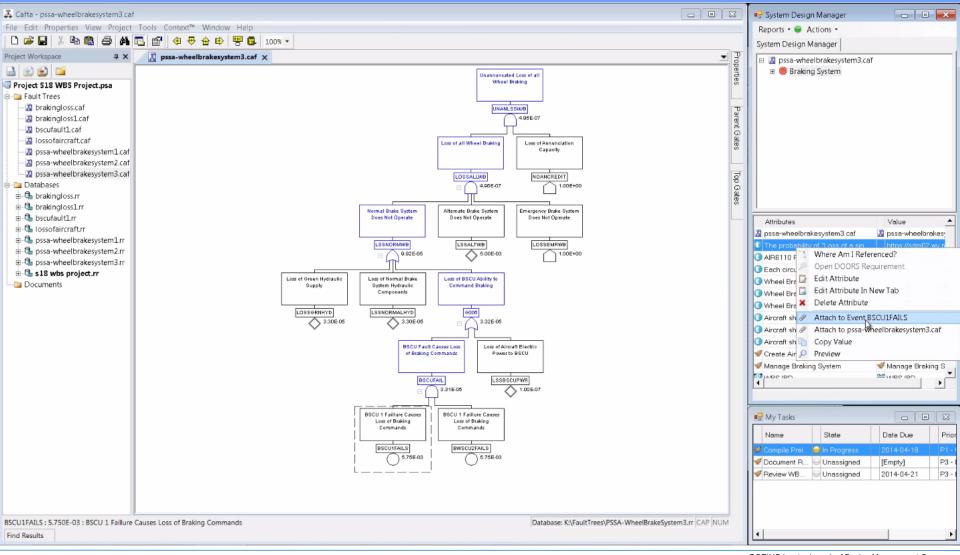








CAFTA Fault Tree Integration

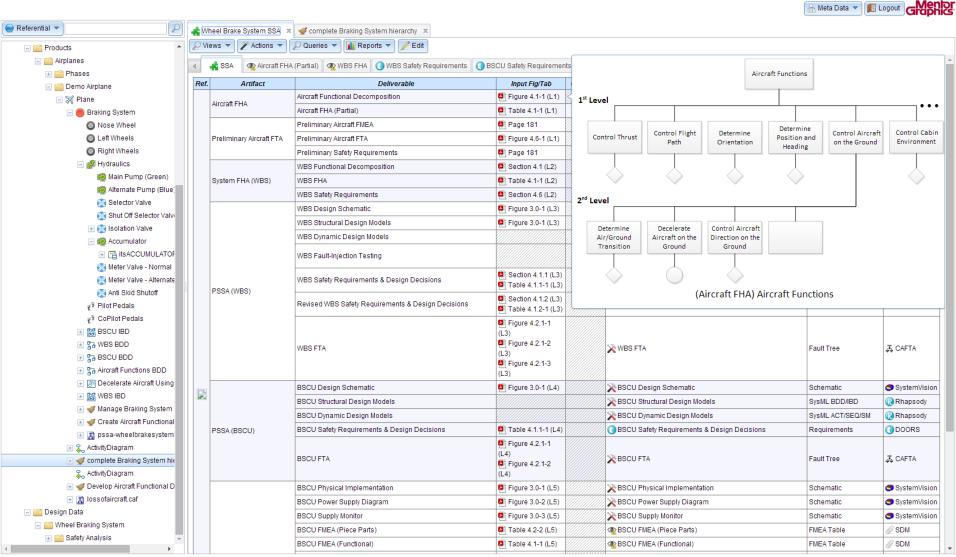














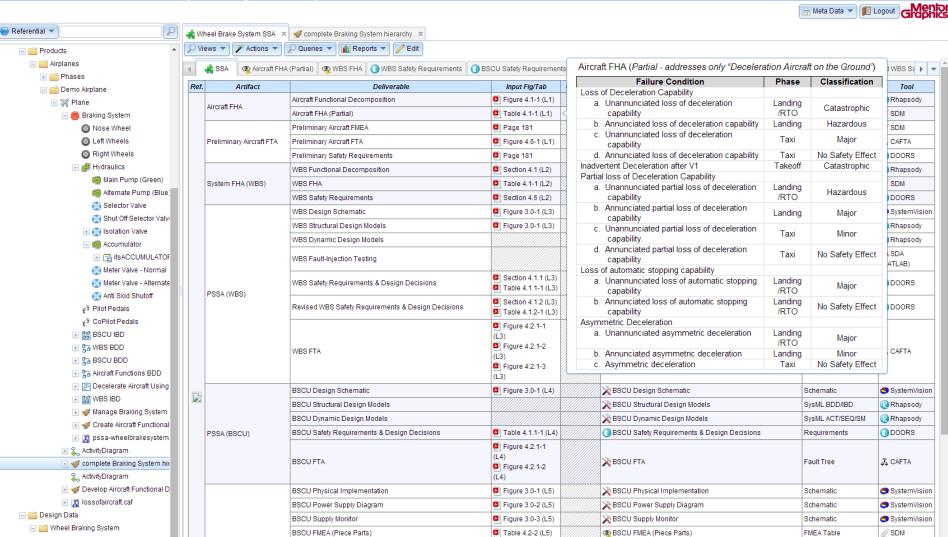








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Safety Analysis







BSCU FMEA (Functional)



RSCU FMEA (Functional)

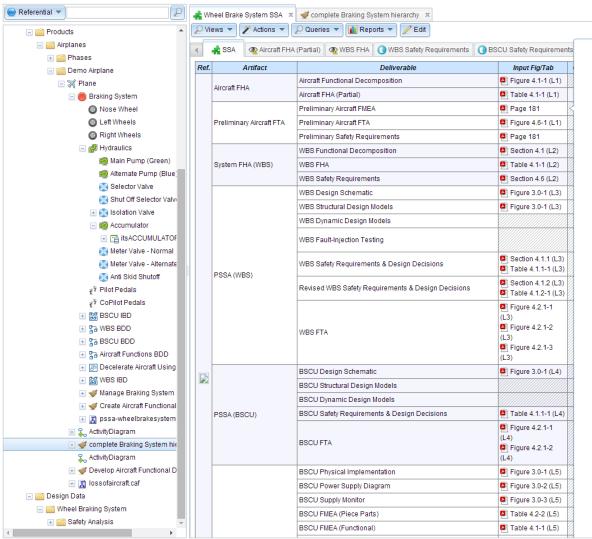
Table 4.1-1 (L5)

FMEA Table

∅ SDM

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4.1.6 Aircraft FHA Outputs

(Editor Note: The aircraft level FHA and associated fault tree give a preliminary set of failure conditions and associated requirements to consider at the system level. These failure conditions and requirements will be validated and updated during the system level FHA.)

Based on the FHA safety objectives, architectural decisions were made during the conceptual design phase. These architectural decisions are the basis for the preliminary aircraft fault tree shown in Figure 4.6-1.

The requirement of 1E-9 per flight hour for "Unannunciated loss of deceleration capability" results from the failure condition classification of catastrophic. This requirement is equivalent to a requirement of 5E-9 per flight, since the average flight length is 5 hours.

The requirements of 5E-7 per flight for "Unannunciated loss of all speed brakes on contaminated runway" and for "Unannunciated loss of all wheel brakes" result from the classification of these failure conditions as Hazardous (this classification is equivalent to 1E-7 per flight hour). These classifications are based on knowledge and experience with these system failures conditions. These requirements result in a requirement probability of 1E-6 per flight (i.e., 2x5E-7 per flight hr.) at the next higher level of "Unannunciated loss of effective wheel braking".

As shown in Figure 4.6-1, the allocation of the above requirements allows the budget for "Unannunciated loss of thrust reversers" to be set at 5E-3 per flight. This is 5E-9 divided by 1E-6.

Figure 4.6-1 also shows a fault tree leg associated with inadvertent deceleration after V1. Three aircraft systems can exhibit failure conditions that cause an inadvertent deceleration after V1. Each of the failure conditions is classified as Catastrophic and must meet 1E-9 per flight hour or 5E-9 per flight.

However, since they are only catastrophic during a specific phase of flight operation, their "per hour" requirements need to be factored. The factor is the average flight length of 5 hours divided by the at risk time (15 seconds would be a conservative estimate of the time from V1 to rotation).

Hence, the hourly failure rate requirement for each is 1E-9/flt hr * 5 flt hrs/flt * 1 flt/0.25 min * 60 min/1 hr = 1.2E-6/hr

The probability requirements after converting them to failure rate requirements would read as follows:

Inadvertent Thrust Reverse after

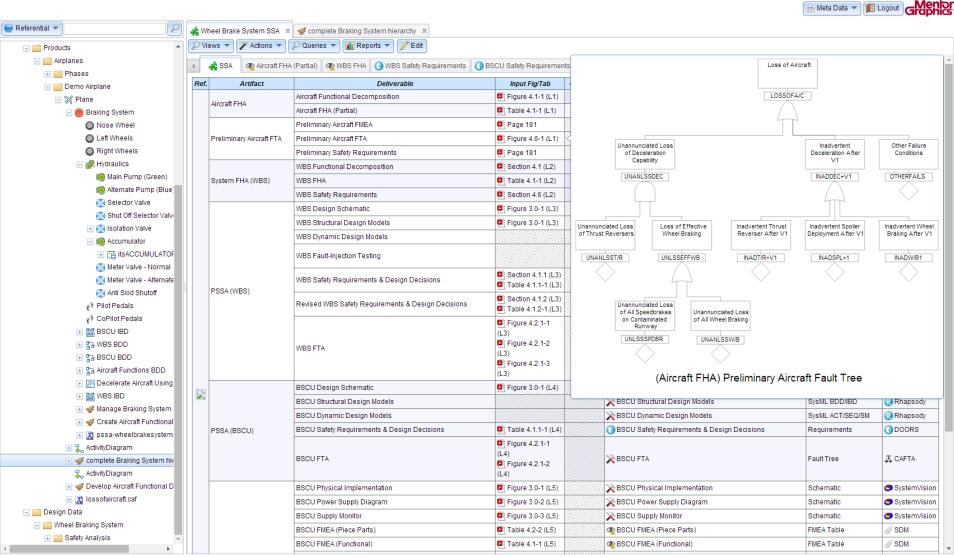
V1 1.2E-6 per hour

2) Inadvertent spoiler deployment after

V1 1.2E-6 per flour V1 1.2E-6 per hour







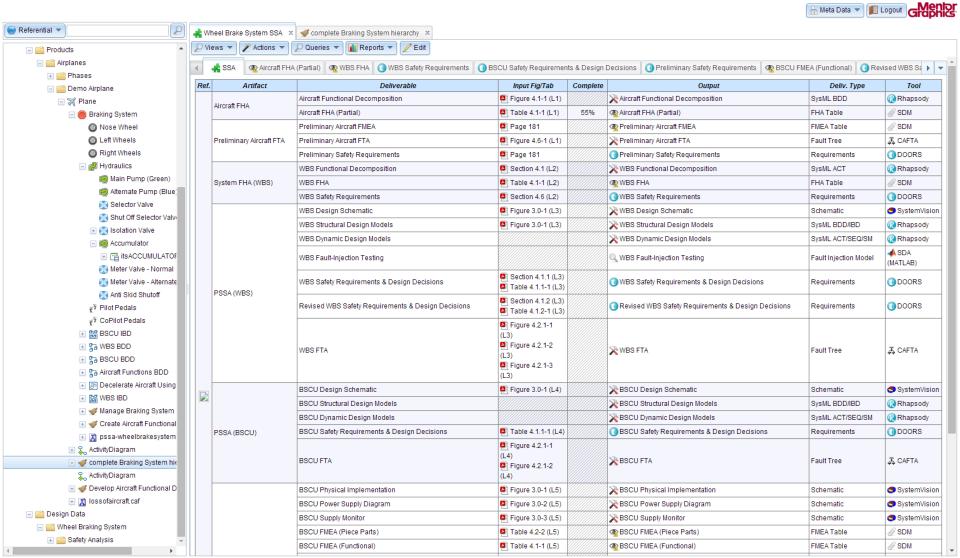














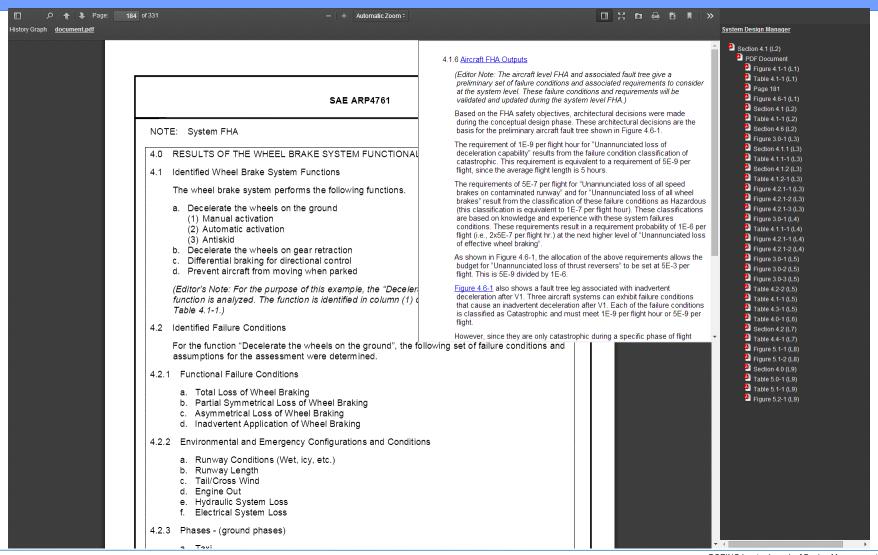








Integral PDF Viewer Adds Interactivity









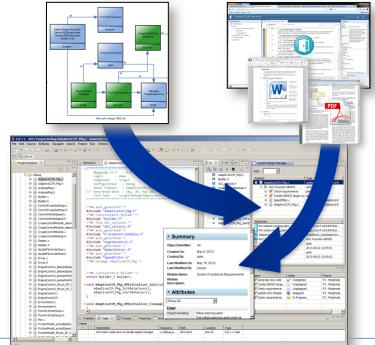


Context Supports the Users' Daily Tasks

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No walking to the bookshelf
(or heaven forbid - the library) to find the spec,
going to the next status meeting to raise the red flag,
and then coming back to the design to try to
remember where she was

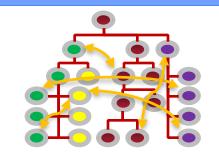


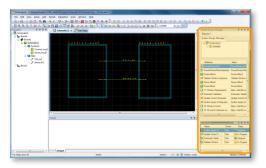


- This really works to make the designer's daily tasks easier, and supports better product management
- It plugs in to what they do today, into the tools they use today, without requiring methodology change

Context SDM – Three Key Capabilities

- Manage relationships between tools throughout design disciplines
 - Coordinate changes, dependencies, and impacts
 - Integrate with current tools and flows
- Bring information and interaction to the users where it can be applied directly
 - Sourced from any original repositories
 - Interact with appropriate design tools
 - Maximize usability and efficiency
- Enable product management, tracing, analytics and reporting
 - View or export dynamic data views
 - Standards compliance support

















Augmenting Current Tools and Processes

to increase the productivity of an engineering team

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Interoperability

Summary

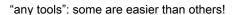
- "Integration through Data Exchange"
- "Design representations and requirements synchronized"
- Interactive system design management in users' familiar tools
- Standards-based connection to any* necessary tools

Future Directions

- Integral templated process support for ARP, etc.
- Increased automation of repetitive steps
- A path towards effective Model Driven Safety Analysis

For More Information

- See us at our Vendor Expo this afternoon Table 4
- bill chown@mentor.com













Thank You!

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